

E

the tangent component  $K_t = \|c''\|$  is the geodesic curvature

Note  $K^2 \geq K_n^2$  with equality at  $p \Leftrightarrow e_2 \parallel N$  at  $p$   
 $\Leftrightarrow K_t = 0 \Leftrightarrow$  the osculating plane of  $C$  at  $p$  contains  $N(p)$

Rmk Since  $K_n = \mathbb{I}(x, x)$  where  ~~$x = c'$~~   
 or  $x = c'$ ,  $K_n$  depends only on  
 (known as Meusnier's)  
 theorem the tangent vector of a curve,  
 not on the curve itself!

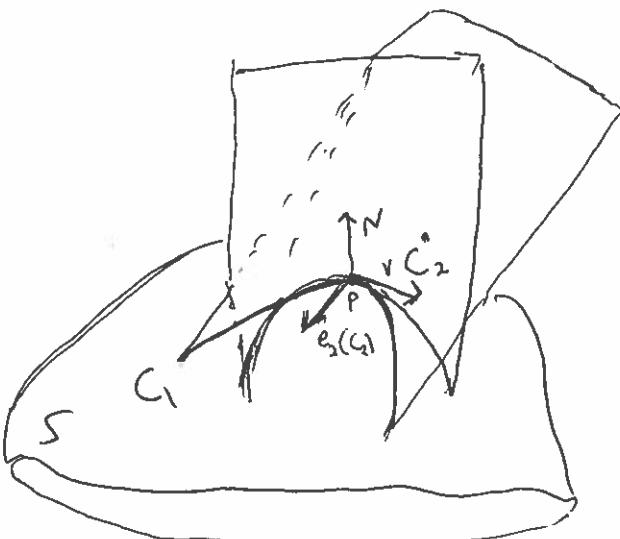
$C_1$  &  $C_2$  have

the same tangent vector

so they have the same  
 normal curvature

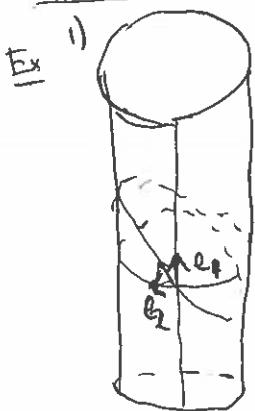
$C_1$  has nonzero geodesic  
 curvature but

$C_2 = S \cap \text{Span}(N, v) \leftarrow$   
 has zero geodesic curvature  
 &  $X = K_n$



"normal section"

In particular  $C_2$  is the unique  
 curve through  $p$  with tangent  $v$   
 & geodesic curvature 0



$$\mathbb{I}(x, x) = \langle x_1 e_1 + x_2 e_2, L(x_1 e_1 + x_2 e_2) \rangle = x_2^2$$

$$L \approx \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \quad \text{if } X \text{ is a unit vector,}$$

then  $K_n$  varies between

| if  $X = \pm e_2$   
 0 if  $X = \pm e_1$

Linear algebra: 1) The eigenvalues of  $L$  are real: (8)

Proof: Let  $v$  be an eigenvector with eigenvalue  $\lambda$ , then  $\langle Lv, Lv \rangle = \langle v, L^2 v \rangle = \langle v, \lambda^2 v \rangle = \lambda^2 \langle v, v \rangle = \lambda^2 \|v\|^2$   
 $\Rightarrow \lambda^2 = \frac{\langle Lv, Lv \rangle}{\|v\|^2} \in \mathbb{R}_{>0}$

2) if  $\lambda_1 \neq \lambda_2$ , then the eigenvectors  $e_1$  &  $e_2$  are orthogonal

$$\lambda_1 \langle e_1, e_2 \rangle = \langle Le_1, e_2 \rangle = \langle e_1, Le_2 \rangle = \langle e_1, e_2 \rangle \lambda_2 \\ \Rightarrow \langle e_1, e_2 \rangle = 0 \quad \text{since } \lambda_1 \neq \lambda_2$$

Max ~~Min~~ ~~Max~~ ~~Min~~

Def - Prop (Olinde-Rodriguez) let  $X \in T_p S$  be a unit tangent vector ( $I(X, X) = 1$ ), then the following are equivalent  
1)  $X$  is a stationary point for  $\mathcal{II}(X, X)$  under the constraint  $I(X, X) = 1$   
2)  $X$  is an eigenvector of  $L$

In this case,  $X$  is a principal curvature direction

&  $\lambda$  (the eigenvalue) is a principal curvature.

Note  $\mathcal{II}(X, X) = I(X, LX) = \lambda I(X, X) = \lambda$  so  $\lambda$  = normal curvature in  $X$  direction

- recall stationary = derivative is zero. This is a Lagrange multiplier problem. Note that the gradient of  $\mathcal{II}(X, X) = X$  is  $LX$  & gradient of  $I(X, X) = X$

So  $X$  is stationary  $\Leftrightarrow \exists$  Lagrange multiplier  
with constraint  $I(X, X) = 1$

$\Leftrightarrow X$  eigenvector with

eigenvalue  $\lambda$ .

$$\begin{array}{l} \text{grad}_{\mathbb{II}} X = \lambda \text{grad}_{\mathbb{I}} X \\ LX = \lambda X \end{array}$$

Rmk We may pick orthonormal eigenbases  $e_1, e_2$  for  $T_p S$  with eigenvalues  $\lambda_1, \lambda_2$

then any unit vector  $X = \cos \theta e_1 + \sin \theta e_2$  so

$$\begin{aligned} K_n = \mathbb{II}(X, X) &= I(LX, X) = I(\lambda_1 \cos \theta e_1 + \lambda_2 \sin \theta e_2, \cos \theta e_1 + \sin \theta e_2) \\ &= [\lambda_1 \cos^2 \theta + \lambda_2 \sin^2 \theta = K_n] \end{aligned}$$

Rmk a (Signs) everything we've done here is independent of choices except! in the choice of orientation. There are two choices of  $N$  which differ by sign  $\Rightarrow L$  differs by a sign but  $\mathbb{III}$  does not,  $\lambda_1$  &  $\lambda_2$  differ by  $\lambda_1 \lambda_2 = \det(L)$  doesn't, etc ...  
(sometimes we'll call  $\lambda_i, K_i$  for curvature)

Def 1) The Gaussian Curvature  $K = \lambda_1 \lambda_2 = \det(L)$

2) The mean curvature  $H = \frac{1}{2} \text{Tr}(L) = \frac{1}{2} (\lambda_1 + \lambda_2)$

Rmk 1)  $H^2 - K = \frac{1}{4} (\lambda_1 - \lambda_2)^2 \geq 0$  with equality  $\Leftrightarrow \lambda_1 = \lambda_2$

recall then since  $\lambda_i$  are the max & min of normal curvature then this happens  $\Leftrightarrow$  the normal curvature is constant

fix a chart  $f: U \rightarrow S$

$$L = (h_{ij}^i) = (h_{ab})(g^{cd})$$

$h_{ab}$  = coefficients  
of II

(10)

$$h_i^i = \sum_k h_{ik} g^{ki} \Rightarrow K = \det(L) = \frac{h_{11} h_{22} - h_{12}^2}{g_{11} g_{22} - g_{12}^2}$$

Recall:  $dA = \sqrt{EG - F^2} du_1 du_2$

$$= \frac{Eg - f^2}{EG - F^2}$$

$\nu$  = parametrization of  $S^2$

Via  $N \circ f: U \rightarrow S^2$

$$= \frac{LN - M^2}{EG - F^2}$$

with 1st fundamental form

$$(h_{ij})$$

Thus,  $K$  is measuring the difference or "distortion" between the area form on  $S$  & the area form on  $S^2$  via Gauss map.

$$H = \frac{1}{2} \text{Tr}(L) = \frac{1}{2}(h_1^i + h_2^i) = \frac{1}{2} \sum_{i,j} h_{ij} g^{ji}$$

$$= \frac{1}{2 \det(g_{ij})} \cancel{\det(g_{ij})} h_{11} g_{22} - 2h_{12} g_{12} + h_{22} g_{11}$$

$\underline{f}$  a point  $p \in S$  is called

elliptic if  $K(p) > 0$

hyperbolic if  $K(p) < 0$

parabolic if  $K(p) = 0$  but  $H(p) \neq 0$

umbilic if  $K_1(p) = K_2(p)$

strictly umbilic if  
umbilic &  $K \neq 0$

level point if  
 $K_1 = K_2 = 0$

Ex: 1) Sphere or radius 1 & every point is umbilic  $L = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  so  $K_1 = K_2 = 1$



2) Cylinder  $L = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$   $K_1 = 0 < K_2 = 1$   $K = 0$

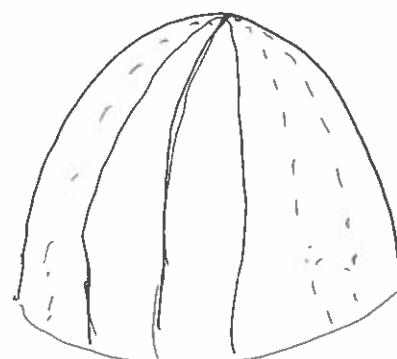


every point is parabolic

3) elliptic point

$$a^2x^2 + b^2y^2 + c^2z^2 = 1$$

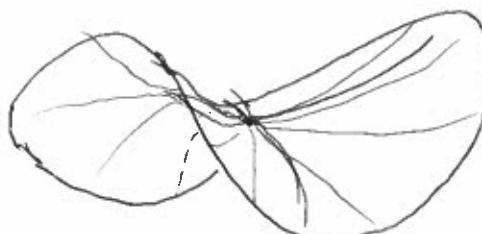
$K_1$  &  $K_2$  have the same sign



4) hyperbolic point

$$x^2 + y^2 - z^2 = 1$$

"saddle point"



- Def 1) a line of curvature is a regular curve  $c: I \rightarrow S$  s.t.  $c'$  is a principal curvature direction ~~at~~ at  $c(t)$  for all  $t \in I$
- 2) an asymptotic direction is a direction in which the normal curvature is zero
- 3) an asymptotic curve is a curve for which  $c'(t)$  is an asymptotic direction for all  $t \in I$ .