

Thm (Fundamental of Theorem of the local theory) (34)

Suppose $U \subseteq \mathbb{R}^n$ open, g_{ij}, h_{ij} given smooth functions on U for $1 \leq i, j \leq n$ satisfying the Gauss eqns & Codazzi-Mainardi eqns. let $u_0 \in U$, $p_0 \in \mathbb{R}^{n+1}$, $X_i^{(0)} \in T_{p_0} \mathbb{R}^{n+1}$ given initial conditions $i=1, \dots, n$

with $g_{ij}(u_0) = \langle X_i^{(0)}, X_j^{(0)} \rangle$ & $\nu^{(0)}$ a unit normal to $X_i^{(0)}$. Then there exists an open connected $p_0 \in V \subseteq U$ and a unique regular surface element

$$F: V \rightarrow \mathbb{R}^{n+1} \quad \text{with Gauss map } \nu \text{ s.t.}$$

- 1) $F(u_0) = p_0$
- 2) $\frac{\partial F}{\partial u_i^{(0)}}(u_0) = X_i^{(0)}$
- 3) $\nu(u_0) = \nu^{(0)}$
- 4) I & II of F are (g_{ij}) & (h_{ij}) respectively

PF sketch

we have the Gauss & Weingarten

formulas

$$\frac{\partial X_j}{\partial u^i} = \Gamma_{ii}^k X_k + h_{ij} \nu$$

$$\frac{\partial \nu}{\partial u_i^{(0)}} = -h_{ij} g^{jk} X_k$$

want F s.t. $\frac{\partial F}{\partial u^i} = X_i$ so we better

have $\frac{\partial^2 X_i}{\partial u^j \partial u^k} = \frac{\partial^2 X_i}{\partial u^k \partial u^j}$ ~~that~~ $\frac{\partial^2 v}{\partial u^i \partial u^j} = \frac{\partial^2 v}{\partial u^j \partial u^i}$

but this is exactly Gauss + Codazzi-Mainardi eqns

Frobenius integrability theorem \Rightarrow we can integrate

these ~~to~~ with initial condition $X_i^{(0)}, v^{(0)}$ to

let $X_i, v: \underset{U}{\mathbb{V}} \rightarrow \mathbb{R}^n$

Now we check that $\langle v, v \rangle = 1$ $\langle v, X_i \rangle = 0$

$\langle X_i, X_j \rangle = g_{ij}$

$\frac{\partial \langle v, v \rangle}{\partial u^i} = 2 \langle \frac{\partial v}{\partial u^i}, v \rangle = -2 h_{ik} g^{kl} \langle X_l, v \rangle$

$\frac{\partial \langle v, X_j \rangle}{\partial u^i} = -h_{ik} g^{kl} \langle X_l, X_j \rangle + \Gamma_{ij}^k \langle v, X_k \rangle + h_{ij} \langle v, v \rangle$

$\frac{\partial \langle X_i, X_j \rangle}{\partial u^k} = \Gamma_{ik}^r \langle X_r, X_j \rangle + \Gamma_{jk}^s \langle X_i, X_s \rangle + h_{ik} \langle v, X_j \rangle + h_{jk} \langle X_i, v \rangle$

but $\langle v, v \rangle = 1$ $\langle v, X_j \rangle = 0$ $\langle X_i, X_j \rangle = g_{ij}$

are solutions to these eqns, so by uniqueness, there the only ones

Now we have x_i & v_j we want

f s.t. $\frac{\partial f}{\partial u_i} = x_i$ $v = \frac{\partial f}{\partial u_i} \times \frac{\partial f}{\partial u_j}$ (**)

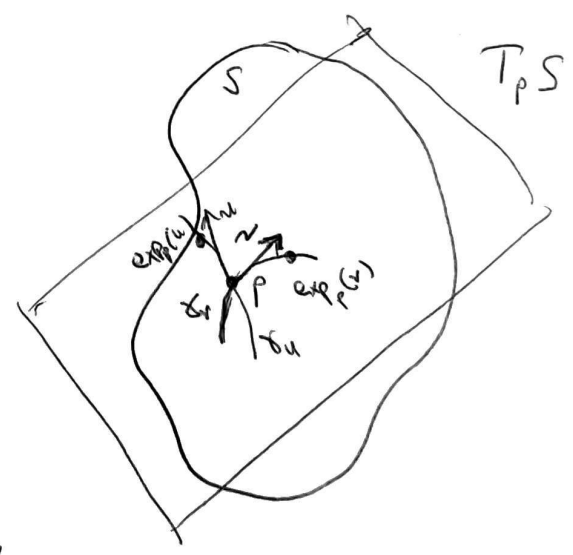
For this, we need integrability:

$$\frac{\partial x_i}{\partial u^j} = \text{scribble} \Gamma_{ij}^k x_k + h_{ij} v = \Gamma_{ji}^k x_k + h_{ji} v = \frac{\partial x_j}{\partial u^i}$$

So we again apply Frobenius integrability to get f satisfying (**)

The exponential map

$\gamma(t, v) =$ geodesic with $\gamma(0) = p$ $\gamma'(0) = v$
 $t \in (-\epsilon, \epsilon)$



Note $\gamma(t, \lambda v) = \gamma(\lambda t, v)$

Indeed, $\bar{\gamma}' = \lambda \gamma'$ by chain rule
 so 1) $\bar{\gamma}'(0) = \lambda v$ 2) $\bar{\gamma}(0) = p$

3) $\nabla_{\bar{\gamma}'} \bar{\gamma}' = \nabla_{\lambda \gamma'} \lambda \gamma' = \lambda^2 \nabla_{\gamma'} \gamma' = 0$

so $\bar{\gamma} = \gamma(t, \lambda v)$ by uniqueness of geodesics

We want to define a map

$$T_p S \rightarrow S \quad \text{by taking}$$

$$v \mapsto \gamma(1, v)$$

Call this the exponential map $\exp_p(v) := \gamma(1, v)$

$$\exp_p : \begin{matrix} U \\ \cong \\ T_p S \end{matrix} \rightarrow S$$

~~exp_p : U \to S~~

Prop Given $p \in S$, there exists $\varepsilon > 0$ s.t. \exp_p is well defined, differentiable, and a diffeomorphism on the ball

$$B_\varepsilon := \{v \in T_p S \mid \|v\| < \varepsilon\} \subseteq T_p S.$$

PF sketch We know for each v , $\exists \varepsilon(v)$ s.t.

$\gamma(t, v)$ is well defined. Take $\|v\|=1$

Then ~~is~~ $\gamma(t, v) = \gamma(1, tv) = \exp_p(tv)$ for all $t \in (-\varepsilon(v), \varepsilon(v))$ & differentiable,

$t \in (-\varepsilon(v), \varepsilon(v))$ is well defined, & we just need

to know that $\varepsilon(v) > 0$ can be chosen small enough to be independent of v

This shows \exp_p is well defined & diff on some ball B_ε for $\varepsilon > 0$ small enough

$$\exp_p : B_\varepsilon \xrightarrow{\subseteq T_p S} S$$

What is $d(\exp_p)_0 : T_0 B_\varepsilon \rightarrow T_p S$?

Let $\alpha_v(t) = tv$ be a curve in B_ε

$$\alpha'_v(0) = v \in T_p S$$

$$\begin{aligned} d(\exp_p)_0(v) &= \left. \frac{d}{dt} \exp_p(\alpha_v(t)) \right|_{t=0} \\ &= \left. \frac{d}{dt} \exp_p(tv) \right|_{t=0} \\ &= \left. \frac{d}{dt} \gamma(t, tv) \right|_{t=0} \\ &= \left. \frac{d}{dt} \gamma(t, v) \right|_{t=0} = v \end{aligned}$$

Thus, $d(\exp_p)_0$ is the identity, which in particular is invertible so by

Inverse function theorem,

\exp_p is invertible after possibly shrinking B_ε . □

Thus, \exp_p gives us a coordinate chart at $p \in S$, in fact two distinguished coordinate charts

$$\dim S = 2$$

$\{e_1, e_2\}$ orthonormal basis for $T_p S$ (3a)

Geodesic normal coordinates :

take u, v to be standard orthonormal coordinates on $T_p S$, then $F(u, v) := \exp_p(ue_1 + ve_2)$

is a chart with $(g_{ij})_p = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

Geodesic polar coordinates

let r, θ be polar coordinates on $T_p S$

then $F(r, \theta) = \exp_p(r \cos \theta e_1 + r \sin \theta e_2)$
are coordinates with

$$(g_{ij})_p = \begin{bmatrix} 1 & 0 \\ 0 & G(r, \theta) \end{bmatrix}$$

~~with $(g_{ij})_p = \begin{bmatrix} 1 & 0 \\ 0 & G(r, \theta) \end{bmatrix}$~~

Thm (Minding) Two surfaces with the same constant Gaussian curvature are locally isometric.

let S, \tilde{S} two such surfaces with $p \in S, \tilde{p} \in \tilde{S}$
Pick orthonormal bases $\{e_1, e_2\}$ for $T_p S$ $\{\tilde{e}_1, \tilde{e}_2\}$ for $T_{\tilde{p}} \tilde{S}$

In geodesic polar coordinates, $K = -\frac{\partial^2 \sqrt{G}}{\partial r^2} / \sqrt{G} = \text{Constant}$

$$\text{So } \frac{\partial^2}{\partial r^2} \sqrt{G} + K\sqrt{G} = 0 \quad \frac{\partial^2}{\partial r^2} \sqrt{\tilde{G}} + K\sqrt{\tilde{G}} = 0$$

By uniqueness of solutions to diff eq, $G = \tilde{G}$

thus $g_{ij} = \tilde{g}_{ij}$ so S & \tilde{S} are isometric

□