

Topics for Exam 4

Parametrizations you should know:

straight line from \vec{A} to \vec{B} : $\vec{r}(t) = \vec{A} + (\vec{B} - \vec{A})t$ with $0 \leq t \leq 1$

circle $x^2 + y^2 = R^2, z = 0$: $\vec{r}(t) = (R \cos t, R \sin t, 0)$ with $0 \leq t \leq 2\pi$

sphere $x^2 + y^2 + z^2 = R^2$: $\vec{r}(\phi, \theta) = (R \sin \phi \cos \theta, R \sin \phi \sin \theta, R \cos \phi)$ with $0 \leq \theta \leq 2\pi, 0 \leq \phi \leq \pi$

cylinder $x^2 + y^2 = R^2, a \leq z \leq b$: $\vec{r}(\theta, z) = (R \cos \theta, R \sin \theta, z)$ with $0 \leq \theta \leq 2\pi, a \leq z \leq b$

graph of function: points $z = f(x, y)$ for $a \leq x \leq b, c \leq y \leq d$: $\vec{r}(x, y) = (x, y, f(x, y))$ with $a \leq x \leq b, c \leq y \leq d$

Line integrals

scalar function f : $ds = \|\vec{r}'\| dt$

“work integral” for vector field \vec{F} : $d\vec{r} = \vec{r}' dt$

Surface integrals

scalar function f : $dS = \|\vec{r}_u \times \vec{r}_v\| du dv$

“flux integral” for vector field \vec{F} : $\vec{n} dS = (\vec{r}_u \times \vec{r}_v) du dv$

Finding potential f for vector field \vec{F} : If $\text{curl } \vec{F} = \vec{0}$ there exists a potential $f(x, y, z)$ (in domain without “holes”)

1. $f_x = F_1$: taking antiderivative w.r.t. x gives $f(x, y, z) = (\dots) + g(y, z)$

2. $f_y = F_2$ gives $g_y(y, z) = \dots$, taking antiderivative w.r.t. y gives $g(y, z) = (\dots) + h(z)$

3. $f_z = F_3$ gives $h'(z) = \dots$, taking antiderivative w.r.t. z gives $h(z) = (\dots)$ (we can use constant $C = 0$)

Fundamental theorem of line integrals: $\int_{\mathcal{C}} \text{grad } f \cdot d\vec{r} = f(\vec{B}) - f(\vec{A})$

The curve \mathcal{C} starts at point \vec{A} and ends at point \vec{B} .

Green's theorem: $\iint_R \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dA = \int_{\mathcal{C}} (F_1 dx + F_2 dy)$

The curve \mathcal{C} is the boundary of the 2D region R , oriented counter clockwise.

Divergence theorem: $\iiint_D \text{div } \vec{F} dV = \iint_{\Sigma} \vec{F} \cdot \vec{n} dS$

The surface Σ is the boundary of the 3D region D , with the normal vector \vec{n} pointing outside.