

Proof of THM:

PLAN: Show that the sequence of Newton iterates

$$\vec{x}_{k+1} = \vec{x}_k - Df(\vec{x}_k)^{-1} f(\vec{x}_k)$$

is a Cauchy sequence and therefore converges.

Step I: Show that $\forall \vec{x} \in D$, $Df(\vec{x})$ is invertible, and

$$\|Df(\vec{x})^{-1}\| \leq 2 \|Df(\vec{x}_0)^{-1}\|.$$

If $\vec{x} \in D$ then

$$D = \{x: \|x - x_1\| \leq \delta\} \quad \delta = \frac{r}{1-r} \|x_1 - x_0\|$$

$$\|\vec{x} - \vec{x}_0\| \leq \|x - x_1\| + \|x_1 - x_0\| \leq \delta + \|x_1 - x_0\| = \left(\frac{r}{1-r} + 1\right) \|x_1 - x_0\|$$

$$= \left(\frac{1}{1-r}\right) \|x_1 - x_0\|$$

$$\frac{1}{1-r} = \frac{1}{r} \left[\frac{1}{\frac{1}{r} - 1} \right] \quad r < \frac{1}{3} \Rightarrow \frac{1}{r} \geq 3 \Rightarrow \frac{1}{r} - 1 \geq 2$$

$$\Rightarrow \frac{1}{\frac{1}{r} - 1} \leq \frac{1}{2}$$

$$\Rightarrow \|x - x_0\| \leq \frac{1}{2r} \|x_1 - x_0\| \leq \frac{1}{2r} \|Df(x_0)^{-1}\| \|f(x_0)\|$$

$$\Rightarrow \frac{1}{2L \|Df(x_0)^{-1}\|}$$

$$r = L \|Df(x_0)^{-1}\| \|f(x_0)\|$$

To make the notation more compact, let $A = Df(x_0)$ and $B = Df(x)$.

If $x \in D$, we know that $\|x - x_0\| \leq \frac{1}{2L\|A^{-1}\|}$.

$x \rightarrow Df(x)$ is Lip. cont $\Rightarrow \forall n \ x \in D$:

$$\|A - B\| \leq L\|x - x_0\| \leq \frac{1}{2\|A^{-1}\|}$$

$$\Rightarrow \|A^{-1}\| \|A - B\| \leq \frac{1}{2}.$$

By the theorem (11.2), B is invertible and

$$\|B^{-1}\| \leq \frac{\|A^{-1}\|}{1 - \underbrace{\|A^{-1}\| \|A - B\|}_{\leq \frac{1}{2}}} \leq 2\|A^{-1}\|$$

$$\text{i.e. } \|Df(x)^{-1}\| \leq 2\|Df(x_0)^{-1}\|.$$

Step II: We show that the Newton iterates $x_k \in D \ \forall k$ and

$$\|x_k - x_{k-1}\| \leq r^{k-1} \|x_1 - x_0\|. \quad (*)$$

The proof is by induction.

Assume that $x_1, \dots, x_k \in D$ and that $(*)$

holds $\forall i \leq k$. We will show that $(*)$ holds

for $k+1$ and that $x_{k+1} \in D$.

$$\|x_{k+1} - x_k\| \leq \|Df(x_k)^{-1}\| \|f(x_k)\| \leq 2\|Df(x_0)^{-1}\| \|f(x_k)\|.$$

$\Rightarrow$ We need to estimate $\|f(x_k)\|$.

The linear approximation of f at x_{k-1} evaluated at x_k :

$$f(x_k) = f(x_{k-1}) + Df(x_{k-1})(x_k - x_{k-1}) + R(x_k, x_{k-1})$$

But x_k is chosen such that

$$f(x_{k-1}) + Df(x_{k-1})(x_k - x_{k-1}) = 0$$

$$\Rightarrow \|f(x_k)\| = \|R(x_k, x_{k-1})\| \underset{\text{Lemma}}{\leq} \frac{L}{2} \|x_k - x_{k-1}\|^2 \underset{\text{induction hypothesis}}{\leq}$$

$$\leq \frac{L}{2} (r^{k-1} \|x_1 - x_0\|)^2 = \frac{L r^{2k-2}}{2} \|x_1 - x_0\| \cdot \|x_1 - x_0\|$$

$$\leq \frac{r^{2k-2} L}{2} \underbrace{\|Df(x_0)^{-1}\| \|f(x_0)\|}_{\text{(One iteration of Newton)}} \|x_1 - x_0\|$$

Combining this result with the previous estimate:

$$\begin{aligned} \|x_{k+1} - x_k\| &\leq 2 \|Df(x_0)^{-1}\| \|f(x_0)\| \leq r^{2k-2} L \|Df(x_0)^{-1}\|^2 \|f(x_0)\| \|x_1 - x_0\| \\ &\leq r^{2k-1} \|x_1 - x_0\| \leq r^k \|x_1 - x_0\|. \end{aligned}$$

$\nearrow$
 $2k-1 \geq k$ and $r \leq 1/3$

So we are done with proving ② for $k+1$.

To show that $x_{k+1} \in D$:

$$\|x_{k+1} - x_0\| \leq \|x_{k+1} - x_k\| + \dots + \|x_2 - x_1\| \leq (r^k + \dots + r) \|x_1 - x_0\|$$

$$= r \underbrace{(1 + \dots + r^{k-1})}_{\leq \frac{1}{1-r}} \|x_1 - x_0\| \leq \frac{r}{1-r} \|x_1 - x_0\| = \delta. \Rightarrow x_{k+1} \in D. \quad \checkmark$$

Step 3: The sequence $\{x_k\}$ converges and the limit is a root of f .

- From the inequality $\|x_k - x_{k-1}\| \leq r^{k-1} \|x_1 - x_0\|$ it can be immediately shown that $\{x_k\}$ is a Cauchy sequence (just like in the proof of the contraction mapping Thm) $\Rightarrow x_k$ converges to a limit $x_* \in D$. (Since D is closed).

- Due to the estimate $\|f(x_k)\| \leq \frac{r^{2k-2}}{2} \|Df(x_0)^{-1}\| \|f(x_0)\| \|x_1 - x_0\|$ we know that $f(x_k) \xrightarrow{k \rightarrow \infty} 0$.

The continuity of f implies that

$$f(x_*) = f\left(\lim_{k \rightarrow \infty} x_k\right) = \lim_{k \rightarrow \infty} f(x_k) = 0 \quad \text{so } x_* \text{ is a root.}$$

Step 4: The convergence is quadratic, i.e. there exists a constant K such that for k sufficiently large

$$\|x_{k+1} - x_*\| \leq K \|x_k - x_*\|^2.$$

Proof: The $k+1$ iterate is defined as

$$0 = f(x_k) + Df(x_k)(x_{k+1} - x_k)$$

With the linear approximation of f at x_k :

$$0 = f(x_*) = f(x_k) + Df(x_k)(x_* - x_k) + R(x_*, x_k)$$

Combining this with the previous line:

$$0 = Df(x_k)(x_* - x_{k+1}) + R(x_*, x_k)$$

$$\Rightarrow x_{k+1} - x_* = Df(x_k)^{-1} R(x_*, x_k)$$

$$\Rightarrow \|x_{k+1} - x_*\| \leq \|Df(x_k)^{-1}\| \|R(x_*, x_k)\|$$

$$\leq 2 \|Df(x_0)^{-1}\| \frac{L}{2} \|x_k - x_*\|^2$$

Take $K = L \|Df(x_0)^{-1}\|$ and we are done with the proof of (at least) quadratic convergence.

QED

Remark: In the TAM we assumed that $x \mapsto Df(x)$ is Lip cont. with Lip cont. L . The following TAM will provide a practical way to estimate L . We expect this L to be bounded by the max. of the 2nd-order derivatives.