

## Math 246, Jeffrey Adams

Test 3, Friday, November 16, 2018 SOLUTIONS

Problem 1

(a) Convert the linear differential equation

$$ty''' + e^t y'' - \frac{1}{t} y' + 6y = \sin(t)$$

into a single first order matrix equation.

(b) Find the inverse Laplace transform  $\mathcal{L}^{-1}[X(s)](t)$  of the function

$$X(s) = \frac{3s + 11}{s^2 - 3s - 4}$$

*Solution:*

(a)

$$\begin{pmatrix} x_1'(t) \\ x_2'(t) \\ x_3'(t) \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\frac{6}{t} & \frac{1}{t^2} & -\frac{e^t}{t} \end{pmatrix} \begin{pmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ \sin(t) \end{pmatrix}$$

(b)

*Solution*

$$s^2 - 3s - 4 = (s + 1)(s - 4), \text{ so}$$

$$\frac{3s + 11}{s^2 - 3s - 4} = \frac{A}{s + 1} + \frac{B}{s - 4}$$

for some  $A, B$ . Combining over a common denominator gives

$$\frac{3s + 11}{s^2 - 3s - 4} = \frac{A(s - 4) + B(s + 1)}{s^2 - 3s - 4}$$

or

$$\frac{3s + 11}{s^2 - 3s - 4} = \frac{(A + B)s + (-4A + B)}{s^2 - 3s - 4}$$

So  $A + B = 2$  and  $4A + B = 11$ , which gives

$$A = \frac{-8}{5}, \quad B = \frac{23}{5}$$

So the inverse Laplace transform is

$$\mathcal{L}^{-1}\left(\frac{-\frac{8}{5}}{s+1}\right) + \mathcal{L}^{-1}\left(\frac{\frac{23}{5}}{s-4}\right)$$

By the table we conclude this equals

$$-\frac{8}{5}e^{-t} + \frac{23}{5}e^{4t}$$

Problem 2 Find the general solution of

$$ty'' + y' = 1$$

You can use the fact that the solutions to  $ty'' + y' = 0$  are 1 and  $\ln(t)$ .

*Solution:*

The normal form is  $y'' + \frac{1}{t}y' = \frac{1}{t}$ . Variation of parameters gives  $y = u_1(t) + u_2(t)\ln(t)$ , where

$$\begin{aligned}u_1' + u_2' \ln(t) &= 0 \\u_1' * 0 + u_2' \frac{1}{t} &= \frac{1}{t}.\end{aligned}$$

This gives  $u_2' = 1$ , so  $u_2 = t$ . Then  $u_1' = -\ln(t)$ , so  $u_1 = -(t \ln(t) - t)$ . Then

$$y = -(t \ln(t) - t) * 1 + t(\ln(t)) = t$$

is a particular solution, and the general solution is

$$c_1 + c_2 \ln(t) + t$$

Problem 3

Find the general real solution of the system

$$\frac{d\vec{x}}{dt} = \begin{pmatrix} -3 & 1 \\ -1 & -1 \end{pmatrix} \vec{x}(t)$$

*Solution:*

The characteristic polynomial is  $(-3-z)(-1-z)+1 = z^2+3z+z+3+1 = z^2 + 4z + 4 = (z + 2)^2$ . The  $-2$  eigenspace is given by

$$\begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

So  $\vec{v} = (1, 1)$ . So one solution is  $\vec{x}_1(t) = e^{-2t}(1, 1)$ . Take  $\vec{w} = (1, 0)$  to give another solution:

$$\begin{aligned} e^{-2t}(\vec{w} + (A + 2I)t\vec{w}) &= e^{-2t}\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) \\ &= e^{-2t}\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ -1 \end{pmatrix}\right) \\ &= e^{-2t} \begin{pmatrix} 1-t \\ -t \end{pmatrix} \end{aligned}$$

So the general solution is

$$c_1 e^{-2t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 e^{-2t} \begin{pmatrix} 1-t \\ -t \end{pmatrix}$$

There are other ways to solve this problem.

#### Problem 4

Consider the initial value problem

$$y'' + 4y' - 3y = f(t) \quad y(0) = 2, \quad y'(0) = 1$$

where

$$f(t) = \begin{cases} t & 0 \leq t \leq 1 \\ e^t & 1 < t \end{cases}$$

- (a) Compute the Laplace transform of  $f(t)$   
 (b) Determine the Laplace transform  $Y(s)$  of the solution  $y(t)$  of the equation.  
 It is *not* necessary to find the inverse Laplace transform  $y(t)$ .

*Solution:*

- (a) The function is

$$f(t) = t(u(t) - u(t-1)) + e^t u(t-1) = tu(t) + (-t + e^t)u(t-1)$$

So

$$\mathcal{L}(f)(s) = \mathcal{L}(t) + \mathcal{L}((e^t - t)u(t-1))$$

and  $\mathcal{L}(t) = \frac{1}{s^2}$ . Also

$$\mathcal{L}((e^t - 1)u(t-1)) = \mathcal{L}(u(t-1)j(t-1))$$

where  $j(t) = e^{t+1} - (t + 1)$ . Then  $\mathcal{L}(j)(s) = \mathcal{L}(ee^t - t - 1) = e\frac{1}{s-1} - \frac{1}{s^2} + \frac{1}{s}$ .  
Therefore

$$\mathcal{L}((e^t - 1)u(t - 1)) = e^{-s}\mathcal{L}(j) = e^{-s}\left(\frac{e}{s-1} - \frac{1}{s^2} + \frac{1}{s}\right)$$

(b)

$$\begin{aligned}\mathcal{L}(y'' + r4y' - 3y) &= s^2\mathcal{L}(y) - (sy'(0) + y(0)) + 4(s\mathcal{L}(y) - y(0)) - 3\mathcal{L}(y) \\ &= (s^2 + 4s - 3)\mathcal{L}(y) - (s + 2) - 8 \\ &= (s^2 + 4s - 3)\mathcal{L}(y) - s - 10\end{aligned}$$

So the equation is

$$(s^2 + 4s - 3)Y(s) - s - 10 = e^{-s}\left(\frac{e}{s-1} - \frac{1}{s^2} + \frac{1}{s}\right).$$

Problem 5

Consider the following MATLAB commands.

```
syms t s Y;
f=['t^2+exp(t)'];
eq=sym(['D(D(y))(t)+3*D(y)(t)+2*y(t)= ' f]);
leq=laplace(eq,t,s)
algeqn=subs(leq,{'laplace(y(t),t,s)', 'y(0)', 'D(y)(0)'},{Y,2,-1});
ytrans=simplify(solve(algeqn,Y));
y=ilaplace(ytrans,s,t)
```

- (a) What is the initial value problem that is being solved?  
(b) What is the value of the `algeqn` variable? Hint: it is of the form

$$2 * Y + \dots == 1/(s - 1) + \dots$$

and you should fill in the missing terms.

*Solution*

- (a) The differential equation is

$$y'' + 3y' + 2y = t^2 + e^t \quad y(0) = 2, y'(0) = -1$$

(b)

Take the Laplace transform of both sides:

$$\mathcal{L}(y'') + 3\mathcal{L}(y') + 2\mathcal{L}(y) = \mathcal{L}(t^2) + L(e^t)$$

this gives

$$s^2\mathcal{L}(y) - (sy(0) + y'(0)) + 3(s\mathcal{L}(y) - y(0)) + 2\mathcal{L}(y) = \frac{2}{s^3} + \frac{1}{s-1}$$

(the terms on the right are from the table of Laplace transforms). Plugging in  $y(0) = 2, y'(0) = -1$  gives

$$s^2\mathcal{L}(y) - (2s - 1) + 3(s\mathcal{L}(y) - 2) + 2\mathcal{L}(y) = \frac{2}{s^3} + \frac{1}{s-1}$$

and setting  $\mathcal{L}(y) = Y$  this is

$$(s^2 + 3s + 2)Y - (2s + 5) = \frac{2}{s^3} + \frac{1}{s-1}$$

Here is the literal output from Matlab:

algeqn =

$$2*Y - 2*s + 3*Y*s + Y*s^2 - 5 == 1/(s - 1) + 2/s^3$$

### Table of Laplace Transforms

$\mathcal{L}[t^n](s)$	$\frac{n!}{s^{n+1}}$	for $s > 0$
$\mathcal{L}[t^n e^{at}](s)$	$\frac{n!}{(s-a)^{n+1}}$	for $s > a$
$\mathcal{L}[e^{at} \cos(bt)](s)$	$\frac{s-a}{(s-a)^2+b^2}$	for $s > a$
$\mathcal{L}[e^{at} \sin(bt)](s)$	$\frac{b}{(s-a)^2+b^2}$	for $s > a$
$\mathcal{L}[t^n j(t)](s)$	$(-1)^n J^{(n)}(s)$	where $J(s) = \mathcal{L}[j(t)](s)$
$\mathcal{L}[e^{at} j(t)](s)$	$J(s-a)$	where $J(s) = \mathcal{L}[j(t)](s)$
$\mathcal{L}[u(t-c)j(t-c)](s)$	$e^{-cs} J(s)$	where $J(s) = \mathcal{L}[j(t)](s)$  $u$ is the unit step function