- 1. Consider the three vectors $\bar{u} = \begin{bmatrix} -2\\1 \end{bmatrix}$, $\bar{v} = \begin{bmatrix} 1\\-1 \end{bmatrix}$ and $\bar{w} = \begin{bmatrix} 1\\1 \end{bmatrix}$.
 - (a) Show that \bar{u}, \bar{v} and \bar{w} are not linearly independent using the strict definition.
 - (b) Explain why any pair of these vectors is linearly independent.
 - (c) Give an example of a fourth vector \bar{x} which, when paired with any of \bar{u} , \bar{v} or \bar{w} , yields a pair which is linearly dependent.
- 2. Define

$$A = \begin{bmatrix} 1 & 2 & 0 \\ -2 & -4 & 1 \\ 1 & 2 & -1 \end{bmatrix}$$

(a) Solve $A\bar{x} = \bar{0}$. Express your answer in parametric form.

(b) It is a fact that
$$\begin{bmatrix} -5\\0\\2 \end{bmatrix}$$
 is a solution to $A\bar{x} = \begin{bmatrix} -5\\12\\-7 \end{bmatrix}$. Find all solutions to this equation.
Express your answer in parametric form.

- (c) Find some \bar{y} so that \bar{y} is not in the span of the columns of A and justify why it is not.
- 3. (a) Consider the transformation determined by the matrix

$$A = \begin{bmatrix} 1 & 0 & -1 & 2 \\ -1 & 2 & 1 & 0 \end{bmatrix}$$

Rewrite this transformation in the form $T(x_1, ...) = (...)$ with as many x_i as necessary for the dimensions.

- (b) Suppose a linear transformation $T : \mathbb{R}^2 \to \mathbb{R}^2$ is given by first compressing by a factor of $\frac{1}{2}$ in the x_1 -direction and then rotating 180° about the origin. Find the matrix for T and use this to find T(-2,3).
- 4. (a) Show that the transformation $T : \mathbb{R}^2 \to \mathbb{R}^3$ given by $T(x_1, x_2) = (2x_1 x_2, x_2, -3x_1)$ is a linear transformation.
 - (b) Suppose a linear transformation T corresponds to a 4×5 matrix. Explain why T is not one-to-one.
- 5. (a) Use the inverse of a matrix to solve the vector equation

$$x_1 \begin{bmatrix} 1.5\\2 \end{bmatrix} + x_2 \begin{bmatrix} -0.5\\-1 \end{bmatrix} = \begin{bmatrix} 1\\2 \end{bmatrix}$$

(b) Determine all values of h for which the following matrix is invertible.

$$\begin{bmatrix} -1 & 1 & 0 \\ 2 & 0 & 4 \\ 0 & 3 & h \end{bmatrix}$$