

## Summary of recipes for solving linear ODEs with constant coefficients with right-hand side in the characteristic form

We are considering ODEs of the form

$$y^{(n)} + a_1 y^{(n-1)} + \dots + a_{n-1} y' + a_n y = f(t). \quad (1)$$

The polynomial

$$p(z) := z^n + a_1 z^{n-1} + \dots + a_{n-1} z + a_n \quad (2)$$

is the characteristic polynomial of Eq. (1). Eq. (1) can be written as

$$Ly := p(D)y = f(t), \quad \text{where } D := \frac{d}{dt}. \quad (3)$$

The polynomial  $p(z)$  has  $n$  complex roots according to the main theorem of algebra, hence it can be written as

$$p(z) = (z - z_1)^{m_1} (z - z_2)^{m_2} \dots (z - z_k)^{m_k}, \quad \text{where } m_1 + m_2 + \dots + m_k = n. \quad (4)$$

We call the number  $m_i$  the multiplicity of the root  $z_i$ .

Suppose the right-hand side  $f(t)$  of Eq. (1) is in the characteristic form, i.e.,

$$\begin{aligned} f(t) = & (F_0 t^d + F_1 t^{d-1} + \dots + F_{d-1} t + F_d) e^{\mu t} \cos(\nu t) \\ & + (G_0 t^d + G_1 t^{d-1} + \dots + G_{d-1} t + G_d) e^{\mu t} \sin(\nu t). \end{aligned} \quad (5)$$

The number  $d$  is called the degree of the right-hand side. The multiplicity of the root  $z = \mu + i\nu$  of the characteristic polynomial  $p(z)$  is called the multiplicity of the right-hand side. If  $z = \mu + i\nu$  is not a root of  $p(z)$  then the multiplicity is zero.

### Method of undetermined coefficients

If the right-hand side is of the form of Eq. (5) then a particular solution should be sought of the form

$$\begin{aligned} y_p(t) = & (A_0 t^{d+m} + A_1 t^{d+m-1} + \dots + A_{d-1} t^{m+1} + A_d t^m) e^{\mu t} \cos(\nu t) \\ & + (B_0 t^{d+m} + B_1 t^{d+m-1} + \dots + B_{d-1} t^{m+1} + B_d t^m) e^{\mu t} \sin(\nu t), \end{aligned} \quad (6)$$

where  $m$  is the multiplicity of the root  $z = \mu + i\nu$  of the polynomial  $p(z)$ . The particular cases of this rule are listed in Table 1.

$f(t)$	$y_p(t)$
$F e^{rt}$	$A t^m e^{rt}$ , $m$ is the multiplicity of $z = r$
$F \cos(\nu t)$ or $G \sin(\nu t)$	$t^m (A \cos(\nu t) + B \sin(\nu t))$ , $m$ is the multiplicity of $z = i\nu$
$F e^{\mu t} \cos(\nu t)$ or $G e^{\mu t} \sin(\nu t)$	$t^m e^{\mu t} (A \cos(\nu t) + B \sin(\nu t))$ , $m$ is the multiplicity of $z = \mu + i\nu$
$F_0 t^d + \dots + F_{d-1} t + F_d$	$A_0 t^{d+m} + \dots + A_{d-1} t^{m+1} + A_d t^m$ , $m$ is the multiplicity of $z = 0$
$(F_0 t^d + \dots + F_{d-1} t + F_d) e^{rt}$	$(A_0 t^{d+m} + \dots + A_{d-1} t^{m+1} + A_d t^m) e^{rt}$ , $m$ is the multiplicity of $z = r$
$(F_0 t^d + \dots + F_{d-1} t + F_d) \cos(\nu t)$ or $(G_0 t^d + \dots + G_{d-1} t + G_d) \sin(\nu t)$	$(A_0 t^{d+m} + \dots + A_{d-1} t^{m+1} + A_d t^m) \cos(\nu t) +$ $(B_0 t^{d+m} + \dots + B_{d-1} t^{m+1} + B_d t^m) \sin(\nu t)$ , $m$ is the multiplicity of $z = i\nu$
$(F_0 t^d + \dots + F_{d-1} t + F_d) e^{\mu t} \cos(\nu t)$ or $(G_0 t^d + \dots + G_{d-1} t + G_d) e^{\mu t} \sin(\nu t)$	$(A_0 t^{d+m} + \dots + A_{d-1} t^{m+1} + A_d t^m) e^{\mu t} \cos(\nu t) +$ $(B_0 t^{d+m} + \dots + B_{d-1} t^{m+1} + B_d t^m) e^{\mu t} \sin(\nu t)$ , $m$ is the multiplicity of $z = \mu + i\nu$

Table 1: Forms of the right-hand sides and the corresponding particular solutions for the method of undetermined coefficients

## Using the Key Identity

The Key Identity for Eq. (2) and its first three derivatives with respect to  $z$  are given by

$$\begin{aligned}L(e^{zt}) &\equiv p(D)e^{zt} = p(z)e^{zt}, \\L(te^{zt}) &= (p(z)t + p'(z))e^{zt}, \\L(t^2e^{zt}) &= (p(z)t^2 + 2p'(z)t + p''(z))e^{zt}, \\L(t^3e^{zt}) &= (p(z)t^3 + 3p'(z)t^2 + 3p''(z)t + p'''(z))e^{zt}.\end{aligned}$$

In order to find a particular solution for the right-hand side with degree  $d$  and multiplicity  $m$  we will need to write  $d + 1$  equations that are the derivatives of the Key Identity of orders  $m, m + 1, \dots, m + d$ . To apply this approach to  $f(t)$  containing trigonometric functions we need to take real and imaginary parts of complex functions. By Euler's formula,

$$e^{i\nu t} = \cos(\nu t) + i \sin(\nu t).$$

If  $z = u + iv$  is a complex number then  $u$  and  $v$  are called its real and imaginary parts respectively and denoted by

$$u \equiv \operatorname{Re}(z), \quad v \equiv \operatorname{Im}(z).$$

Therefore,

$$\cos(\nu t) = \operatorname{Re}(e^{i\nu t}) \quad \text{and} \quad \sin(\nu t) = \operatorname{Im}(e^{i\nu t}).$$

The Key Identity approach for degree  $d = 0$  is summarized in Table 2.

The Key Identity approach for degree  $d = 1$  and multiplicity  $m = 0$  is summarized in Table 3.

The Key Identity approach for degree  $d = 1$  and multiplicity  $m = 0$  is summarized in Table 4.

$f(t)$	$y_p(t)$
$F e^{rt}$	$F \frac{t^m e^{rt}}{p^{(m)}(r)},$ $m$ is the multiplicity of $z = r$
$F \cos(\nu t)$	$\operatorname{Re} \left( F \frac{t^m e^{i\nu t}}{p^{(m)}(i\nu)} \right),$ $m$ is the multiplicity of $z = i\nu$
$G \sin(\nu t)$	$\operatorname{Im} \left( G \frac{t^m e^{i\nu t}}{p^{(m)}(i\nu)} \right),$ $m$ is the multiplicity of $z = i\nu$
$F e^{\mu t} \cos(\nu t)$	$\operatorname{Re} \left( F e^{\mu t} \frac{t^m e^{i\nu t}}{p^{(m)}(\mu + i\nu)} \right),$ $m$ is the multiplicity of $z = \mu + i\nu$
$G e^{\mu t} \sin(\nu t)$	$\operatorname{Im} \left( G e^{\mu t} \frac{t^m e^{i\nu t}}{p^{(m)}(\mu + i\nu)} \right),$ $m$ is the multiplicity of $z = \mu + i\nu$

Table 2: The Key identity approach for  $d = 0$ .

$f(t)$	$y_p(t)$
$Fte^{rt}$ . $r$ is not a root of $p(z)$ , i.e., $m = 0$ , $d = 1$ .	<p>Write 2 equations</p> $L(e^{rt}) = p(r)e^{rt},$ $L(te^{rt}) = p(r)te^{rt} + p'(r)e^{rt}$ <p>Express <math>te^{rt}</math> in terms of <math>L(e^{rt})</math>, <math>L(te^{rt})</math>, <math>p(r)</math>, and <math>p'(r)</math>, and multiply by <math>F</math>. Obtain</p> $Fte^{rt} = L(\dots).$ <p>The expression in the parentheses is <math>y_p(t)</math>.</p>
$Ft \cos(\nu t)$ or $Ft \sin(\nu t)$ , where $i\nu$ is not a root of $p(z)$ , i.e., $m = 0$ , $d = 1$ .	<p>Write 2 equations</p> $L(e^{i\nu t}) = p(i\nu)e^{i\nu t},$ $L(te^{i\nu t}) = p(i\nu)te^{i\nu t} + p'(i\nu)e^{i\nu t}.$ <p>Express <math>te^{i\nu t}</math> in terms of <math>L(e^{i\nu t})</math>, <math>L(te^{i\nu t})</math>, <math>p(i\nu)</math>, and <math>p'(i\nu)</math>, and multiply by <math>F</math>. Obtain</p> $Fte^{i\nu t} = L(\dots).$ <p>Then for <math>f(t) = Ft \cos(\nu t)</math> <math>y_p(t)</math> is the real part of the expression in the parentheses, while for <math>f(t) = Ft \sin(\nu t)</math> <math>y_p</math> is the imaginary part of the expression in the parentheses.</p>
$Fte^{\mu t} \cos(\nu t)$ or $Fte^{\mu t} \sin(\nu t)$ , where $\mu + i\nu$ is not a root of $p(z)$ , i.e., $m = 0$ , $d = 1$ .	<p>Write 2 equations</p> $L(e^{(\mu+i\nu)t}) = p(\mu + i\nu)e^{(\mu+i\nu)t},$ $L(te^{(\mu+i\nu)t}) = p(\mu + i\nu)te^{(\mu+i\nu)t} + p'(\mu + i\nu)e^{(\mu+i\nu)t}.$ <p>Express <math>te^{(\mu+i\nu)t}</math> in terms of <math>L(e^{(\mu+i\nu)t})</math>, <math>L(te^{(\mu+i\nu)t})</math>, <math>p(\mu + i\nu)</math>, and <math>p'(\mu + i\nu)</math>, and multiply by <math>F</math>. Obtain</p> $Fte^{(\mu+i\nu)t} = L(\dots).$ <p>Then for <math>f(t) = Fte^{\mu t} \cos(\nu t)</math> <math>y_p(t)</math> is the real part of the expression in the parentheses, while for <math>f(t) = Fte^{\mu t} \sin(\nu t)</math> <math>y_p</math> is the imaginary part of the expression in the parentheses.</p>

Table 3: The Key identity approach for  $d = 1$  and  $m = 0$ .

$f(t)$	$y_p(t)$
$Fte^{rt}$ , <i>r</i> is a root of $p(z)$ of multiplicity 1, i.e., $m = 1$ , $d = 1$ .	<p>Note that <math>p(r) = 0</math>. Write 2 equations</p> $L(te^{rt}) = p'(r)e^{rt},$ $L(t^2e^{rt}) = 2p'rt e^{rt} + p''re^{rt}.$ <p>Express <math>te^{rt}</math> in terms of <math>L(te^{(\mu+i\nu)t})</math>, <math>L(t^2e^{rt})</math>, <math>p'(r)</math>, and <math>p''(r)</math>, and multiply by <math>F</math>. Obtain</p> $Fte^{rt} = L(\dots).$ <p>Then <math>y_p(t)</math> is the expression in the parentheses.</p>
$Ft \cos(\nu t)$ or $Ft \sin(\nu t)$ , where $i\nu$ is a root of $p(z)$ of multiplicity 1, i.e., $m = 1$ , $d = 1$ .	<p>Note that <math>p(i\nu) = 0</math>. Write 2 equations</p> $L(te^{(i\nu)t}) = p'(i\nu)e^{(i\nu)t},$ $L(t^2e^{(i\nu)t}) = 2p'(i\nu)te^{(i\nu)t} + p''(i\nu)e^{(i\nu)t}.$ <p>Express <math>te^{(i\nu)t}</math> in terms of <math>L(te^{(i\nu)t})</math>, <math>L(t^2e^{(i\nu)t})</math>, <math>p'(i\nu)</math>, and <math>p''(i\nu)</math>, and multiply by <math>F</math>. Obtain</p> $Fte^{(i\nu)t} = L(\dots).$ <p>Then for <math>f(t) = Ft \cos(\nu t)</math> <math>y_p(t)</math> is the real part of the expression in the parentheses, while for <math>f(t) = Ft \sin(\nu t)</math> <math>y_p</math> is the imaginary part of the expression in the parentheses.</p>
$Fte^{\mu t} \cos(\nu t)$ or $Fte^{\mu t} \sin(\nu t)$ , where $\mu + i\nu$ is a root of $p(z)$ of multiplicity 1, i.e., $m = 1$ , $d = 1$ .	<p>Note that <math>p(\mu + i\nu) = 0</math>. Write 2 equations</p> $L(te^{(\mu+i\nu)t}) = p'(\mu + i\nu)e^{(\mu+i\nu)t},$ $L(t^2e^{(\mu+i\nu)t}) = 2p'(\mu + i\nu)te^{(\mu+i\nu)t} + p''(\mu + i\nu)e^{(\mu+i\nu)t}.$ <p>Express <math>te^{(\mu+i\nu)t}</math> in terms of <math>L(te^{(\mu+i\nu)t})</math>, <math>L(t^2e^{(\mu+i\nu)t})</math>, <math>p'(\mu + i\nu)</math>, and <math>p''(\mu + i\nu)</math>, and multiply by <math>F</math>. Obtain</p> $Fte^{(\mu+i\nu)t} = L(\dots).$ <p>Then for <math>f(t) = Fte^{\mu t} \cos(\nu t)</math> <math>y_p(t)</math> is the real part of the expression in the parentheses, while for <math>f(t) = Fte^{\mu t} \sin(\nu t)</math> <math>y_p(t)</math> is the imaginary part of the expression in the parentheses.</p>

Table 4: The Key identity approach for  $d = 1$  and  $m = 1$ .