

**Third In-Class Exam**  
**Math 246, Professor David Levermore**  
**Tuesday, 21 November 2017**

**Your Name:** \_\_\_\_\_

**UMD SID:** \_\_\_\_\_

**Discussion Instructor (circle one):**            Yan Tay            Jing Zhou  
**Discussion Time (circle one):**            8:00            9:00            10:00

**No books, notes, calculators, or any electronic devices.** If you need more space to answer a problem then use the back of one of these pages. Clearly indicate where your answer to each part of every problem is located. **Give your reasoning for full credit.** Any work that you do not want to be considered should be crossed out. Good luck!

**University Honor Pledge:** *I pledge on my honor that I have not given or received any unauthorized assistance on this examination.*

**Signature:** \_\_\_\_\_

Problem 1: \_\_\_\_\_/6                      Problem 2: \_\_\_\_\_/10

Problem 3: \_\_\_\_\_/6                      Problem 4: \_\_\_\_\_/10

Problem 5: \_\_\_\_\_/6                      Problem 6: \_\_\_\_\_/8

Problem 7: \_\_\_\_\_/8                      Problem 8: \_\_\_\_\_/8

Problem 9: \_\_\_\_\_/10                    Problem 10: \_\_\_\_\_/8

Problem 11: \_\_\_\_\_/12                   Problem 12: \_\_\_\_\_/8

Total Score: \_\_\_\_\_/100      Grade: \_\_\_\_\_

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- (1) [6] Recast the ordinary differential equation  $v'''' = \cos(v)v'''' + (v'')^4 + \sin(t^2 + v')$  as a first-order system of ordinary differential equations.

- (2) [10] Consider the vector-valued functions  $\mathbf{x}_1(t) = \begin{pmatrix} t^4 \\ 1 \end{pmatrix}$ ,  $\mathbf{x}_2(t) = \begin{pmatrix} -e^t \\ e^t \end{pmatrix}$ .

- (a) [2] Compute the Wronskian  $\text{Wr}[\mathbf{x}_1, \mathbf{x}_2](t)$ .
- (b) [3] Find  $\mathbf{A}(t)$  such that  $\mathbf{x}_1, \mathbf{x}_2$  is a fundamental set of solutions to the system  $\mathbf{x}' = \mathbf{A}(t)\mathbf{x}$  wherever  $\text{Wr}[\mathbf{x}_1, \mathbf{x}_2](t) \neq 0$ .
- (c) [2] Give a general solution to the system found in part (b).
- (d) [3] Compute the Green matrix associated with the system found in part (b).

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- (3) [6] Two interconnected tanks are filled with brine (salt water). At  $t = 0$  the first tank contains 23 liters and the second contains 32 liters. Brine with a salt concentration of 8 grams per liter flows into the first tank at 6 liters per hour. Well-stirred brine flows from the first tank into the second at 7 liters per hour, from the second into the first at 5 liters per hour, from the first into a drain at 3 liter per hour, and from the second into a drain at 4 liters per hour. At  $t = 0$  there are 17 grams of salt in the first tank and 29 grams in the second. Give an initial-value problem that governs the amount of salt in each tank as a function of time.

- (4) [10] Solve the initial-value problem

$$\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 & -1 \\ 4 & 6 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}, \quad \begin{pmatrix} x(0) \\ y(0) \end{pmatrix} = \begin{pmatrix} 0 \\ 3 \end{pmatrix}.$$

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- (5) [6] Given that 3 is an eigenvalue of the matrix

$$\mathbf{A} = \begin{pmatrix} 4 & 0 & -3 \\ 0 & 5 & 4 \\ 2 & 2 & 1 \end{pmatrix},$$

find all the eigenvectors of  $\mathbf{A}$  associated with 3.

- (6) [8] A  $4 \times 4$  matrix  $\mathbf{A}$  has the eigenpairs

$$\left( 3, \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \right), \quad \left( 4, \begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix} \right), \quad \left( -1, \begin{pmatrix} 0 \\ 1 \\ 0 \\ -1 \end{pmatrix} \right), \quad \left( -2, \begin{pmatrix} -1 \\ 1 \\ -1 \\ 1 \end{pmatrix} \right).$$

- (a) Give an invertible matrix  $\mathbf{V}$  and a diagonal matrix  $\mathbf{D}$  such that  $e^{t\mathbf{A}} = \mathbf{V}e^{t\mathbf{D}}\mathbf{V}^{-1}$ .  
(You do not have to compute either  $\mathbf{V}^{-1}$  or  $e^{t\mathbf{A}}$ !)
- (b) Give a fundamental matrix for the system  $\mathbf{x}' = \mathbf{A}\mathbf{x}$ .

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(7) [8] Find a real general solution of the system

$$\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 & 2 \\ 5 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} .$$

(8) [8] Find a real general solution of the system

$$\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -4 & 1 \\ -5 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} .$$

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- (9) [10] Sketch the phase-plane portrait for each of the systems  $\mathbf{x}' = \mathbf{A}\mathbf{x}$  from the previous two problems. Indicate typical orbits. Identify the type of this phase-plane portrait. Give a reason why the origin is either attracting, stable, unstable, or repelling.

(a)  $\mathbf{A} = \begin{pmatrix} 0 & 2 \\ 5 & 3 \end{pmatrix}$ ,

(b)  $\mathbf{A} = \begin{pmatrix} -4 & 1 \\ -5 & -2 \end{pmatrix}$ .

- (10) [8] Compute the Laplace transform of  $f(t) = u(t - 2)e^{-4t}$  from its definition. (Here  $u$  is the unit step function.)

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(11) [12] Consider the following MATLAB commands.

```
>> syms t s Y; f = [t + heaviside(t - 3)*(6 - t) - heaviside(t - 6)*6];
>> diffeqn = sym('D(D(y))(t) + 4*D(y)(t) + 20*y(t) = ' f);
>> eqntrans = laplace(diffeqn, t, s);
>> algeqn = subs(eqntrans, {'laplace(y(t),t,s),t,s'}, 'y(0)', 'D(y)(0)'), {Y, -2, 5});
>> ytrans = simplify(solve(algeqn, Y));
>> y = ilaplace(ytrans, s, t)
```

- (a) [4] Give the initial-value problem for  $y(t)$  that is being solved.  
 (b) [8] Find the Laplace transform  $Y(s)$  of the solution  $y(t)$ . (DO NOT take the inverse Laplace transform of  $Y(s)$  to find  $y(t)$ , just solve for  $Y(s)$ !)

You may refer to the table on the last page.

(12) [8] Find the inverse Laplace transform  $\mathcal{L}^{-1}[Y(s)](t)$  of the function

$$Y(s) = e^{-3s} \frac{3s + 10}{s^2 + 4s + 5}.$$

You may refer to the table on the last page.

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Workspace (Give the number of the problem being worked!)

### A Short Table of Laplace Transforms

$$\mathcal{L}[t^n e^{at}](s) = \frac{n!}{(s-a)^{n+1}} \quad \text{for } s > a.$$

$$\mathcal{L}[e^{at} \cos(bt)](s) = \frac{s-a}{(s-a)^2 + b^2} \quad \text{for } s > a.$$

$$\mathcal{L}[e^{at} \sin(bt)](s) = \frac{b}{(s-a)^2 + b^2} \quad \text{for } s > a.$$

$$\mathcal{L}[t^n j(t)](s) = (-1)^n J^{(n)}(s) \quad \text{where } J(s) = \mathcal{L}[j(t)](s).$$

$$\mathcal{L}[e^{at} j(t)](s) = J(s-a) \quad \text{where } J(s) = \mathcal{L}[j(t)](s).$$

$$\mathcal{L}[u(t-c)j(t-c)](s) = e^{-cs} J(s) \quad \text{where } J(s) = \mathcal{L}[j(t)](s) \\ \text{and } u \text{ is the unit step function.}$$