

## Taylor expansion

$$c(s) = c(0) + c'(0)s + \frac{c''(0)}{2}s^2 + \dots + \frac{c^{(n)}(0)}{n!}s^n + \dots$$

Def  $c_1$  &  $c_2$  have contact order  $k$

if  $c_1^{(n)}(0) = c_2^{(n)}(0)$  for  $n=0, \dots, k$

e.g. if  $k=1$  then  $c_1$  &  $c_2$  are tangent

## Def (Frenet frames & curves)

let  $c: I \rightarrow \mathbb{R}^n$  be a regular  $C^n$ -curve <sup>par arc by length</sup>

$c$  is Frenet if  $c', \dots, c^{(n-1)}$  are linearly

independent. In this case, a Frenet frame

$e_1, \dots, e_n$  is an orthonormal positively oriented

basis of  $T_{c(t)}\mathbb{R}^n$  (depending on  $t$ !) s.t.

$$1) \text{ Span}(e_1, \dots, e_k) = \text{Span}(c', c'', \dots, c^{(k)})$$

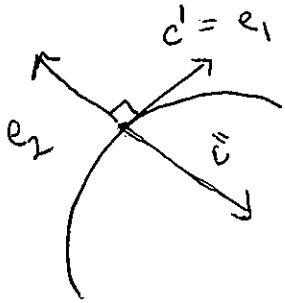
for all  $k=1, \dots, n-1$

$$2) \langle c^{(k)}, e_k \rangle > 0 \quad \text{for } k=1, \dots, n-1$$

given  $c', \dots, c^{(n-1)}$  gram schmidt  $e_1, \dots, e_{n-1}$

Then  $e_n$  is uniquely determined by the positive orientation.

Ex 1) For  $n=2$ , every regular  $C^2$  curve is Frenet



$e_1 =$  unit tangent

$e_2 =$  unit normal

$$0 = \frac{d}{ds} \langle c', c' \rangle = 2 \langle c', c'' \rangle = 2 \langle e_1, c'' \rangle$$

So  $c'' = K e_2$  for some function  $K$

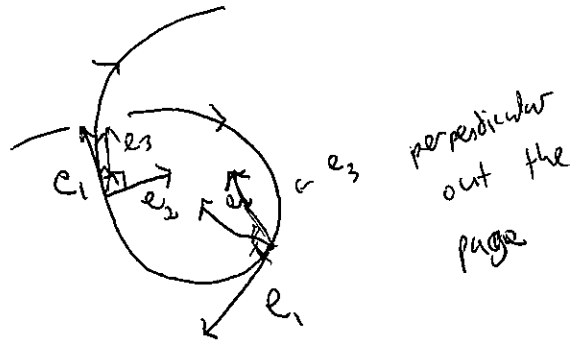
2) for  $n=3$  a regular  $C^3$  curve is Frenet called the curvature

if  $c'' \neq 0$

$$e_1 = c'$$

$$e_2 = \frac{c''}{\|c''\|}$$

$$e_3 = e_1 \times e_2$$



Plane curves

$$c'' = K e_2$$

$$e_1' = c'' = K e_2$$

$$0 = \frac{d}{ds} \langle e_1, e_2 \rangle$$

$$e_2' = -K e_1$$

use this to compute the 2<sup>nd</sup> eqn



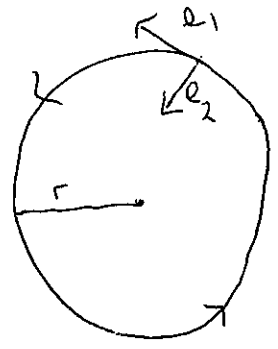
~~Ex~~  $\frac{d}{ds} \begin{pmatrix} e_1 \\ e_2 \end{pmatrix} = \begin{pmatrix} 0 & k \\ -k & 0 \end{pmatrix} \begin{pmatrix} e_1 \\ e_2 \end{pmatrix}$  Frenet eqns

Ex 1)  $c(s) = \left( r \cos\left(\frac{s}{r}\right), r \sin\left(\frac{s}{r}\right) \right)$

$c'(s) = \left( -\sin\left(\frac{s}{r}\right), \cos\left(\frac{s}{r}\right) \right)$

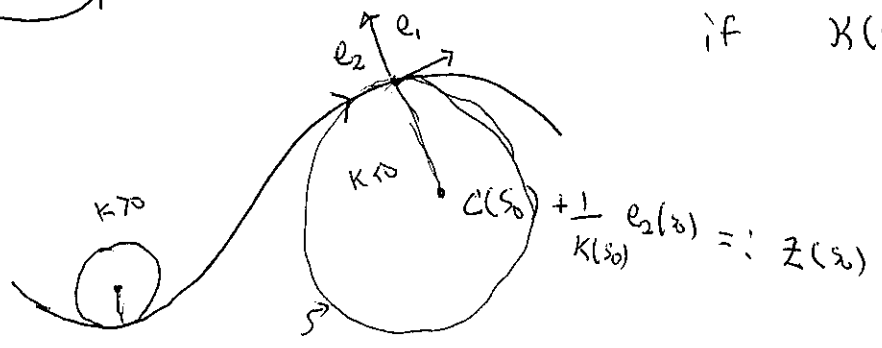
$c''(s) = \frac{-1}{r} \left( \cos\left(\frac{s}{r}\right), \sin\left(\frac{s}{r}\right) \right)$

$= \frac{1}{r} e_2$   $K = \frac{1}{r}$  is constant



if  $K(s_0) \neq 0$

2)



Osculating circle  
Centered at  $z(s_0)$   
radius  $\frac{1}{|K(s_0)|}$

$S(s_0)$  meets  $c(s_0)$   
to order 2

3) Consider a graph  $y = f(x)$  & suppose  $f(0) = f'(0) = 0$   
 $f''(0) \neq 0$

$c(t) = (t, f(t))$

$\dot{c}(t) = (1, f'(t))$   $e_1 = \dot{c}(0) = (1, 0)$  unit vector

$K(0) = f''(0)$

$\ddot{c}(0) = (0, f''(0)) = f''(0) (0, 1) = f''(0) e_2$

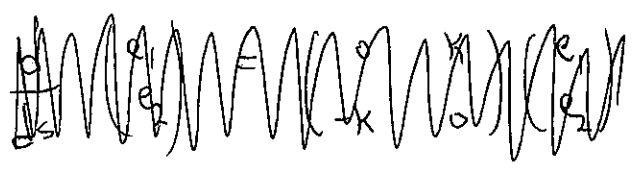
Thm A regular plane curve has constant curvature  $K$  if & only if either

1) it is an arc of a circle of radius  $\frac{1}{|K|}$  (if  $K \neq 0$ )

2) it is a line segment if  $K=0$

Proof

Suppose  $K \neq 0$ , then ~~the system~~



has a unique solution

Consider the osculating circle with center

$z(s) = c(s) + \frac{1}{K} e_2(s)$  & constant radius  $\frac{1}{K}$

$z'(s) = c'(s) + \frac{1}{K} e_2'(s) = e_1(s) + \frac{1}{K} (-K e_1(s))$

Frenet eqns = 0

thus  $z(s) = z_0$  is constant. Moreover,

$\|z(s) - c(s)\| = \frac{1}{K}$  so  $c(s)$

lies on the circle  $S(z_0, \frac{1}{K})$  for all  $s$ .

If  $K=0$ , then by Frenet eqns

$c^{(n)} = 0$  for all  $n \geq 2$  &

$c'(s) = (a_1, a_2) = \vec{a}$  so  $c(s) = \vec{a}s + \vec{b}$   
 $\Rightarrow$  a line, □

Thm For each continuous function  $K(s)$ , there exists a regular plane curve, unique up to translation & rotation, ~~with~~ with curvature  $K$ .

Pf idea

Write  $e_1 = (\cos(\alpha(s)), \sin(\alpha(s)))$ , by orthonormality,  
 $e_2 = (-\sin(\alpha(s)), \cos(\alpha(s)))$ . ~~Let~~  $Ke_2 = e_1' = \alpha' e_2$

so  $K = \alpha'(s)$  Suppose wlog ~~at~~  $c(0) = (0,0)$

then  $\alpha(0) = 0$ ,  $\alpha(s) = \int_0^s K(t) dt$  by FTC  $e_1(0) = (1,0)$

Now  $x(s) = \int_0^s \cos\left(\int_0^\sigma K(t) dt\right) d\sigma$   $y(s) = \int_0^s \sin\left(\int_0^\sigma K(t) dt\right) d\sigma$

$c(s) = (x(s), y(s))$  &  $c(s)$  is unique by the theory of D.E. □

# Space Curves (n=3)

regular

a  $C^3$ -curve is Frenet iff  $c'' \neq 0$

$e_1 = c'$  mit tangent  $K := \|c''\|$

$e_2 = \frac{c''}{\|c''\|}$  principal normal is the curvature

$e_3 = e_1 \times e_2$  binormal

$e_1' = \kappa e_2,$

$$e_2' = \underbrace{\langle e_2', e_1 \rangle}_{\langle -e_2, e_1 \rangle = -\kappa} e_1 + \underbrace{\langle e_2', e_2 \rangle}_0 e_2 + \underbrace{\langle e_2', e_3 \rangle}_{\tau} e_3$$

$$= -\kappa e_1 + \tau e_3$$

$$e_3' = \underbrace{\langle e_3', e_1 \rangle}_{\langle e_3, -e_1 \rangle = 0} e_1 + \underbrace{\langle e_3', e_2 \rangle}_{\langle e_3, -e_2 \rangle = -\tau} e_2 + \underbrace{\langle e_3', e_3 \rangle}_0 e_3$$

$= -\tau e_2$

$\tau$  is the torsion

$$\frac{d}{ds} \begin{pmatrix} e_1 \\ e_2 \\ e_3 \end{pmatrix} = \begin{pmatrix} 0 & \kappa & 0 \\ -\kappa & 0 & \tau \\ 0 & -\tau & 0 \end{pmatrix} \begin{pmatrix} e_1 \\ e_2 \\ e_3 \end{pmatrix}$$

not planar  $\Leftrightarrow \tau \neq 0!$