

Math 241 Chapter 15 Integral Study Guide

Important 1: Curves are always parametrized by $\vec{r}(t) = x(t)\hat{i} + y(t)\hat{j} + z(t)\hat{k}$ for $a \leq t \leq b$. Note that some components might be 0 and the \hat{k} component will definitely be 0 in 2D.

Important 2: Surfaces are always parametrized by $\vec{r}(u, v) = x(u, v)\hat{i} + y(u, v)\hat{j} + z(u, v)\hat{k}$ for u, v restricted by R . Note that often it's not u, v but x, y or z, θ or ...

Important 3: Keep in mind that $\int_C 1 ds$ is length of C , $\iint_\Sigma 1 dS$ is surface area of Σ , $\iint_R 1 dA$ is area of R and $\iiint_D 1 dV$ is volume of D .

1. Line integral of a function. One choice:

$$\int_C f ds = \int_a^b f(x(t), y(t), z(t)) \|\vec{r}'(t)\| dt$$

2. Line integral of a vector field. Lots of possibilities. This one has the most options.

- (a) Most basic. Could be so ugly as to be nonintegrable:

$$\int_C \vec{F} \cdot d\vec{r} = \int_a^b \vec{F}(x(t), y(t), z(t)) \cdot \vec{r}'(t) dt$$

- (b) If \vec{F} is conservative and f is a potential function then:

$$\int_C \vec{F} \cdot d\vec{r} = f(\text{endpt of } C) - f(\text{startpt of } C)$$

- (c) If \vec{F} is conservative and C is closed then:

$$\int_C \vec{F} \cdot d\vec{r} = 0$$

- (d) If C is the edge of Σ with induced orientation then Stokes's Theorem gives:

$$\int_C \vec{F} \cdot d\vec{r} = \iint_\Sigma (\nabla \times \vec{F}) \cdot \vec{n} dS \quad \text{Then go to 4(a)}$$

- (e) Note that there is alternate notation for this:

$$\int_C Mdx + Ndy + Pdz \quad \text{means} \quad \int_C (M\hat{i} + N\hat{j} + P\hat{k}) \cdot d\vec{r}$$

- (f) If in 2D and C is the edge of R with the cows on the left then Green's Theorem gives:

$$\int_C (M\hat{i} + N\hat{j}) \cdot d\vec{r} \quad \text{or} \quad \int_C Mdx + Ndy = \iint_R N_x - M_y dA$$

3. Surface integral of a function. One choice:

$$\iint_\Sigma f dS = \iint_R f(x(u, v), y(u, v), z(u, v)) \|\vec{r}_u \times \vec{r}_v\| dA$$

4. Surface integral of a vector field. Two possibilities.

- (a) Always unless the Divergence Theorem applies:

$$\iint_\Sigma \vec{F} \cdot \vec{n} dS = \pm \iint_R \vec{F}(x(u, v), y(u, v), z(u, v)) \cdot [\vec{r}_u \times \vec{r}_v] dA$$

- (b) If Σ is the boundary surface of a solid object D with outward orientation then we can use the Divergence Theorem (Gauss's Theorem) giving:

$$\iint_\Sigma \vec{F} \cdot \vec{n} dS = \iiint_D \nabla \cdot \vec{F} dV$$