

%Kevin Paszinski 5/12/09 Math246 0231

%Extra Credit Matlab Assignment

%Attached to this PDF file is a scanned copy of the written work done with

%this assignment. The original problem given was

%(d²x)/(dt²) + b(dx/dt) + x - x² = 0 where b=[0,1]

%The scanned sheet shows the reduction of the problem into a first order

%equation (dx/dt and dy/dt). From here I found the stationary points by

%setting the derivative equal to zero. The stationary points came to (0,0)

%and (1,0). Linearization was done to find that (0,0) was a CW center and

%(1,0) was a saddle point. When graphed you get the phase portraits below.

%I printed the graphs for b=0 to b=1 on increments of 0.1 to show the small

%changes as b increased. I graphed b=0 twice to start to show a large view

%of the portrait to make sure nothing was going on with large values of t.

%The next 11 portraits are all zoomed in real close to show the slight

%changes at the stationary points as b increases.

%There is a perfectly defined saddle and center at b=0. As b increases, the

%portrait becomes distorted as the first derivative of x is being factored

%into the equation. This is causing the graph to be stretched approximately

%on the line y=-x. This deformation eventually causes the center to become

%an ellipse and then break open somewhere between b= 0.8 and 0.9. The

%saddle keeps its main shape half way through. When b approaches 0.8 the

%right hand side of the saddle remains intact but the saddle breaks on the

%left hand side opening up to the broken side of the center forming a gap

%in the center of the portrait. When b finally reaches a value of 1, the

%center of the graph finally stops distorting. The portrait seems to only

%revolve clockwise around (0,0).

%In conclusion the behavior of this second order differential equation

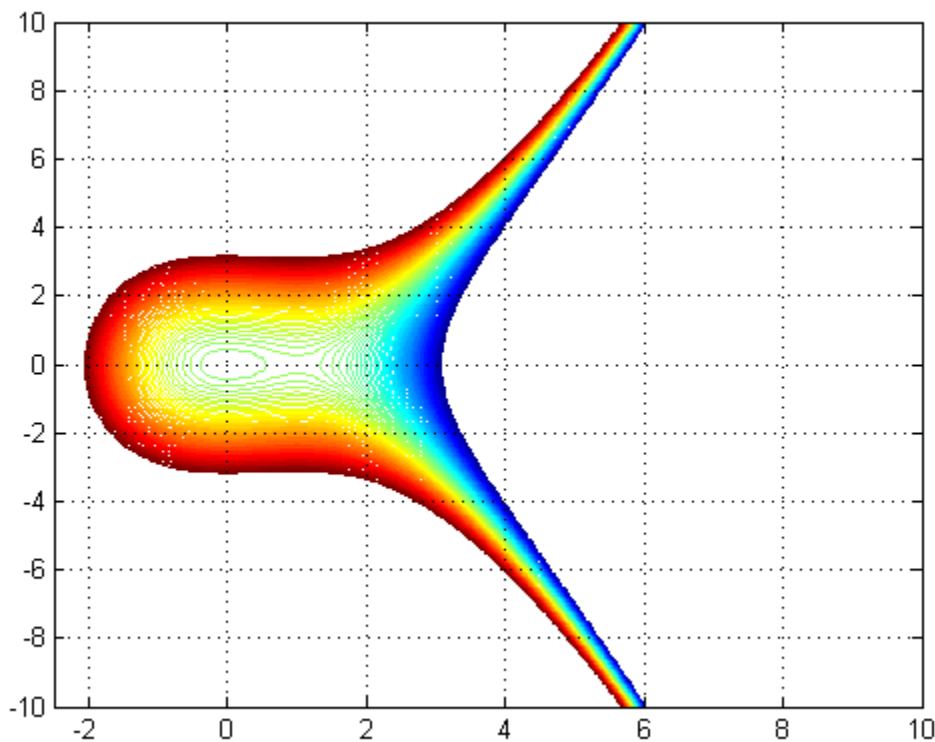
%doesn't change drastically until higher values of b. From here one

%stationary point is lost and another is redefined.

```

b=0;
f=@(x,y)(y.^2/2)+(b*y.*x)+(x.^2)/2 -(x.^3)/3;
x=-15:.1:15; y=-15:.1:15;
[X,Y]=meshgrid(x,y);
Z=f(X,Y);
level=-5:.1:5;
contour(X,Y,Z,level)
axis([-2.5 10 -10 10])
grid on

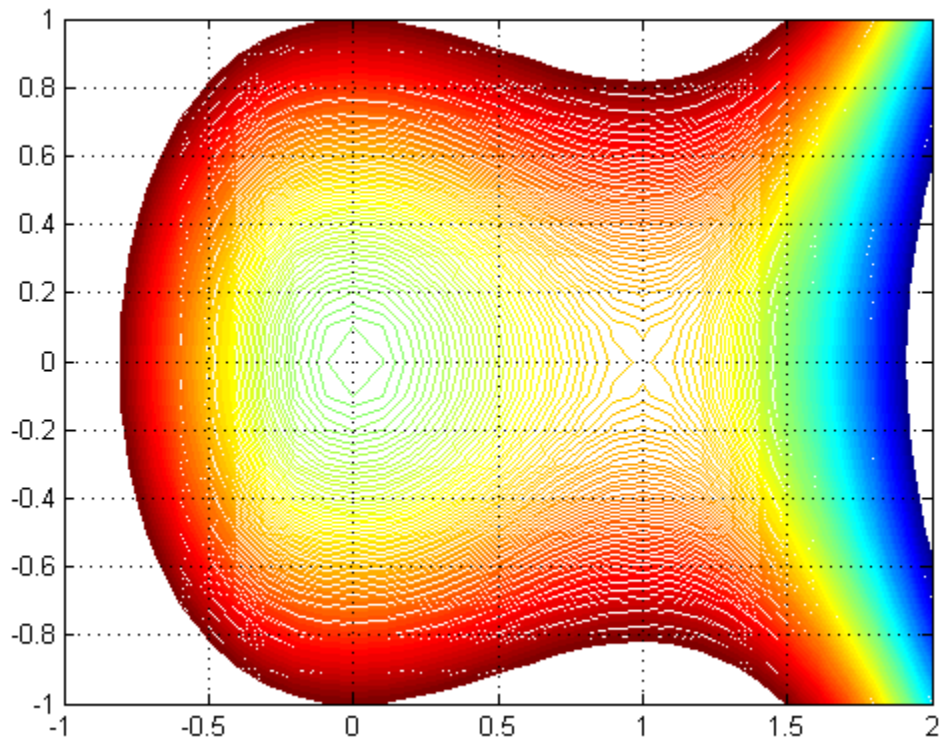
```



```

b=0;
f=@(x,y)(y.^2/2)+(b*y.*x)+(x.^2)/2 -(x.^3)/3;
x=-15:.1:15; y=-15:.1:15;
[X,Y]=meshgrid(x,y);
Z=f(X,Y);
level=-.5:.005:.5;
contour(X,Y,Z,level)
axis([-1 2 -1 1])
grid on

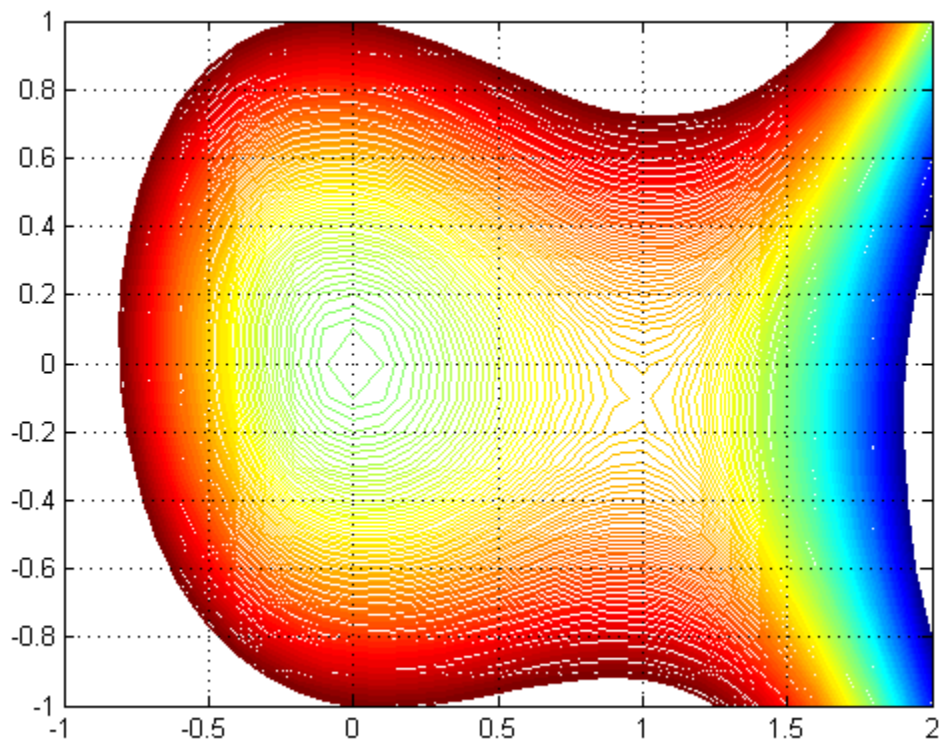
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```

b=0.1;
f=@(x,y)(y.^2/2)+(b*y.*x)+(x.^2)/2 -(x.^3)/3;
x=-15:.1:15; y=-15:.1:15;
[X,Y]=meshgrid(x,y);
z=f(X,Y);
level=-.5:.005:.5;
contour(X,Y,z,level)
axis([-1 2 -1 1])
grid on

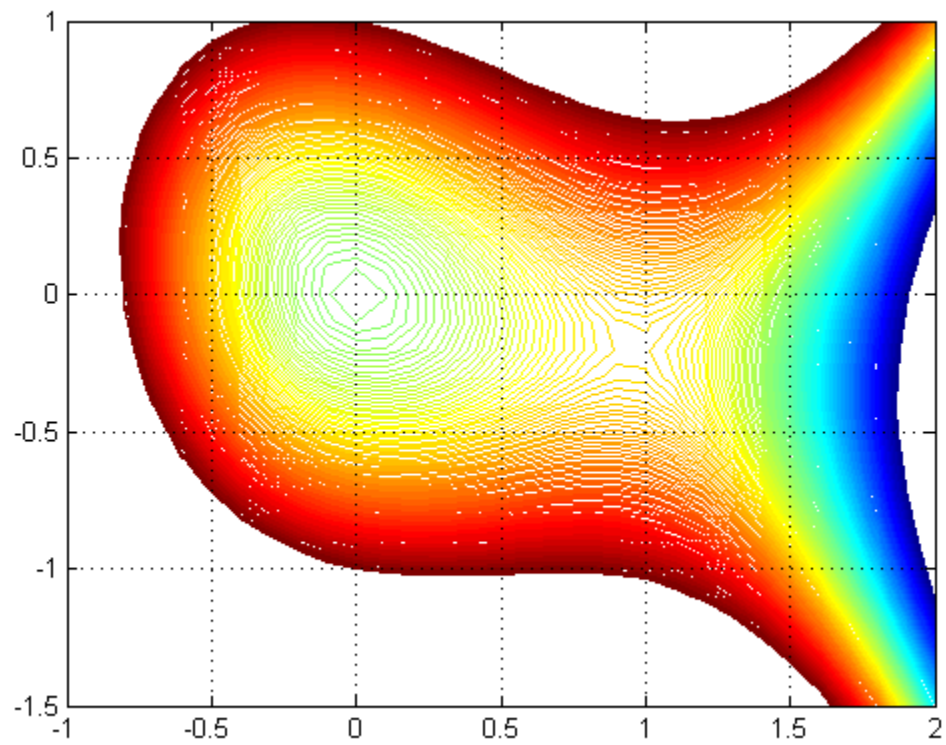
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```

b=0.2;
f=@(x,y)(y.^2/2)+(b*y.*x)+(x.^2)/2 -(x.^3)/3;
x=-15:.1:15; y=-15:.1:15;
[X,Y]=meshgrid(x,y);
z=f(X,Y);
level=-.5:.005:.5;
contour(X,Y,z,level)
axis([-1 2 -1.5 1])
grid on

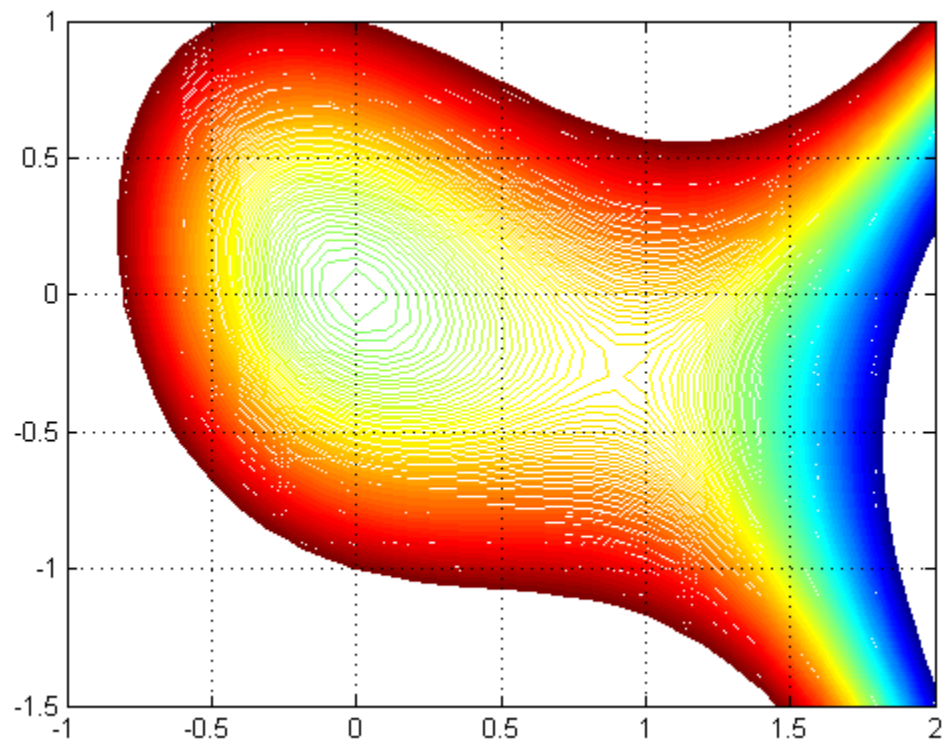
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```

b=0.3;
f=@(x,y)(y.^2/2)+(b*y.*x)+(x.^2)/2 -(x.^3)/3;
x=-15:.1:15; y=-15:.1:15;
[X,Y]=meshgrid(x,y);
z=f(X,Y);
level=-.5:.005:.5;
contour(X,Y,z,level)
axis([-1 2 -1.5 1])
grid on

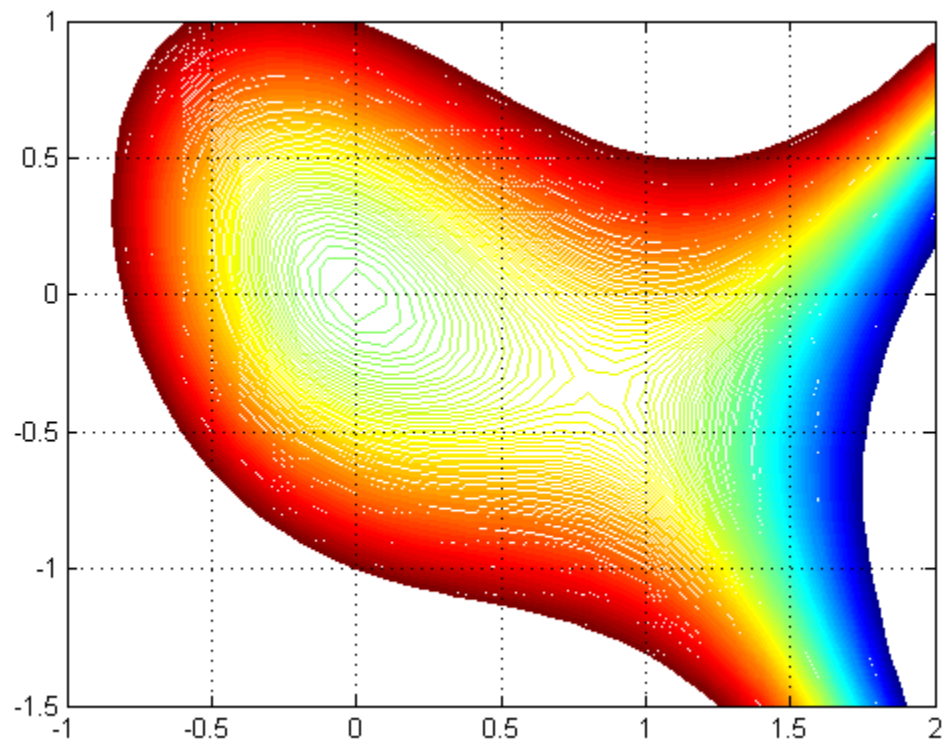
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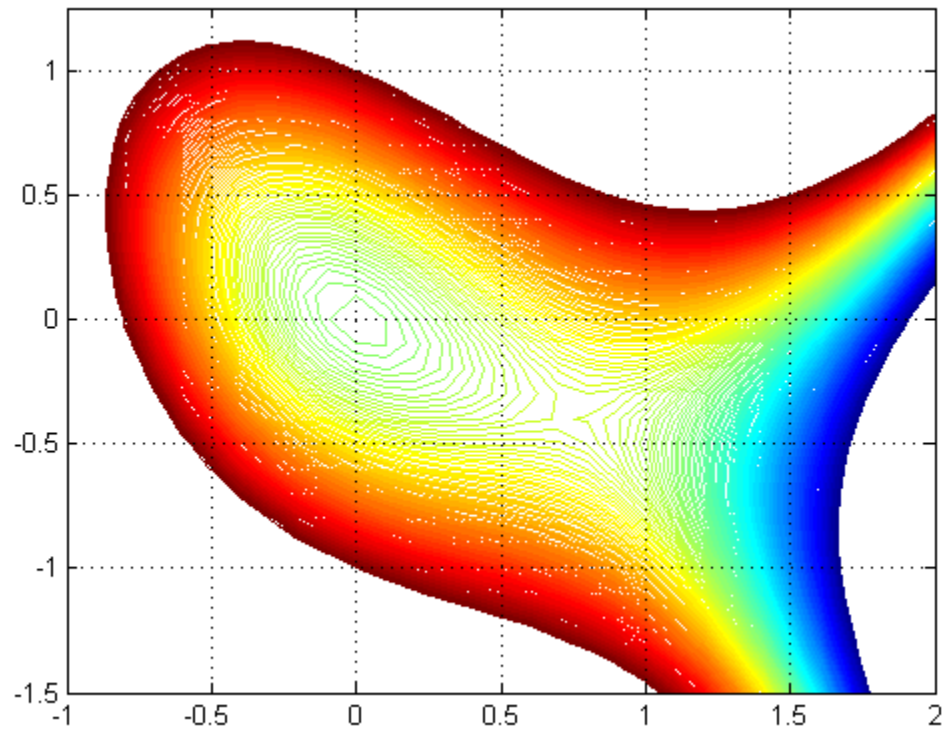
```

b=0.4;
f=@(x,y)(y.^2/2)+(b*y.*x)+(x.^2)/2 -(x.^3)/3;
x=-15:.1:15; y=-15:.1:15;
[X,Y]=meshgrid(x,y);
z=f(X,Y);
level=-.5:.005:.5;
contour(X,Y,z,level)
axis([-1 2 -1.5 1])
grid on

```



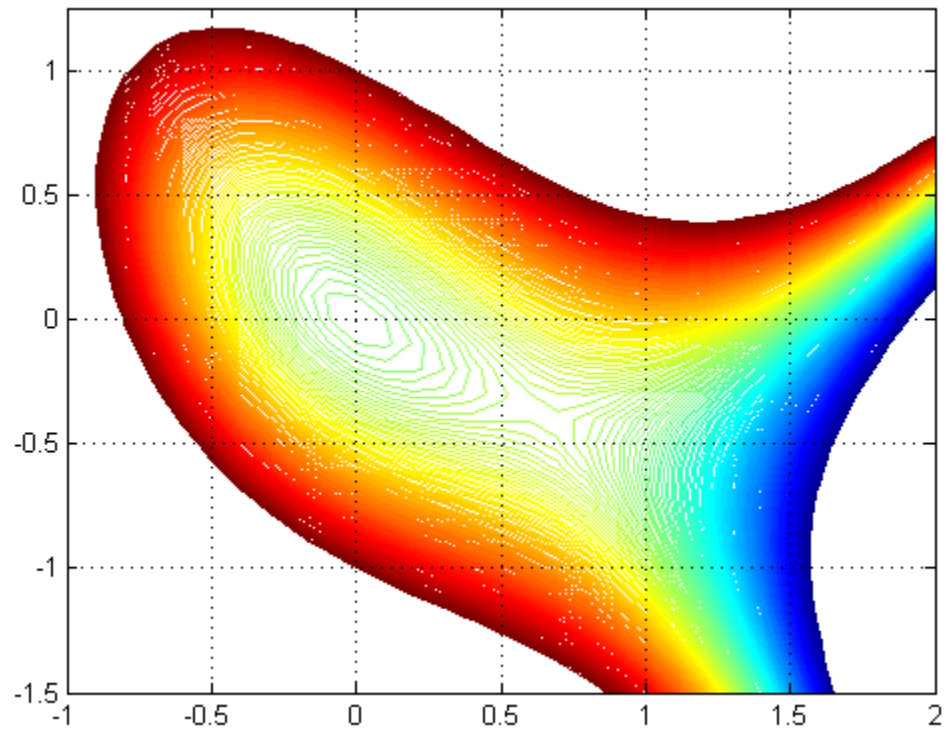
```
b=0.5;  
f=@(x,y)(y.^2/2)+(b*y.*x)+(x.^2)/2 -(x.^3)/3;  
x=-15:.1:15; y=-15:.1:15;  
[X,Y]=meshgrid(x,y);  
Z=f(X,Y);  
level=-.5:.005:.5;  
contour(X,Y,Z,level)  
axis([-1 2 -1.5 1.25])  
grid on
```



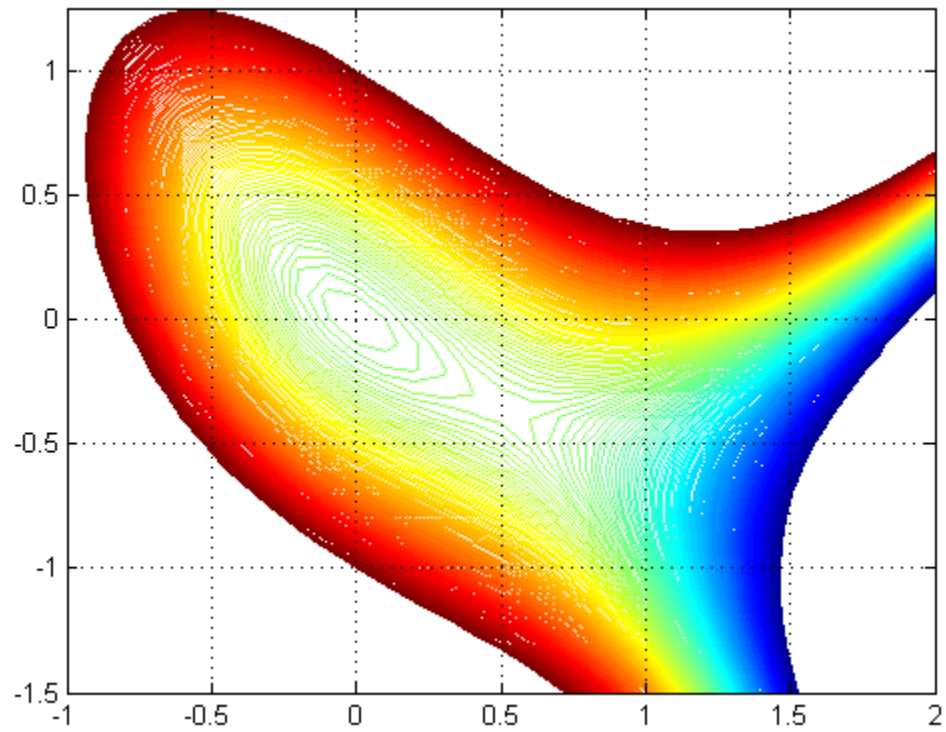
```

b=0.6;
f=@(x,y)(y.^2/2)+(b*y.*x)+(x.^2)/2 -(x.^3)/3;
x=-15:.1:15; y=-15:.1:15;
[X,Y]=meshgrid(x,y);
z=f(X,Y);
level=-.5:.005:.5;
contour(X,Y,z,level)
axis([-1 2 -1.5 1.25])
grid on

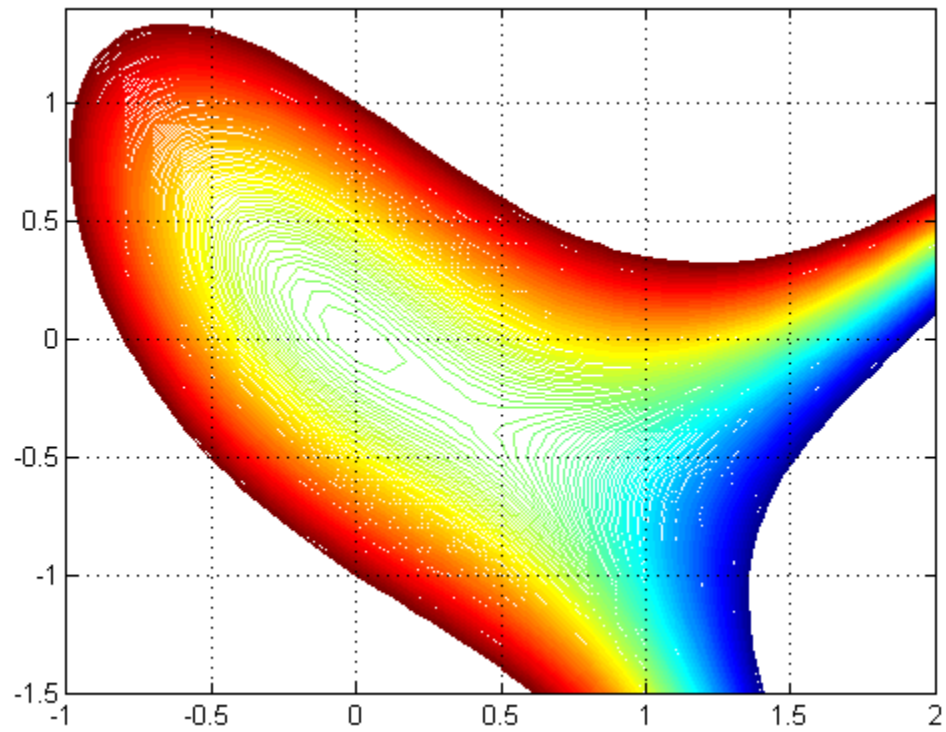
```

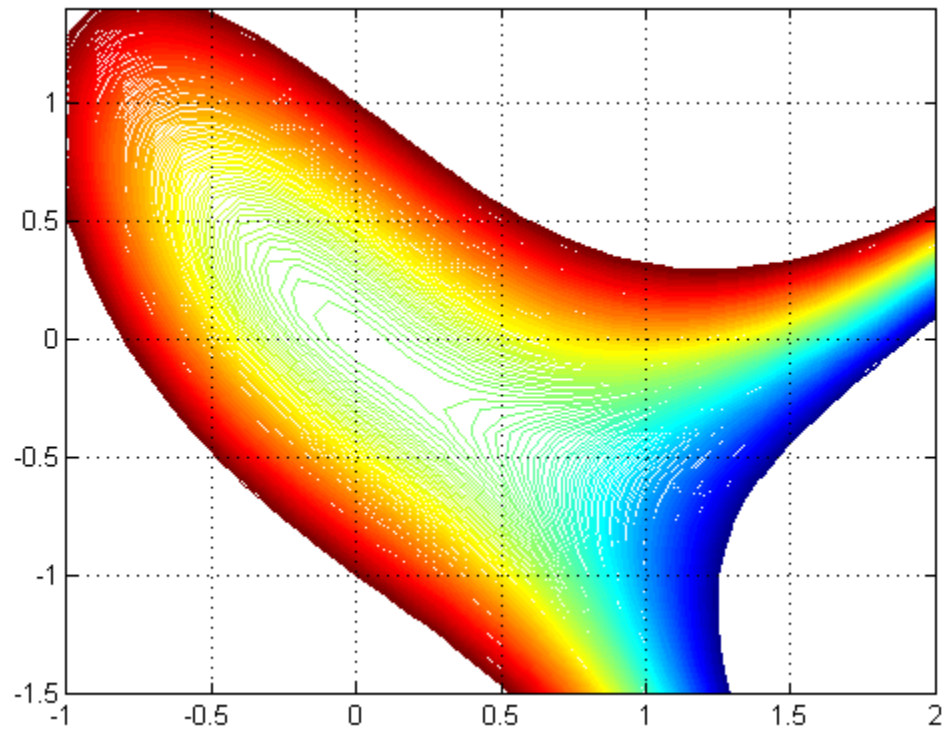
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b=0.7;  
f=@(x,y)(y.^2/2)+(b*y.*x)+(x.^2)/2 -(x.^3)/3;  
x=-15:.1:15; y=-15:.1:15;  
[X,Y]=meshgrid(x,y);  
Z=f(X,Y);  
level=-.5:.005:.5;  
contour(X,Y,Z,level)  
axis([-1 2 -1.5 1.25])  
grid on
```



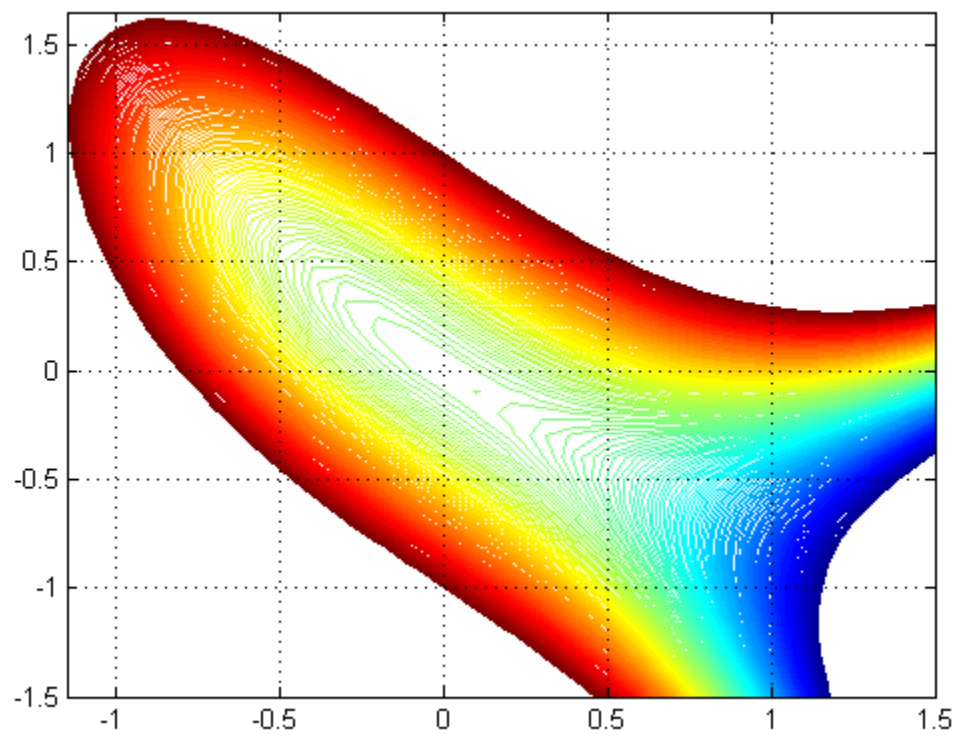
```
b=0.8;  
f=@(x,y)(y.^2/2)+(b*y.*x)+(x.^2)/2 -(x.^3)/3;  
x=-15:.1:15; y=-15:.1:15;  
[X,Y]=meshgrid(x,y);  
Z=f(X,Y);  
level=-.5:.005:.5;  
contour(X,Y,Z,level)  
axis([-1 2 -1.5 1.4])  
grid on
```



```
b=0.9;  
f=@(x,y)(y.^2/2)+(b*y.*x)+(x.^2)/2 -(x.^3)/3;  
x=-15:.1:15; y=-15:.1:15;  
[X,Y]=meshgrid(x,y);  
Z=f(X,Y);  
level=-.5:.005:.5;  
contour(X,Y,Z,level)  
axis([-1 2 -1.5 1.4])  
grid on
```



```
b=1.0;  
f=@(x,y)(y.^2/2)+(b*y.*x)+(x.^2)/2 -(x.^3)/3;  
x=-15:.1:15; y=-15:.1:15;  
[X,Y]=meshgrid(x,y);  
Z=f(X,Y);  
level=-.5:.005:.5;  
contour(X,Y,Z,level)  
axis([-1.15 1.5 -1.5 1.65])  
grid on
```



Kevin Paszinski Math 246 0231 Extra Credit

given: $\frac{d^2x}{dt^2} + b \frac{dx}{dt} + x - x^2 = 0$ where $b \in [0, 1]$

$$\frac{dx}{dt} = y \quad \left\{ \begin{array}{l} \frac{dy}{dt} = \frac{dy}{dt} \cdot \frac{dt}{dx} = \frac{dy}{dx} = \frac{-by + x^2 - x}{y} \rightarrow y dy = (-by + x^2 - x) dx \\ \frac{dy}{dt} = -by + x^2 - x \end{array} \right. \rightarrow \text{integrate both sides}$$

$$\rightarrow \frac{y^2}{2} = -byx + \frac{1}{3}x^3 - \frac{1}{2}x^2 \rightarrow \frac{1}{2}y^2 + byx - \frac{1}{3}x^3 + \frac{1}{2}x^2 = 0$$

$\rightarrow H(x, y) = \frac{1}{2}y^2 + byx - \frac{1}{3}x^3 + \frac{1}{2}x^2 = 0$

$\frac{dx}{dt} = y = f(x, y)$

Stationary Points = $(0, 0)$ and $(1, 0)$

$\frac{dy}{dt} = -by + x^2 - x = g(x, y)$

$\frac{dx}{dt} = y = 0 \rightarrow y = 0$

Linearization

$\frac{dy}{dt} = -by + x^2 - x = 0$

$A = \begin{pmatrix} \frac{dx}{dx} & \frac{dy}{dx} \\ \frac{dx}{dy} & \frac{dy}{dy} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 2x-1 & -b \end{pmatrix}$

$= -b(0) + x^2 - x = 0$

$= x^2 - x = 0$

$x(x-1) = 0$

$x = 0, 1$

@ $(0, 0)$ $A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$ $\det(A - \lambda I) = \det \begin{pmatrix} -\lambda & 1 \\ 0 & -\lambda \end{pmatrix} = (-\lambda)(-\lambda) = \lambda^2$
 $= \lambda^2 + 1$ $\lambda^2 = -1$ $\lambda = \pm i$

$(A - \lambda I) = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} - \begin{pmatrix} i & 0 \\ 0 & i \end{pmatrix} = \begin{pmatrix} -i & 1 \\ -1 & -i \end{pmatrix}$ (Clockwise)

@ $(1, 0)$ $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ $\det(A - \lambda I) = \det \begin{pmatrix} -\lambda & 1 \\ 1 & -\lambda \end{pmatrix} = \lambda^2 - 1 = \lambda^2 - 1$

for $\lambda = 1$ $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix}$ $\lambda = \pm 1$

$-x_1 + x_2 = 0$ $-x_1 = -x_2$ $x_1 = x_2$ $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$

for $\lambda = -1$ $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$ $x_1 + x_2 = 0$ $x_1 = -x_2$ $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$

So when $b=0$, there is a stationary point at $(0, 0)$ which is a center which is stable. Also there is a stationary point at $(1, 0)$ which is a saddle which is unstable.