

Lecture 5: More on Linear Transformations

Today, we tidy up some odds and ends.

Theorem (Text, Theorem 13.1)

Let $\mathcal{B} = \{b_1, \dots, b_n\}$ be a basis for V . Let w_1, \dots, w_n be arbitrary vectors in W . Then there exists a unique $T \in \text{Hom}(V, W)$ with

$$T(b_i) = w_i, \quad 1 \leq i \leq n.$$

Proof. Uniqueness is clear.

Existence: Define $T(v)$ for $v \in V$ as follows. Write $v = x_1b_1 + \dots + x_nb_n$ and “define”

$$T(v) = \sum_{i=1}^n x_i w_i.$$

Is T well-defined?

Yes. Since \mathcal{B} is a basis, the x_i 's are uniquely determined. Also, note that T is linear. □

Now we can prove:

Theorem

Fix a basis $\mathcal{B} = (b_1, \dots, b_n)$ for V . Then the map $M_{\mathcal{B}} : \text{Hom}(V, V) \rightarrow M_n(\mathbb{R})$ sending a linear transformation T to its matrix with respect to the basis \mathcal{B} is 1:1 and onto.

Proof.

1:1: Let $T_1, T_2 \in \text{Hom}(V, V)$. Suppose $M_{\mathcal{B}}(T_1) = M_{\mathcal{B}}(T_2) = (a_{ij})$.

Then for $1 \leq j \leq n$, $T_1(b_j) = \sum_{i=1}^n a_{ij} b_i$ and

$$T_2(b_j) = \sum_{i=1}^n a_{ij} b_i.$$

Thus, $T_1(b_j) = T_2(b_j)$ hence $T_1 = T_2$.

onto: Let $(a_{ij}) \in M_n(\mathbb{R})$.

Then define $w_j = \sum_{i=1}^n a_{ij} b_i$, $1 \leq j \leq n$.

There exists T with $T(b_i) = w_i$, $1 \leq i \leq n$. □

Back to $T : V \longrightarrow W$

There are two useful subsets.

Definition

The **Range** of T , denoted $T(V)$ or $R(T)$ is defined as

$$T(V) := \{T(v) : v \in V\} \subset W.$$

Lemma: $T(V)$ is a subspace.

Proof. Use the fact that T is linear.

Definition

The **Nullspace** of T , denoted $N(T)$ is defined as

$$N(T) := \{v \in V : T(v) = 0\} \subset V.$$

Lemma: $N(T)$ is a subspace.

Proof. Use the fact that T is linear.

A dimension formula

Theorem (Text, Theorem 13.9)

Let $T \in \text{Hom}(V, W)$. Then

$$\dim T(V) + \dim N(T) = \dim V$$

To prove this, we will need a very useful proposition.

Proposition

Any linearly independent set $\{v_1, \dots, v_k\} \in V$ can be completed to a basis $\{v_1, \dots, v_k, v_{k+1}, \dots, v_n\}$ for V .

Proof. Assume $\dim V = n$. If $\{v_1, \dots, v_k\}$ spans V we are done. Otherwise there exists a vector v_{k+1} that is not in the span of $\{v_1, \dots, v_k\} \in V$. Then $\{v_1, \dots, v_k, v_{k+1}\}$ is still independent. If $\{v_1, \dots, v_k, v_{k+1}\}$ spans V , we are done, otherwise, continue. We will be done in $n - k$ steps.

Remark: Any spanning set can be refined to a basis.

Proof of Theorem 13.9. Assume $\dim V = n$ and $\dim N(T) = k$.

Choose a basis $\{b_1, \dots, b_k\}$ for $N(T)$ and complete it to a basis $\{b_1, \dots, b_k, b_{k+1}, \dots, b_n\}$ for V . It sufficed to prove

Claim: $\{T(b_{k+1}), \dots, T(b_n)\}$ is a basis for $R(T)$.

Spanning set: Clear.

Independent set: Suppose $x_{k+1}T(b_{k+1}) + \dots + x_nT(b_n) = 0$. Then $x_{k+1}b_{k+1} + \dots + x_nb_n \in N(T)$ and hence

$$x_{k+1}b_{k+1} + \dots + x_nb_n = x_1b_1 + \dots + x_kb_k.$$

Thus

$$x_1b_1 + \dots + x_kb_k - x_{k+1}b_{k+1} - \dots - x_nb_n = 0$$

But $\{b_1, \dots, b_k, b_{k+1}, \dots, b_n\}$ is a basis, so all the coefficients x_i , $1 \leq i \leq n$ are zero. Hence x_{k+1}, \dots, x_n are zero. □

First, we need

Proposition

Suppose $T : V \rightarrow W$. Then T is 1:1 $\iff N(T) = \{0\}$.

Proof. (\implies) Suppose $T(v) = 0$. Then since $T(0) = 0$, we have $v = 0$, hence if $v \in N(T)$ then $v = 0$.

(\impliedby) Suppose $T(v_1) = T(v_2)$. Then since T is linear $T(v_1 - v_2) = 0$, hence $v_1 - v_2 \in N(T)$ and thus $v_1 - v_2 = 0$. Finally, $v_1 = v_2$. \square

Proposition

Let $T \in \text{End}(V)$ (so $V = W$). Then T is 1:1 $\iff T$ is onto.

Proof. We use $\dim V = \dim R(T) + \dim N(T)$.

(\implies) T is 1:1 so $N(T) = 0$, hence $\dim R(T) = \dim V$, thus $R(T) = V$ (since $R(T) \subset V$).

(\impliedby) T is onto, so $R(T) = V$ and $\dim R(T) = \dim V$. Thus $\dim N(T) = 0$ and so $N(T) = \{0\}$.

Warning: This is not true if $W \neq V$.

Now do problem pg. 108 # 10.