

STRICTLY CONVEX ENTROPY AND ENTROPY STABLE SCHEMES FOR REACTIVE EULER EQUATIONS

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ABSTRACT. This paper presents entropy analysis and entropy stable (ES) finite difference schemes for the reactive Euler equations with chemical reactions. For such equations we point out that the thermodynamic entropy is no longer strictly convex. To address this issue, we propose a strictly convex entropy function by adding an extra term to the thermodynamic entropy. Thanks to the strict convexity of the proposed entropy, the Roe-type dissipation operator in terms of the entropy variables can be formulated. Furthermore, we construct two sets of second-order entropy preserving (EP) numerical fluxes for the reactive Euler equations. Based on the EP fluxes and the Roe-type dissipation operators, high-order EP/ES fluxes are derived. Numerical experiments validate the designed accuracy and good performance of our schemes for smooth and discontinuous initial value problems. The entropy decrease of ES schemes is verified as well.

1. INTRODUCTION

This paper is concerned with the reactive Euler equations describing inviscid compressible flow with chemical reactions, which are fundamental for modeling detonations. In one dimension (1D), these equations read as [9, 12]

$$(1.1) \quad \partial_t \begin{pmatrix} \rho \\ \rho u \\ \rho E \\ \rho Y \end{pmatrix} + \partial_x \begin{pmatrix} \rho u \\ \rho u^2 + p \\ \rho E u + p u \\ \rho u Y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ \omega \end{pmatrix},$$

where ρ is the fluid density, u is the velocity, p is the pressure, E is the total energy and Y is the reactant mass fraction. The source term is assumed to be in an Arrhenius form

$$\omega = -\tilde{K}\rho Y e^{-\tilde{T}/T},$$

where $T = p/\rho$ is the temperature, $\tilde{T} > 0$ is the activation constant temperature and $\tilde{K} > 0$ is a constant rate coefficient. The equation of state is $\rho E = \frac{1}{2}\rho u^2 + \frac{p}{\gamma-1} + q\rho Y$ with $q > 0$ the heat release of reaction and γ the specific heat ratio.

Generally, for N chemical species there should be N species conservation equations for Y_i , $i = 1, 2, \dots, N$, with Y_i being the mass fraction of species i . The above reactive Euler equations (1.1) are a simplified form under the assumption that there are only two species present, reacted and unreacted species, and that

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the unreacted species is converted to reacted species by a one-step irreversible chemical reaction [10,12]. Though relatively simple in form, (1.1) can give complicated stable and unstable wave patterns, which have been observed in experiments [4,10]. Due to the practical importance, the reactive Euler equations have been widely investigated both theoretically and numerically in the past decades; see e.g. [4,7,9,10,13,20,21,33].

Eqs. (1.1) are a system of hyperbolic balance laws and degenerate to the Euler equations when $Y = 0$. For these equations as hyperbolic systems, it is well known that entropy conditions are necessary to determine the correct weak solution across a shock. Then it is natural for corresponding numerical schemes to satisfy a discrete version of the entropy condition in computations. Actually, such schemes for hyperbolic conservation laws have been well developed since the pioneer work of Osher and Tadmor [26,27,31,32]. In particular, Tadmor [31] proposed a framework to construct second-order entropy conservative (EC) fluxes, which are locally consistent with the given entropy conservation. Furthermore, entropy stable (ES) fluxes are obtained by adding dissipation operators to the EC fluxes [31]. Using these fluxes as building blocks, high-order EC/ES schemes are designed in [25] and [17]. Though the framework in [31] is quite general, some additional efforts are needed to obtain explicit expressions of the EC fluxes. This issue is addressed in [22,28] for the compressible Euler equations by choosing a suitable set of algebraic variables. Following the procedure of [22,28], EC fluxes are derived for the shallow water equations [15], magnetohydrodynamic systems [6,34,35] and relativistic hydrodynamics [11]. Moreover, numerical fluxes that are both EC and kinetic-energy preserving (KEP) are proposed in [5] for the Euler equations. Except for those based on the framework in [31], ES schemes have also been developed via the summation-by-parts property; see e.g. [8,14,18,19].

In this paper, we aim to construct ES finite difference schemes for the reactive Euler equations in both one- and two-dimensions on a Cartesian mesh. First, we point out that the thermodynamic entropy is no longer strictly convex for the reactive Euler equations. To address this issue, we propose a strictly convex entropy function by adding an extra term ρY^2 to the thermodynamic entropy. As a result, a new entropy-entropy flux pair is obtained for the reactive Euler equations. Thanks to the strict convexity of the proposed entropy, the Roe-type dissipation operator in terms of the entropy variables can be formulated [28]. Note that such dissipation operators are not available based on the thermodynamic entropy, as it is not strictly convex. Additionally, for the reactive Euler equations as hyperbolic balance laws, the strict convexity of entropy function is crucial for the global existence of solution [36]. The present strictly convex entropy may be helpful for the theoretical analysis of the reactive Euler equations.

Furthermore, we construct two sets of second-order entropy preserving (EP) fluxes by extending those in [5,28] for the Euler equations within the framework of [31]. Here we use EP instead of EC due to the source term in the entropy equation. In particular, the EP fluxes extended from [5] are also KEP. With the EP fluxes and the above Roe-type dissipation operators, high-order EP/ES fluxes are derived following [17,25], where the sign-preserving ENO [16] and WENO [3] reconstructions are employed for high-order dissipation operators. Numerical experiments in 1D and 2D not only validate the designed accuracy of our schemes but also demonstrate

their good performance for problems with discontinuities. The entropy decrease of ES schemes is verified as well.

The rest of the paper is organized as follows. In Section 2, we present a strictly convex entropy for the reactive Euler equations. In Section 3, we derive ES schemes in 1D and extensions to 2D are given in Section 4. Section 5 provides some numerical experiments to validate our schemes. Finally, some conclusions and remarks are given in Section 6.

2. STRICTLY CONVEX ENTROPY FOR REACTIVE EULER EQUATIONS

2.1. **1D case.** The 1D reactive Euler equations (1.1) can be written as

$$(2.1) \quad \partial_t U + \partial_x F(U) = Q(U),$$

where

$$U = \begin{pmatrix} \rho \\ \rho u \\ \rho E \\ \rho Y \end{pmatrix}, F(U) = \begin{pmatrix} \rho u \\ \rho u^2 + p \\ \rho E u + p u \\ \rho u Y \end{pmatrix}, Q(U) = \begin{pmatrix} 0 \\ 0 \\ 0 \\ \omega \end{pmatrix}.$$

Let $s = \ln(p) - \gamma \ln(\rho)$ be the thermodynamic entropy and define

$$(2.2) \quad \hat{\eta} = \frac{-\rho s}{\gamma - 1}, \quad \hat{\phi} = \frac{-\rho u s}{\gamma - 1},$$

which are the classical entropy and entropy flux for the Euler equations, respectively. It is direct to verify for the reactive Euler equations (2.1) that

$$(2.3) \quad \partial_t \hat{\eta} + \partial_x \hat{\phi} = \frac{\rho}{p} q \omega \leq 0,$$

which implies that $(\hat{\eta}, \hat{\phi})$ may be an entropy-entropy flux pair for (2.1). However, for (2.1) $\hat{\eta}$ is no longer strictly convex. To see this, we compute

$$\hat{\eta}_U := \frac{\partial \hat{\eta}}{\partial U} = \begin{pmatrix} \frac{\gamma - s}{\gamma - 1} - \frac{\rho u^2}{2p} \\ \frac{\rho u}{p} \\ -\frac{\rho}{p} \\ q \frac{\rho}{p} \end{pmatrix}.$$

Note that the third and fourth entries of $\hat{\eta}_U$ are proportional. Then the third and fourth rows of the Hessian matrix $\hat{\eta}_{UU}$ are proportional and thus $\hat{\eta}_{UU}$ is singular. This indicates that $\hat{\eta}$ is not strictly convex.

To address the above problem, we propose the following entropy-entropy flux pair

$$(2.4) \quad \eta = \hat{\eta} + \rho Y^2, \quad \phi = \hat{\phi} + \rho u Y^2$$

by adding ρY^2 and $\rho u Y^2$ to $\hat{\eta}$ and $\hat{\phi}$, respectively. It follows from the first and fourth equations of (2.1) that

$$\partial_t(\rho Y^2) + \partial_x(\rho u Y^2) = 2Y\omega \leq 0.$$

With this and (2.3), we have

$$(2.5) \quad \partial_t \eta + \partial_x \phi = (q \frac{\rho}{p} + 2Y)\omega \leq 0.$$

On the other hand, the corresponding entropy variable of η is

$$(2.6) \quad V := \eta_U = \begin{pmatrix} \frac{\gamma-s}{\gamma-1} - \frac{\rho u^2}{2p} - Y^2 \\ \frac{\rho u}{p} \\ -\frac{\rho}{p} \\ q\frac{\rho}{p} + 2Y \end{pmatrix}$$

and the Hessian matrix is given by

$$(2.7) \quad \eta_{UU} = \begin{pmatrix} \frac{\gamma-1}{\gamma-1} \frac{1}{\rho} + (\gamma-1) \frac{\rho u^4}{4p^2} + 2 \frac{Y^2}{\rho} & -(\gamma-1) \frac{\rho u^3}{2p^2} & -\frac{1}{p} + (\gamma-1) \frac{\rho u^2}{2p^2} & q \frac{1}{p} - (\gamma-1) q \frac{\rho u^2}{2p^2} - 2 \frac{Y}{\rho} \\ -(\gamma-1) \frac{\rho u^3}{2p^2} & \frac{1}{p} + (\gamma-1) \frac{\rho u^2}{p^2} & -(\gamma-1) \frac{\rho u}{p^2} & (\gamma-1) q \frac{\rho u}{p^2} \\ -\frac{1}{p} + (\gamma-1) \frac{\rho u^2}{2p^2} & -(\gamma-1) \frac{\rho u}{p^2} & (\gamma-1) \frac{\rho}{p^2} & -(\gamma-1) q \frac{\rho}{p^2} \\ q \frac{1}{p} - (\gamma-1) q \frac{\rho u^2}{2p^2} - 2 \frac{Y}{\rho} & (\gamma-1) q \frac{\rho u}{p^2} & -(\gamma-1) q \frac{\rho}{p^2} & (\gamma-1) q^2 \frac{\rho}{p^2} + \frac{2}{\rho} \end{pmatrix}.$$

The positive definiteness of the above matrix is proved as follows. Additionally, the entropy potential of the entropy-entropy flux pair (η, ϕ) can be computed as $\psi := V^T F - \phi = \rho u$, which is the same as that for the Euler equations. Here the superscript T stands for the transpose operator.

Theorem 2.1. *The Hessian matrix η_{UU} in (2.7) is positive definite. Namely, the entropy function η in (2.4) is strictly convex.*

Proof. We prove this by showing that all the leading principal minors of η_{UU} are positive. Note that the leading principle 3×3 submatrix of η_{UU} is actually $A_3 := A_{\text{Euler}} + \text{diag}(2 \frac{Y^2}{\rho}, 0, 0)$, where A_{Euler} is the Hessian matrix of the classical entropy $\hat{\eta}$ for the Euler equations and thereby is positive definite. Then A_3 is positive definite and the first three leading principal minors of η_{UU} are positive. Next we only need to show that the fourth leading principal minor, i.e., the determinant of η_{UU} , is positive. To do this, we compute

$$\begin{aligned} |\eta_{UU}| &= \begin{vmatrix} \frac{\gamma-1}{\gamma-1} \frac{1}{\rho} + (\gamma-1) \frac{\rho u^4}{4p^2} + 2 \frac{Y^2}{\rho} & -(\gamma-1) \frac{\rho u^3}{2p^2} & -\frac{1}{p} + (\gamma-1) \frac{\rho u^2}{2p^2} & q \frac{1}{p} - (\gamma-1) q \frac{\rho u^2}{2p^2} - 2 \frac{Y}{\rho} \\ -(\gamma-1) \frac{\rho u^3}{2p^2} & \frac{1}{p} + (\gamma-1) \frac{\rho u^2}{p^2} & -(\gamma-1) \frac{\rho u}{p^2} & (\gamma-1) q \frac{\rho u}{p^2} \\ -\frac{1}{p} + (\gamma-1) \frac{\rho u^2}{2p^2} & -(\gamma-1) \frac{\rho u}{p^2} & (\gamma-1) \frac{\rho}{p^2} & -(\gamma-1) q \frac{\rho}{p^2} \\ q \frac{1}{p} - (\gamma-1) q \frac{\rho u^2}{2p^2} & (\gamma-1) q \frac{\rho u}{p^2} & -(\gamma-1) q \frac{\rho}{p^2} & (\gamma-1) q^2 \frac{\rho}{p^2} \end{vmatrix} \\ &+ \begin{vmatrix} \frac{\gamma-1}{\gamma-1} \frac{1}{\rho} + (\gamma-1) \frac{\rho u^4}{4p^2} + 2 \frac{Y^2}{\rho} & -(\gamma-1) \frac{\rho u^3}{2p^2} & -\frac{1}{p} + (\gamma-1) \frac{\rho u^2}{2p^2} & q \frac{1}{p} - (\gamma-1) q \frac{\rho u^2}{2p^2} - 2 \frac{Y}{\rho} \\ -(\gamma-1) \frac{\rho u^3}{2p^2} & \frac{1}{p} + (\gamma-1) \frac{\rho u^2}{p^2} & -(\gamma-1) \frac{\rho u}{p^2} & (\gamma-1) q \frac{\rho u}{p^2} \\ -\frac{1}{p} + (\gamma-1) \frac{\rho u^2}{2p^2} & -(\gamma-1) \frac{\rho u}{p^2} & (\gamma-1) \frac{\rho}{p^2} & -(\gamma-1) q \frac{\rho}{p^2} \\ -2 \frac{Y}{\rho} & 0 & 0 & \frac{2}{\rho} \end{vmatrix} \\ &= \begin{vmatrix} \frac{\gamma-1}{\gamma-1} \frac{1}{\rho} + (\gamma-1) \frac{\rho u^4}{4p^2} + 2 \frac{Y^2}{\rho} & -(\gamma-1) \frac{\rho u^3}{2p^2} & -\frac{1}{p} + (\gamma-1) \frac{\rho u^2}{2p^2} & q \frac{1}{p} - (\gamma-1) q \frac{\rho u^2}{2p^2} - 2 \frac{Y}{\rho} \\ -(\gamma-1) \frac{\rho u^3}{2p^2} & \frac{1}{p} + (\gamma-1) \frac{\rho u^2}{p^2} & -(\gamma-1) \frac{\rho u}{p^2} & (\gamma-1) q \frac{\rho u}{p^2} \\ -\frac{1}{p} + (\gamma-1) \frac{\rho u^2}{2p^2} & -(\gamma-1) \frac{\rho u}{p^2} & (\gamma-1) \frac{\rho}{p^2} & -(\gamma-1) q \frac{\rho}{p^2} \\ -2 \frac{Y}{\rho} & 0 & 0 & \frac{2}{\rho} \end{vmatrix} \\ &= 2 \frac{Y}{\rho} \begin{vmatrix} -(\gamma-1) \frac{\rho u^3}{2p^2} & -\frac{1}{p} + (\gamma-1) \frac{\rho u^2}{2p^2} & q \frac{1}{p} - (\gamma-1) q \frac{\rho u^2}{2p^2} - 2 \frac{Y}{\rho} \\ \frac{1}{p} + (\gamma-1) \frac{\rho u^2}{p^2} & -(\gamma-1) \frac{\rho u}{p^2} & (\gamma-1) q \frac{\rho u}{p^2} \\ -(\gamma-1) \frac{\rho u}{p^2} & (\gamma-1) \frac{\rho}{p^2} & -(\gamma-1) q \frac{\rho}{p^2} \end{vmatrix} + \frac{2}{\rho} |A_3|. \end{aligned}$$

Furthermore, we have

$$\begin{aligned}
 & 2\frac{Y}{\rho} \begin{vmatrix} -(\gamma-1)\frac{\rho u^3}{2p^2} & -\frac{1}{p} + (\gamma-1)\frac{\rho u^2}{2p^2} & q\frac{1}{p} - (\gamma-1)q\frac{\rho u^2}{2p^2} - 2\frac{Y}{\rho} \\ \frac{1}{p} + (\gamma-1)\frac{\rho u^2}{p^2} & -(\gamma-1)\frac{\rho u}{p^2} & (\gamma-1)q\frac{\rho u}{p^2} \\ -(\gamma-1)\frac{\rho u}{p^2} & (\gamma-1)\frac{\rho}{p^2} & -(\gamma-1)q\frac{\rho}{p^2} \end{vmatrix} \\
 &= 2\frac{Y}{\rho} \begin{vmatrix} -(\gamma-1)\frac{\rho u^3}{2p^2} & -\frac{1}{p} + (\gamma-1)\frac{\rho u^2}{2p^2} & q\frac{1}{p} - (\gamma-1)q\frac{\rho u^2}{2p^2} \\ \frac{1}{p} + (\gamma-1)\frac{\rho u^2}{p^2} & -(\gamma-1)\frac{\rho u}{p^2} & (\gamma-1)q\frac{\rho u}{p^2} \\ -(\gamma-1)\frac{\rho u}{p^2} & (\gamma-1)\frac{\rho}{p^2} & -(\gamma-1)q\frac{\rho}{p^2} \end{vmatrix} \\
 &+ 2\frac{Y}{\rho} \begin{vmatrix} -(\gamma-1)\frac{\rho u^3}{2p^2} & -\frac{1}{p} + (\gamma-1)\frac{\rho u^2}{2p^2} & -2\frac{Y}{\rho} \\ \frac{1}{p} + (\gamma-1)\frac{\rho u^2}{p^2} & -(\gamma-1)\frac{\rho u}{p^2} & 0 \\ -(\gamma-1)\frac{\rho u}{p^2} & (\gamma-1)\frac{\rho}{p^2} & 0 \end{vmatrix} \\
 &= -4\frac{Y^2}{\rho^2} \begin{vmatrix} \frac{1}{p} + (\gamma-1)\frac{\rho u^2}{p^2} & -(\gamma-1)\frac{\rho u}{p^2} \\ -(\gamma-1)\frac{\rho u}{p^2} & (\gamma-1)\frac{\rho}{p^2} \end{vmatrix}
 \end{aligned}$$

and

$$\begin{aligned}
 \frac{2}{\rho}|A_3| &= \frac{2}{\rho}|A_{\text{Euler}}| + \frac{2}{\rho} \begin{vmatrix} 2\frac{Y^2}{\rho} & -(\gamma-1)\frac{\rho u^3}{2p^2} & -\frac{1}{p} + (\gamma-1)\frac{\rho u^2}{2p^2} \\ 0 & \frac{1}{p} + (\gamma-1)\frac{\rho u^2}{p^2} & -(\gamma-1)\frac{\rho u}{p^2} \\ 0 & -(\gamma-1)\frac{\rho u}{p^2} & (\gamma-1)\frac{\rho}{p^2} \end{vmatrix} \\
 &= \frac{2}{\rho}|A_{\text{Euler}}| + 4\frac{Y^2}{\rho^2} \begin{vmatrix} \frac{1}{p} + (\gamma-1)\frac{\rho u^2}{p^2} & -(\gamma-1)\frac{\rho u}{p^2} \\ -(\gamma-1)\frac{\rho u}{p^2} & (\gamma-1)\frac{\rho}{p^2} \end{vmatrix}.
 \end{aligned}$$

Combining the above equations, we arrive at $|\eta_{UU}| = \frac{2}{\rho}|A_{\text{Euler}}| > 0$. Therefore, all the leading principal minors of η_{UU} are positive and η_{UU} is positive definite. \square

Remark 2.2. It will be seen in the next section that the strict convexity of the entropy function is crucial for constructing entropy stable schemes. More specifically, it will be used to formulate the Roe-type dissipation operator in terms of the entropy variables [28], which is not available if the entropy is not strictly convex.

Remark 2.3. According to the above analysis, for any $\ell > 0$, $\hat{\eta} + \ell\rho Y^2$ is also a strictly convex entropy and the corresponding entropy flux is $\hat{\phi} + \ell\rho u Y^2$.

Remark 2.4. It is direct to verify that U is orthogonal to the fourth column of η_{UU} . Then it follows that $U^T \eta_{UU} Q_U = (0, 0, 0, 0)$ and thereby $U^T \eta_{UU} Q_U U = 0$. This relation may be helpful in the mathematical analysis of the reactive Euler equations.

2.2. 2D case. The above entropy analysis can be directly extended to the 2D reactive Euler equations

$$(2.8) \quad \partial_t U + \partial_x F(U) + \partial_y G(U) = Q(U),$$

3. ENTROPY STABLE SCHEMES IN 1D

Based on the strictly convex entropy above, in this section we construct second- and high-order finite difference entropy stable schemes within the framework of [31]. Here we consider 1D reactive Euler equations and the 2D case will be discussed in the next section.

We employ a uniform Cartesian mesh $\{x_i\}$ with mesh size $\Delta x = x_{i+1} - x_i$ and the point values are denoted as U_i . Set $x_{i+1/2} = \frac{1}{2}(x_{i+1} + x_i)$ and partition the domain into intervals $I_i = [x_{i-1/2}, x_{i+1/2}]$. A conservative finite difference method updating point values of the solution U for (2.1) has the form

$$(3.1) \quad \frac{d}{dt}U_i(t) = -\frac{1}{\Delta x}(\mathbf{F}_{i+1/2}(t) - \mathbf{F}_{i-1/2}(t)) + Q(U_i(t)),$$

where $\mathbf{F}_{i+1/2}$ is the numerical flux at the interface $x_{i+1/2}$.

Following [31], the scheme (3.1) is said to be entropy preserving¹ if it satisfies a discrete entropy equality

$$(3.2) \quad \frac{d}{dt}\eta(U_i(t)) = -\frac{1}{\Delta x}(\tilde{\phi}_{i+1/2} - \tilde{\phi}_{i-1/2}) + \eta_U(U_i(t))Q(U_i(t))$$

for some numerical entropy flux $\tilde{\phi}_{i+1/2}$ consistent with ϕ . Denote by $V := \partial_U \eta$ the entropy variable and by $\psi(U) := V(U)^T F(U) - \phi(U)$ the entropy potential. With notations

$$[[a]]_{i+1/2} = a_{i+1} - a_i, \quad \{\{a\}\}_{1/2} = \frac{1}{2}(a_{i+1} + a_i),$$

we have [31]

Theorem 3.1. *Assume that a consistent numerical flux $\tilde{\mathbf{F}}_{i+1/2}$ satisfies*

$$(3.3) \quad [[V]]_{i+1/2}^T \tilde{\mathbf{F}}_{i+1/2} = \{\{\psi\}\}_{i+1/2}.$$

Then the scheme with numerical flux $\tilde{\mathbf{F}}_{i+1/2}$ is second-order accurate and entropy preserving with the entropy flux given by

$$(3.4) \quad \tilde{\phi}_{i+1/2} = \{\{V\}\}_{i+1/2}^T \tilde{\mathbf{F}}_{i+1/2} - \{\{\psi\}\}_{i+1/2}.$$

Based on the entropy preserving numerical flux, an entropy stable scheme is built by adding appropriate dissipation terms as follows [31].

Theorem 3.2. *If the numerical flux of the scheme (3.1) is defined as*

$$(3.5) \quad \hat{\mathbf{F}}_{i+1/2} = \tilde{\mathbf{F}}_{i+1/2} - \frac{1}{2}D_{i+1/2}[[V]]_{i+1/2},$$

where $\tilde{\mathbf{F}}_{i+1/2}$ satisfies the entropy preserving condition (3.3) and $D_{i+1/2}$ is a semi-positive definite matrix, then the scheme (3.1) is first-order accurate and satisfies

$$(3.6) \quad \begin{aligned} & \frac{d}{dt}\eta(U_i(t)) + \frac{1}{\Delta x}(\hat{\phi}_{i+1/2} - \hat{\phi}_{i-1/2}) \\ &= -\frac{1}{4\Delta x}([V]_{i+1/2}^T D_{i+1/2} [V]_{i+1/2} + [V]_{i-1/2}^T D_{i-1/2} [V]_{i-1/2}) + \eta_U(U_i(t))Q(U_i(t)) \\ &\leq \eta_U(U_i(t))Q(U_i(t)) \leq 0. \end{aligned}$$

¹Here we use “entropy preserving” instead of “entropy conservative” due to the source term in (2.5) or (3.2).

Here

$$(3.7) \quad \hat{\phi}_{i+1/2} = \tilde{\phi}_{i+1/2} - \frac{1}{2} \{\{V\}\}_{i+1/2}^T D_{i+1/2} \llbracket V \rrbracket_{i+1/2}$$

and $\tilde{\phi}_{i+1/2}$ is the entropy flux associated with $\tilde{\mathbf{F}}_{i+1/2}$ in (3.4).

3.1. Two-point entropy preserving flux. In the following we derive two-point entropy preserving flux $\tilde{\mathbf{F}}_{i+1/2} = \tilde{\mathbf{F}}(U_i(t), U_{i+1}(t))$ that satisfies condition (3.3). To simplify notations, we drop the subscript $i + 1/2$ and write (3.3) as

$$(3.8) \quad \llbracket V \rrbracket^T \tilde{\mathbf{F}} = \llbracket \psi \rrbracket.$$

Following [22, 28], we introduce the logarithmic average

$$\{\{a\}\}^{\ln} = \frac{\llbracket a \rrbracket}{\llbracket \ln(a) \rrbracket}$$

and have the identities

$$\llbracket ab \rrbracket = \llbracket a \rrbracket \{\{b\}\} + \llbracket b \rrbracket \{\{a\}\}, \quad \llbracket \ln(a) \rrbracket = \llbracket a \rrbracket / \{\{a\}\}^{\ln}.$$

With these, we construct two sets of entropy preserving flux by extending those in [5, 28] for the Euler equations.

Let $V = (V^1, V^2, V^3, V^4)^T$ and $\tilde{\mathbf{F}} = (\tilde{\mathbf{F}}^1, \tilde{\mathbf{F}}^2, \tilde{\mathbf{F}}^3, \tilde{\mathbf{F}}^4)^T$. Define a set of algebraic variables [22, 28]

$$(3.9) \quad z = \begin{pmatrix} z^1 \\ z^2 \\ z^3 \\ z^4 \end{pmatrix} = \sqrt{\frac{\rho}{p}} \begin{pmatrix} 1 \\ u \\ p \\ Y \sqrt{\frac{p}{\rho}} \end{pmatrix}.$$

Following the procedure in [22, 28], we write each jump term in (3.8) in terms of jumps of the algebraic variables:

$$\begin{aligned} \llbracket V^1 \rrbracket &= \llbracket \frac{\gamma - s}{\gamma - 1} - \frac{\rho u^2}{2p} - Y^2 \rrbracket \\ &= \llbracket \frac{\gamma - \ln(\frac{z^3}{z^1}) + \gamma \ln(z^1 z^3)}{\gamma - 1} - \frac{1}{2}(z^2)^2 - (z^4)^2 \rrbracket \\ &= \frac{\gamma + 1}{\gamma - 1} \llbracket \ln(z^1) \rrbracket + \llbracket \ln(z^3) \rrbracket - \frac{1}{2} \llbracket (z^2)^2 \rrbracket - \llbracket (z^4)^2 \rrbracket \\ &= \frac{\gamma + 1}{\gamma - 1} \frac{\llbracket z^1 \rrbracket}{\{\{z^1\}\}^{\ln}} + \frac{\llbracket z^3 \rrbracket}{\{\{z^3\}\}^{\ln}} - \{\{z^2\}\} \llbracket z^2 \rrbracket - 2\{\{z^4\}\} \llbracket z^4 \rrbracket, \\ \llbracket V^2 \rrbracket &= \llbracket \frac{\rho u}{p} \rrbracket = \llbracket z^1 z^2 \rrbracket = \{\{z^2\}\} \llbracket z^1 \rrbracket + \{\{z^1\}\} \llbracket z^2 \rrbracket, \\ \llbracket V^3 \rrbracket &= \llbracket -\frac{\rho}{p} \rrbracket = \llbracket -(z^1)^2 \rrbracket = -2\{\{z^1\}\} \llbracket z^1 \rrbracket, \\ \llbracket V^4 \rrbracket &= \llbracket q \frac{\rho}{p} + 2Y \rrbracket = \llbracket -q(z^1)^2 + 2z^4 \rrbracket = -2q\{\{z^1\}\} \llbracket z^1 \rrbracket + 2\llbracket z^4 \rrbracket, \\ \llbracket \psi \rrbracket &= \llbracket z^2 z^3 \rrbracket = \{\{z^3\}\} \llbracket z^2 \rrbracket + \{\{z^2\}\} \llbracket z^3 \rrbracket, \end{aligned}$$

where the identities above have been used. Substituting these expressions into (3.8) and matching the coefficients of $\llbracket z^l \rrbracket$, $l = 1, 2, 3, 4$, we obtain a set of linear equations

with respect to $\tilde{\mathbf{F}}^l, l = 1, 2, 3, 4$:

$$\begin{aligned} & \frac{\gamma + 1}{\gamma - 1} \frac{1}{\{\{z^1\}\}^{\ln}} \tilde{\mathbf{F}}^1 + \{\{z^2\}\} \tilde{\mathbf{F}}^2 - 2\{\{z^1\}\} \tilde{\mathbf{F}}^3 - 2q\{\{z^1\}\} \tilde{\mathbf{F}}^4 = 0, \\ & - \{\{z^2\}\} \tilde{\mathbf{F}}^1 + \{\{z^1\}\} \tilde{\mathbf{F}}^2 = \{\{z^3\}\}, \\ & \frac{1}{\{\{z^3\}\}^{\ln}} \tilde{\mathbf{F}}^1 = \{\{z^2\}\}, \\ & - 2\{\{z^4\}\} \tilde{\mathbf{F}}^1 + 2\tilde{\mathbf{F}}^4 = 0. \end{aligned}$$

Then $\tilde{\mathbf{F}}^l$ can be solved out as

$$\begin{aligned} (3.10) \quad & \tilde{\mathbf{F}}^1 = \{\{z^2\}\} \{\{z^3\}\}^{\ln}, \\ & \tilde{\mathbf{F}}^2 = \frac{\{\{z^3\}\}}{\{\{z^1\}\}} + \frac{\{\{z^2\}\}}{\{\{z^1\}\}} \tilde{\mathbf{F}}^1, \\ & \tilde{\mathbf{F}}^3 = \frac{1}{2} \frac{\gamma + 1}{\gamma - 1} \frac{1}{\{\{z^1\}\} \{\{z^1\}\}^{\ln}} \tilde{\mathbf{F}}^1 + \frac{1}{2} \frac{\{\{z^2\}\}}{\{\{z^1\}\}} \tilde{\mathbf{F}}^2 + q\tilde{\mathbf{F}}^4, \\ & \tilde{\mathbf{F}}^4 = \{\{z^4\}\} \tilde{\mathbf{F}}^1. \end{aligned}$$

It is easy to see that this set of numerical flux, satisfying the entropy preserving condition (3.8), is consistent with $F(U)$ in (2.1). When $\tilde{\mathbf{F}}^4 = 0, \tilde{\mathbf{F}}^l, l = 1, 2, 3$ degenerate to those for the Euler equations in [22, 28].

Next we construct another set of entropy preserving flux by defining the algebraic variables as [5]

$$(3.11) \quad z = \begin{pmatrix} z^1 \\ z^2 \\ z^3 \\ z^4 \end{pmatrix} = \begin{pmatrix} \rho \\ u \\ \frac{p}{Y} \\ Y \end{pmatrix}.$$

With the same procedure above, we use these algebraic variables to derive the following entropy preserving flux:

$$\begin{aligned} (3.12) \quad & \tilde{\mathbf{F}}^1 = \{\{z^1\}\}^{\ln} \{\{z^2\}\}, \\ & \tilde{\mathbf{F}}^2 = \frac{\{\{z^1\}\}}{\{\{z^3\}\}} + \{\{z^2\}\} \tilde{\mathbf{F}}^1, \\ & \tilde{\mathbf{F}}^3 = \left(\frac{1}{(\gamma - 1) \{\{z^3\}\}^{\ln}} - \frac{1}{2} \{\{(z^2)^2\}\} \right) \tilde{\mathbf{F}}^1 + \{\{z^2\}\} \tilde{\mathbf{F}}^2 + q\tilde{\mathbf{F}}^4, \\ & \tilde{\mathbf{F}}^4 = \{\{z^4\}\} \tilde{\mathbf{F}}^1. \end{aligned}$$

When $\tilde{\mathbf{F}}^4 = 0, \tilde{\mathbf{F}}^l, l = 1, 2, 3$ degenerate to those for the Euler equations in [5]. Except for the preserving of entropy, an additional property of this set of flux is that it is kinetic-energy preserving (KEP) in the sense of Jameson [23], which is useful in turbulent flow simulations [30]. Specifically, note that the momentum flux $\tilde{\mathbf{F}}^2$ can be written as $\tilde{\mathbf{F}}^2 = \tilde{p} + \{\{u\}\} \tilde{\mathbf{F}}^1$, where $\tilde{p} := \frac{\{\{z^1\}\}}{\{\{z^3\}\}}$ is a consistent pressure

average. With this, we have

$$\begin{aligned} \sum_i \Delta x \frac{d(\frac{1}{2}\rho u^2)_i}{dt} &= \sum_i \Delta x \left[-\frac{1}{2}u_i^2 \frac{d\rho_i}{dt} + u_i \frac{d(\rho u)_i}{dt} \right] \\ &= \sum_i \Delta x \left[\frac{1}{2}u_i^2 (\tilde{\mathbf{F}}_{i+1/2}^1 - \tilde{\mathbf{F}}_{i-1/2}^1) - u_i (\tilde{\mathbf{F}}_{i+1/2}^2 - \tilde{\mathbf{F}}_{i-1/2}^2) \right] \\ &= \sum_i \Delta x \left[\frac{1}{2}(u_i^2 - u_{i+1}^2) \tilde{\mathbf{F}}_{i+1/2}^1 - (u_i - u_{i+1}) \tilde{\mathbf{F}}_{i+1/2}^2 \right] \\ &= \sum_i \Delta x (u_{i+1} - u_i) \tilde{p}_{i+1/2}, \end{aligned}$$

which is consistent with the kinetic energy equation $\frac{d}{dt} \int \frac{1}{2} \rho u^2 dx = \int p \frac{\partial u}{\partial x} dx$. In this sense, the flux (3.12) is KEP.

3.2. Dissipation matrix. Although Theorem 3.2 holds for any semi-positive definite $D_{j+1/2}$, a popular choice is to recast Roe’s dissipation term $R|\Lambda|R^{-1}[[U]]$ to $D[[V]]$ in terms of the entropy variable, where R is the matrix of eigenvectors of the flux Jacobian $\partial_U F$ and $|\Lambda| = \text{diag}(|\lambda_1|, |\lambda_2|, \dots, |\lambda_M|)$ with λ_i the eigenvalues of $\partial_U F$.

Denote $A = \partial_U F$ and note that $\eta_{UU}A$ is symmetric as η is strictly convex. Assume that we have already obtained a complete set of (row) eigenvectors \tilde{L} such that $A = \tilde{L}^{-1}\Lambda\tilde{L}$, where $\Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_M)$ and λ_i are the eigenvalues of A . Thanks to the strict convexity of the entropy, i.e., η_{UU} is positive definite, there exists a symmetric block diagonal matrix G that block scales the eigenvectors \tilde{L} in such a manner that (see Barth’s eigenscaling theorem in [2])

$$A = (G\tilde{L})^{-1}\Lambda(G\tilde{L}), \quad \eta_{UU} = (G\tilde{L})^T(G\tilde{L}).$$

The dimensions of the blocks of G correspond to the multiplicities of the eigenvalues λ_i . It follows from the above equation that $G = (\tilde{L}^{-T}\eta_{UU}\tilde{L}^{-1})^{\frac{1}{2}}$, which can be easily obtained without directly computing η_{UU}^{-1} since $G^2 = \tilde{L}^{-T}\eta_{UU}\tilde{L}^{-1}$ is block diagonal.

With the above \tilde{L} and G , we define $R = (G\tilde{L})^{-1} = \tilde{L}^{-1}G^{-1}$ and then

$$(3.13) \quad A = R\Lambda R^{-1}, \quad \eta_{UU} = R^{-T}R^{-1}.$$

Thus we have

$$R|\Lambda|R^{-1}dU = R|\Lambda|R^{-1}\eta_{UU}^{-1}dV = R|\Lambda|R^T dV$$

and Roe’s dissipation term in terms of the entropy variable is

$$D[[V]], \quad D = R|\Lambda|R^T.$$

If $|\Lambda|$ is replaced by $\max\{|\lambda_1|, |\lambda_2|, \dots, |\lambda_M|\}I$ with I the unit matrix, then we obtain the Rusanov-type dissipation term

$$D[[V]], \quad D = \max\{|\lambda_1|, |\lambda_2|, \dots, |\lambda_M|\}RR^T = \max\{|\lambda_1|, |\lambda_2|, \dots, |\lambda_M|\}\eta_{UU}^{-1}.$$

The key step of constructing the above dissipation terms is to compute the eigenvector matrix R satisfying (3.13). In the following we derive such R for the reactive Euler equations (2.1). Let $H = E + \frac{p}{\rho} = \frac{\gamma}{\gamma-1}\frac{p}{\rho} + \frac{1}{2}u^2 + qY$ and $c = \sqrt{\gamma\frac{p}{\rho}}$.

The flux Jacobian $A = \partial_U \mathbf{F}$ of the reactive Euler equations (2.1) can be computed as

$$A = \begin{pmatrix} 0 & 1 & 0 & 0 \\ \frac{\gamma-3}{2}u^2 & (3-\gamma)u & \gamma-1 & -(\gamma-1)q \\ \frac{\gamma-1}{2}u^3 - Hu & H - (\gamma-1)u^2 & \gamma u & -(\gamma-1)qu \\ -uY & Y & 0 & u \end{pmatrix},$$

the eigenvalues of which are $u, u, u + c$ and $u - c$. Based on the widely used eigen-system (see e.g. [24]) for the Euler equations, we obtain the following left and right eigenvectors of A :

$$(3.14) \quad \begin{aligned} \tilde{L} &= \begin{pmatrix} 1 - \frac{\gamma-1}{2} \frac{u^2}{c^2} & (\gamma-1) \frac{u}{c^2} & -\frac{\gamma-1}{c^2} & q \frac{\gamma-1}{c^2} \\ -\frac{\gamma-1}{2} \frac{u^2}{c^2} Y & (\gamma-1) \frac{u}{c^2} Y & -\frac{\gamma-1}{c^2} Y & 1 + q \frac{\gamma-1}{c^2} \\ \frac{\gamma-1}{4} \frac{u^2}{c^2} - \frac{1}{2} \frac{u}{c} & -\frac{\gamma-1}{2} \frac{u}{c^2} + \frac{1}{2c} & \frac{\gamma-1}{2c^2} & -q \frac{\gamma-1}{2c^2} \\ \frac{\gamma-1}{4} \frac{u^2}{c^2} + \frac{1}{2} \frac{u}{c} & -\frac{\gamma-1}{2} \frac{u}{c^2} - \frac{1}{2c} & \frac{\gamma-1}{2c^2} & -q \frac{\gamma-1}{2c^2} \end{pmatrix}, \\ \tilde{R} = \tilde{L}^{-1} &= \begin{pmatrix} 1 & 0 & 1 & 1 \\ u & 0 & u+c & u-c \\ \frac{1}{2}u^2 & q & H+uc & H-uc \\ 0 & 1 & Y & Y \end{pmatrix}, \end{aligned}$$

which satisfy $\tilde{L}\tilde{A}\tilde{R} = \text{diag}(u, u, u + c, u - c)$. It is direct to compute that

$$G^2 = \tilde{L}^{-T} \eta_{UU} \tilde{L}^{-1} = \text{diag}(C, \frac{2\gamma}{\rho}, \frac{2\gamma}{\rho}), \quad C = \begin{pmatrix} \frac{\gamma}{\gamma-1} \frac{1}{\rho} + 2 \frac{Y^2}{\rho} & -2 \frac{Y}{\rho} \\ -2 \frac{Y}{\rho} & \frac{2}{\rho} \end{pmatrix}.$$

The 2×2 matrix C can be diagonalized as $C = M \text{diag}(\zeta_1, \zeta_2) M^T$, where $\zeta_1, \zeta_2 = \frac{1}{\rho} (\frac{3\gamma-2}{2\gamma-2} + Y^2) \pm \frac{1}{\rho} \sqrt{(\frac{3\gamma-2}{2\gamma-2} + Y^2)^2 - \frac{2\gamma}{\gamma-1}}$ and M is a unitary matrix given by

$$M = \begin{pmatrix} \frac{\zeta_1 \rho - 2}{\sqrt{(\zeta_1 \rho - 2)^2 + 4Y^2}} & \frac{\zeta_2 \rho - 2}{\sqrt{(\zeta_2 \rho - 2)^2 + 4Y^2}} \\ \frac{2Y}{\sqrt{(\zeta_1 \rho - 2)^2 + 4Y^2}} & \frac{2Y}{\sqrt{(\zeta_2 \rho - 2)^2 + 4Y^2}} \end{pmatrix}.$$

Then we have

$$C^{-\frac{1}{2}} := \begin{pmatrix} g_1 & g_2 \\ g_2 & g_3 \end{pmatrix} = M \text{diag}(\frac{1}{\sqrt{\zeta_1}}, \frac{1}{\sqrt{\zeta_2}}) M^T$$

and

$$R = \tilde{R}G^{-1} = \begin{pmatrix} g_1 & g_2 & \sqrt{\frac{\rho}{2\gamma}} & \sqrt{\frac{\rho}{2\gamma}} \\ ug_1 & ug_2 & (u+c)\sqrt{\frac{\rho}{2\gamma}} & (u-c)\sqrt{\frac{\rho}{2\gamma}} \\ \frac{1}{2}u^2g_1 + qg_2 & \frac{1}{2}u^2g_2 + qg_3 & (H+uc)\sqrt{\frac{\rho}{2\gamma}} & (H-uc)\sqrt{\frac{\rho}{2\gamma}} \\ g_2 & g_3 & Y\sqrt{\frac{\rho}{2\gamma}} & Y\sqrt{\frac{\rho}{2\gamma}} \end{pmatrix}, \quad \eta_{UU}^{-1} = RR^T,$$

with which the dissipation matrix D and the dissipation term can be computed.

3.3. High-order entropy stable schemes. The semi-discrete entropy preserving scheme with the two-point flux $\tilde{\mathbf{F}}_{i+1/2}$ is only second-order accurate, while the entropy stable scheme with flux $\hat{\mathbf{F}}_{i+1/2}$ is only first-order accurate due to the dissipation term. In this subsection high-order entropy preserving/stable fluxes are constructed based on the two-point fluxes following [16, 25].

3.3.1. *High-order entropy preserving flux.* The high-order entropy preserving flux is defined as a linear combination of two-point fluxes [25]:

$$(3.15) \quad \tilde{\mathbf{F}}_{i+1/2}^{2k} = \sum_{r=1}^k \alpha_{k,r} \sum_{s=0}^{r-1} \tilde{\mathbf{F}}(U_{i-s}, U_{i-s+r})$$

with constants $\alpha_{k,r}$ satisfying

$$(3.16) \quad \sum_{r=1}^k r\alpha_{k,r} = 1, \quad \sum_{r=1}^k r^{2s-1}\alpha_{k,r} = 0, \quad s = 2, \dots, k.$$

For example, the fourth- and sixth-order fluxes are

$$\begin{aligned} \tilde{\mathbf{F}}_{i+1/2}^4 &= \frac{4}{3}\tilde{\mathbf{F}}(U_i, U_{i+1}) - \frac{1}{6}(\tilde{\mathbf{F}}(U_{i-1}, U_{i+1}) + \tilde{\mathbf{F}}(U_i, U_{i+2})), \\ \tilde{\mathbf{F}}_{i+1/2}^6 &= \frac{3}{2}\tilde{\mathbf{F}}(U_i, U_{i+1}) - \frac{3}{10}(\tilde{\mathbf{F}}(U_{i-1}, U_{i+1}) + \tilde{\mathbf{F}}(U_i, U_{i+2})) \\ &\quad + \frac{1}{30}(\tilde{\mathbf{F}}(U_{i-2}, U_{i+1}) + \tilde{\mathbf{F}}(U_{i-1}, U_{i+2}) + \tilde{\mathbf{F}}(U_i, U_{i+3})). \end{aligned}$$

It is direct to see the consistence of the flux (3.15) by using the first condition in (3.16). Additionally, under the conditions (3.16), the scheme with flux (3.15) has $2k$ -th order accuracy [25].

We show the entropy preserving property by computing

$$\begin{aligned} V_i^T(\tilde{\mathbf{F}}_{i+1/2}^{2k} - \tilde{\mathbf{F}}_{i-1/2}^{2k}) &= \sum_{r=1}^k \alpha_{k,r} V_i^T (\tilde{\mathbf{F}}(U_i, U_{i+r}) - \tilde{\mathbf{F}}(U_{i-r}, U_i)) \\ &= \sum_{r=1}^k \alpha_{k,r} \left[\left(\frac{V_i + V_{i+r}}{2} - \frac{V_{i+r} - V_i}{2} \right)^T \tilde{\mathbf{F}}(U_i, U_{i+r}) - \left(\frac{V_i + V_{i-r}}{2} + \frac{V_i - V_{i-r}}{2} \right)^T \tilde{\mathbf{F}}(U_{i-r}, U_i) \right] \\ &= \sum_{r=1}^k \alpha_{k,r} \left[\frac{V_i + V_{i+r}}{2} \cdot \tilde{\mathbf{F}}(U_i, U_{i+r}) - \frac{1}{2} \{\psi\}_{i+r,i} - \frac{V_i + V_{i-r}}{2} \cdot \tilde{\mathbf{F}}(U_{i-r}, U_i) - \frac{1}{2} \{\psi\}_{i,i-r} \right] \\ &= \sum_{r=1}^k \alpha_{k,r} \left[\left(\frac{V_i + V_{i+r}}{2} \cdot \tilde{\mathbf{F}}(U_i, U_{i+r}) - \{\psi\}_{i+r,i} \right) - \left(\frac{V_i + V_{i-r}}{2} \cdot \tilde{\mathbf{F}}(U_{i-r}, U_i) - \{\psi\}_{i,i-r} \right) \right]. \end{aligned}$$

Thus the discrete entropy flux is

$$(3.17) \quad \tilde{\phi}_{i+1/2}^{2k} = \sum_{r=1}^k \alpha_{k,r} \left(\frac{V_i + V_{i+r}}{2} \cdot \tilde{\mathbf{F}}(U_i, U_{i+r}) - \{\psi\}_{i+r,i} \right)$$

and the scheme is entropy preserving with the discrete entropy equality given by

$$\frac{d}{dt} \eta(U_i(t)) = -\frac{1}{\Delta x} (\tilde{\phi}_{i+1/2}^{2k} - \tilde{\phi}_{i-1/2}^{2k}) + \eta_U(U_i(t))Q(U_i(t)).$$

3.3.2. *High-order entropy stable flux.* With the high-order entropy preserving flux above, we follow [16] to construct high-order entropy stable fluxes by adding high-order dissipation terms based on ENO and WENO reconstructions. The high-order entropy stable flux based on ENO is defined as [16]

$$(3.18) \quad \hat{\mathbf{F}}_{i+1/2} = \tilde{\mathbf{F}}_{i+1/2}^{2k} - \frac{1}{2} \mathbf{R}_{i+1/2} |\Lambda_{i+1/2}| \ll \omega \gg_{i+1/2}^{ENO}$$

with $\tilde{\mathbf{F}}_{i+1/2}^{2k}$ the $2k$ -th order entropy preserving flux in (3.15) and $\ll \omega \gg_{i+1/2}^{ENO} := \omega_{i+1/2}^+ - \omega_{i+1/2}^-$. Here $\omega_{i+1/2}^+$ and $\omega_{i+1/2}^-$ are the right and left limiting values of the scaled entropy variables $\omega := \mathbf{R}_{i+1/2}^T V$ at the interface $x_{i+1/2}$, respectively, and

they are obtained by $2k$ -th order ENO reconstruction. It is shown in [17] that the ENO reconstruction satisfies the sign property

$$(3.19) \quad \text{sign}(\ll \omega \gg_{i+1/2}^{ENO}) = \text{sign}([\omega]_{i+1/2}).$$

With this, the entropy stable property of the ENO based flux (3.18) can be shown by computing

$$\begin{aligned} & V_i^T (\hat{\mathbf{F}}_{i+1/2} - \hat{\mathbf{F}}_{i-1/2}) \\ &= V_i^T (\tilde{\mathbf{F}}_{i+1/2}^{2k} - \tilde{\mathbf{F}}_{i-1/2}^{2k}) \\ & - \frac{1}{2} V_i^T R_{i+1/2} |\Lambda_{i+1/2}| \ll \omega \gg_{i+1/2}^{ENO} + \frac{1}{2} V_i^T R_{i-1/2} |\Lambda_{i-1/2}| \ll \omega \gg_{i-1/2}^{ENO} \\ &= \tilde{\phi}_{i+1/2}^{2k} - \tilde{\phi}_{i-1/2}^{2k} - \frac{1}{2} (\{V\}_{i+1/2} - \frac{1}{2} [V]_{i+1/2})^T R_{i+1/2} |\Lambda_{i+1/2}| \ll \omega \gg_{i+1/2}^{ENO} \\ & + \frac{1}{2} (\{V\}_{i-1/2} + \frac{1}{2} [V]_{i+1/2})^T R_{i-1/2} |\Lambda_{i-1/2}| \ll \omega \gg_{i-1/2}^{ENO} \\ &= \left(\tilde{\phi}_{i+1/2}^{2k} - \frac{1}{2} \{V\}_{i+1/2}^T R_{i+1/2} |\Lambda_{i+1/2}| \ll \omega \gg_{i+1/2}^{ENO} \right) \\ & - \left(\tilde{\phi}_{i-1/2}^{2k} - \frac{1}{2} \{V\}_{i-1/2}^T R_{i-1/2} |\Lambda_{i-1/2}| \ll \omega \gg_{i-1/2}^{ENO} \right) \\ & + \frac{1}{4} \left([V]_{i+1/2}^T R_{i+1/2} |\Lambda_{i+1/2}| \ll \omega \gg_{i+1/2}^{ENO} \right. \\ & \quad \left. + \{V\}_{i-1/2}^T R_{i-1/2} |\Lambda_{i-1/2}| \ll \omega \gg_{i-1/2}^{ENO} \right) \\ &= \hat{\phi}_{i+1/2}^{ENO} - \hat{\phi}_{i-1/2}^{ENO} + \frac{1}{4} \left([\omega]_{i+1/2}^T |\Lambda_{i+1/2}| \ll \omega \gg_{i+1/2}^{ENO} \right. \\ & \quad \left. + [\omega]_{i-1/2}^T |\Lambda_{i-1/2}| \ll \omega \gg_{i-1/2}^{ENO} \right), \end{aligned}$$

where

$$\hat{\phi}_{i+1/2}^{ENO} = \tilde{\phi}_{i+1/2}^{2k} - \frac{1}{2} \{V\}_{i+1/2}^T R_{i+1/2} |\Lambda_{i+1/2}| \ll \omega \gg_{i+1/2}^{ENO}.$$

Thus we arrive at

$$\begin{aligned} & \frac{d\eta(U_i)}{dt} + \frac{\hat{\phi}_{i+1/2}^{ENO} - \hat{\phi}_{i-1/2}^{ENO}}{\Delta x} \\ &= -\frac{1}{4\Delta x} \left([\omega]_{i+1/2}^T |\Lambda_{i+1/2}| \ll \omega \gg_{i+1/2}^{ENO} + [\omega]_{i-1/2}^T |\Lambda_{i-1/2}| \ll \omega \gg_{i-1/2}^{ENO} \right) \\ & \quad + V_i^T Q(U_i(t)) \\ & \leq V_i^T Q(U_i(t)) \leq 0, \end{aligned}$$

where $-\frac{1}{4\Delta x} \left([\omega]_{i+1/2}^T |\Lambda_{i+1/2}| \ll \omega \gg_{i+1/2}^{ENO} + [\omega]_{i-1/2}^T |\Lambda_{i-1/2}| \ll \omega \gg_{i-1/2}^{ENO} \right) \leq 0$ thanks to the sign property (3.19). This indicates that the flux (3.18) guarantees the entropy stable property.

The WENO based high-order entropy stable flux is defined as [3]

$$(3.20) \quad \hat{\mathbf{F}}_{i+1/2} = \tilde{\mathbf{F}}_{i+1/2}^{2k} - \frac{1}{2} \mathbf{R}_{i+1/2} |\Lambda_{i+1/2}| \ll \omega \gg_{i+1/2}^{WENO},$$

where the l -th component of the $\ll \omega \gg_{i+1/2}^{WENO}$ is given by

$$(3.21) \quad \begin{aligned} \ll \omega_l \gg_{i+1/2}^{WENO} &= \theta_{l,i+1/2} (\omega_{l,i+1/2}^+ - \omega_{l,i+1/2}^-), \\ \theta_{l,i+1/2} &:= \begin{cases} 1, & (\omega_{l,i+1/2}^+ - \omega_{l,i+1/2}^-) \llbracket \omega_l \rrbracket_{i+1/2} > 0, \\ 0, & \text{otherwise.} \end{cases} \end{aligned}$$

Here $\omega_{l,i+1/2}^+$ and $\omega_{l,i+1/2}^-$ denote, respectively, the right and left limiting values of ω_l at the interface $x_{i+1/2}$ by using the $(2k - 1)$ -th order WENO reconstruction. Though the standard WENO reconstruction may not satisfy the sign property, the switch operator $\theta_{l,i+1/2}$ ensures that

$$(3.22) \quad \text{sign}(\ll \omega \gg_{l,i+1/2}^{WENO}) = \text{sign}(\llbracket \omega \rrbracket_{l,i+1/2}).$$

With this relation, the entropy stable property can be proved in the same way as for the ENO based flux.

4. ENTROPY STABLE SCHEMES IN 2D

In this section, we construct entropy preserving/stable schemes for the 2D reactive Euler equations (2.8). The construction is similar to the 1D case and the key is to derive the two-point entropy preserving flux and the matrix \mathbf{R} in the dissipation term.

4.1. Two-point entropy preserving flux. As for the 1D case, here we propose two sets of entropy preserving fluxes satisfying

$$(4.1) \quad \llbracket V \rrbracket_{i+1/2,j}^T \tilde{\mathbf{F}}_{i+1/2,j} = \llbracket \psi_1 \rrbracket_{i+1/2,j}, \quad \llbracket V \rrbracket_{i,j+1/2}^T \tilde{\mathbf{G}}_{i,j+1/2} = \llbracket \psi_2 \rrbracket_{i,j+1/2},$$

where $\tilde{\mathbf{F}}_{i+1/2,j}$ and $\tilde{\mathbf{G}}_{i,j+1/2}$ are numerical fluxes consistent with $F(U)$ and $G(U)$, respectively. Define algebraic variables

$$(4.2) \quad z = \begin{pmatrix} z^1 \\ z^2 \\ z^3 \\ z^4 \\ z^5 \end{pmatrix} = \sqrt{\frac{\rho}{p}} \begin{pmatrix} 1 \\ u \\ v \\ p \\ Y \end{pmatrix}.$$

By writing each jump term in (4.1) in terms of jumps of the algebraic variables and matching the coefficients, we obtain

$$\begin{aligned}
 (4.3) \quad & \mathbf{F}_{i+1/2,j}^1 = \{\{z^2\}\}_{i+1/2,j} \{\{z^4\}\}_{i+1/2,j}^{\ln}, \\
 & \tilde{\mathbf{F}}_{i+1/2,j}^2 = \frac{\{\{z^4\}\}_{i+1/2,j}}{\{\{z^1\}\}_{i+1/2,j}} + \frac{\{\{z^2\}\}_{i+1/2,j}}{\{\{z^1\}\}_{i+1/2,j}} \tilde{\mathbf{F}}_{i+1/2,j}^1, \\
 & \tilde{\mathbf{F}}_{i+1/2,j}^3 = \frac{\{\{z^3\}\}_{i+1/2,j}}{\{\{z^1\}\}_{i+1/2,j}} \tilde{\mathbf{F}}_{i+1/2,j}^1, \\
 & \tilde{\mathbf{F}}_{i+1/2,j}^4 = \frac{1}{2} \frac{\gamma + 1}{\gamma - 1} \frac{1}{\{\{z^1\}\}_{i+1/2,j} \{\{z^1\}\}_{i+1/2,j}^{\ln}} \tilde{\mathbf{F}}_{i+1/2,j}^1 + \frac{1}{2} \frac{\{\{z^2\}\}_{i+1/2,j}}{\{\{z^1\}\}_{i+1/2,j}} \tilde{\mathbf{F}}_{i+1/2,j}^2 \\
 & \quad + \frac{1}{2} \frac{\{\{z^3\}\}_{i+1/2,j}}{\{\{z^1\}\}_{i+1/2,j}} \tilde{\mathbf{F}}_{i+1/2,j}^3 + q \tilde{\mathbf{F}}_{i+1/2,j}^5, \\
 & \tilde{\mathbf{F}}_{i+1/2,j}^5 = \{\{z^5\}\}_{i+1/2,j} \tilde{\mathbf{F}}_{i+1/2,j}^1, \\
 & \tilde{\mathbf{G}}_{i,j+1/2}^1 = \{\{z^3\}\}_{i,j+1/2} \{\{z^4\}\}_{i,j+1/2}^{\ln}, \\
 & \tilde{\mathbf{G}}_{i,j+1/2}^2 = \frac{\{\{z^2\}\}_{i,j+1/2}}{\{\{z^1\}\}_{i,j+1/2}} \tilde{\mathbf{G}}_{i,j+1/2}^1, \\
 & \tilde{\mathbf{G}}_{i,j+1/2}^3 = \frac{\{\{z^4\}\}_{i,j+1/2}}{\{\{z^1\}\}_{i,j+1/2}} + \frac{\{\{z^3\}\}_{i,j+1/2}}{\{\{z^1\}\}_{i,j+1/2}} \tilde{\mathbf{G}}_{i,j+1/2}^1, \\
 & \tilde{\mathbf{G}}_{i,j+1/2}^4 = \frac{1}{2} \frac{\gamma + 1}{\gamma - 1} \frac{1}{\{\{z^1\}\}_{i,j+1/2} \{\{z^1\}\}_{i,j+1/2}^{\ln}} \tilde{\mathbf{G}}_{i,j+1/2}^1 + \frac{1}{2} \frac{\{\{z^2\}\}_{i,j+1/2}}{\{\{z^1\}\}_{i,j+1/2}} \tilde{\mathbf{G}}_{i,j+1/2}^2 \\
 & \quad + \frac{1}{2} \frac{\{\{z^3\}\}_{i,j+1/2}}{\{\{z^1\}\}_{i,j+1/2}} \tilde{\mathbf{G}}_{i,j+1/2}^3 + q \tilde{\mathbf{G}}_{i,j+1/2}^5, \\
 & \tilde{\mathbf{G}}_{i,j+1/2}^5 = \{\{z^5\}\}_{i,j+1/2} \tilde{\mathbf{G}}_{i,j+1/2}^1.
 \end{aligned}$$

On the other hand, if the algebraic variables are taken as

$$(4.4) \quad z = \begin{pmatrix} z^1 \\ z^2 \\ z^3 \\ z^4 \\ z^5 \end{pmatrix} = \begin{pmatrix} \rho \\ u \\ v \\ \frac{p}{p} \\ Y \end{pmatrix},$$

then the corresponding entropy preserving flux can be derived as

$$\begin{aligned}
 \tilde{\mathbf{F}}_{i+1/2,j}^1 &= \{\{z^1\}\}_{i+1/2,j}^{\ln} \{\{z^2\}\}_{i+1/2,j}, \\
 \tilde{\mathbf{F}}_{i+1/2,j}^2 &= \frac{\{\{z^1\}\}_{i+1/2,j}}{\{\{z^4\}\}_{i+1/2,j}} + \{\{z^2\}\}_{i+1/2,j} \tilde{\mathbf{F}}_{i+1/2,j}^1, \\
 \tilde{\mathbf{F}}_{i+1/2,j}^3 &= \{\{z^3\}\}_{i+1/2,j} \tilde{\mathbf{F}}_{i+1/2,j}^1, \\
 \tilde{\mathbf{F}}_{i+1/2,j}^4 &= \left(\frac{1}{(\gamma - 1)\{\{z^4\}\}_{i+1/2,j}^{\ln}} - \frac{1}{2} \{\{(z^2)^2 + (z^3)^2\}\}_{i+1/2,j} \right) \tilde{\mathbf{F}}_{i+1/2,j}^1 \\
 &\quad + \{\{z^2\}\}_{i+1/2,j} \tilde{\mathbf{F}}_{i+1/2,j}^2 + \{\{z^3\}\}_{i+1/2,j} \tilde{\mathbf{F}}_{i+1/2,j}^3 + q \tilde{\mathbf{F}}_{i+1/2,j}^5, \\
 \tilde{\mathbf{F}}_{i+1/2,j}^5 &= \{\{z^5\}\}_{i+1/2,j} \tilde{\mathbf{F}}_{i+1/2,j}^1, \\
 \tilde{\mathbf{G}}_{i,j+1/2}^1 &= \{\{z^1\}\}_{i,j+1/2}^{\ln} \{\{z^3\}\}_{i,j+1/2}, \\
 \tilde{\mathbf{G}}_{i,j+1/2}^2 &= \{\{z^2\}\}_{i,j+1/2} \tilde{\mathbf{G}}_{i,j+1/2}^1, \\
 \tilde{\mathbf{G}}_{i,j+1/2}^3 &= \frac{\{\{z^1\}\}_{i,j+1/2}}{\{\{z^4\}\}_{i,j+1/2}} + \{\{z^3\}\}_{i,j+1/2} \tilde{\mathbf{G}}_{i,j+1/2}^1, \\
 \tilde{\mathbf{G}}_{i,j+1/2}^4 &= \left(\frac{1}{(\gamma - 1)\{\{z^4\}\}_{i,j+1/2}^{\ln}} - \frac{1}{2} \{\{(z^2)^2 + (z^3)^2\}\}_{i,j+1/2} \right) \tilde{\mathbf{G}}_{i,j+1/2}^1 \\
 &\quad + \{\{z^2\}\}_{i,j+1/2} \tilde{\mathbf{G}}_{i,j+1/2}^2 + \{\{z^3\}\}_{i,j+1/2} \tilde{\mathbf{G}}_{i,j+1/2}^3 + q \tilde{\mathbf{G}}_{i,j+1/2}^5, \\
 \tilde{\mathbf{G}}_{i,j+1/2}^5 &= \{\{z^5\}\}_{i,j+1/2} \tilde{\mathbf{G}}_{i,j+1/2}^1.
 \end{aligned}
 \tag{4.5}$$

Similar to the 1D case, this set of fluxes preserves both entropy and kinetic energy.

4.2. Dissipation matrix. Let $H = E + \frac{p}{\rho} = \frac{\gamma}{\gamma-1} \frac{p}{\rho} + \frac{1}{2}(u^2 + v^2) + qY$ and $c = \sqrt{\gamma \frac{p}{\rho}}$. The flux Jacobian $\mathbf{A} = \partial_U F$ of the 2D reactive Euler equations (2.8) can be computed as

$$\mathbf{A} = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ \frac{\gamma-3}{2}u^2 + \frac{\gamma-1}{2}v^2 & (3-\gamma)u & (1-\gamma)v & \gamma-1 & -(\gamma-1)q \\ -uv & v & u & 0 & 0 \\ \frac{\gamma-1}{2}(u^2 + v^2)u - Hu & H - (\gamma-1)u^2 & -(\gamma-1)uv & \gamma u & -(\gamma-1)qu \\ -uY & Y & 0 & 0 & u \end{pmatrix},$$

the eigenvalues of which are $u, u, u, u + c$ and $u - c$. The left and right eigenvectors of A can be computed as

$$(4.6) \quad \tilde{L}_A = \begin{pmatrix} 1 - \frac{\gamma-1}{2} \frac{u^2+v^2}{c^2} & (\gamma-1) \frac{u}{c^2} & (\gamma-1) \frac{v}{c^2} & -\frac{\gamma-1}{c^2} & q \frac{\gamma-1}{c^2} \\ -v & 0 & 1 & 0 & 0 \\ -\frac{\gamma-1}{2} \frac{u^2+v^2}{c^2} Y & (\gamma-1) \frac{u}{c^2} Y & (\gamma-1) \frac{v}{c^2} Y & -\frac{\gamma-1}{c^2} Y & 1 + q \frac{\gamma-1}{c^2} Y \\ \frac{\gamma-1}{4} \frac{u^2+v^2}{c^2} - \frac{1}{2} \frac{u}{c} & -\frac{\gamma-1}{2} \frac{u}{c^2} + \frac{1}{2c} & -\frac{\gamma-1}{2} \frac{v}{c^2} & \frac{\gamma-1}{2c^2} & -q \frac{\gamma-1}{2c^2} \\ \frac{\gamma-1}{4} \frac{u^2+v^2}{c^2} + \frac{1}{2} \frac{u}{c} & -\frac{\gamma-1}{2} \frac{u}{c^2} - \frac{1}{2c} & -\frac{\gamma-1}{2} \frac{v}{c^2} & \frac{\gamma-1}{2c^2} & -q \frac{\gamma-1}{2c^2} \end{pmatrix},$$

$$\tilde{R}_A = \tilde{L}_A^{-1} = \begin{pmatrix} 1 & 0 & 0 & 1 & 1 \\ u & 0 & 0 & u+c & u-c \\ v & 1 & 0 & v & v \\ \frac{1}{2}(u^2+v^2) & v & q & H+uc & H-uc \\ 0 & 0 & 1 & Y & Y \end{pmatrix},$$

which satisfy $\tilde{L}_A A \tilde{R}_A = \text{diag}(u, u, u, u + c, u - c)$.

The flux Jacobian $B = \partial_U G$ is

$$B = \begin{pmatrix} 0 & 0 & 1 & 0 & 0 \\ -uv & v & u & 0 & 0 \\ \frac{\gamma-3}{2} v^2 + \frac{\gamma-1}{2} u^2 & (1-\gamma)u & (3-\gamma)v & \gamma-1 & -(\gamma-1)q \\ \frac{\gamma-1}{2}(u^2+v^2)v - Hv & -(\gamma-1)uv & H - (\gamma-1)v^2 & \gamma v & -(\gamma-1)qv \\ -vY & 0 & Y & 0 & v \end{pmatrix}.$$

It can be diagonalized as

$$\tilde{L}_B B \tilde{R}_B = \text{diag}(v, v, v, v + c, v - c)$$

with

$$(4.7) \quad \tilde{L}_B = \begin{pmatrix} 1 - \frac{\gamma-1}{2} \frac{u^2+v^2}{c^2} & (\gamma-1) \frac{u}{c^2} & (\gamma-1) \frac{v}{c^2} & -\frac{\gamma-1}{c^2} & q \frac{\gamma-1}{c^2} \\ -u & 1 & 0 & 0 & 0 \\ -\frac{\gamma-1}{2} \frac{u^2+v^2}{c^2} Y & (\gamma-1) \frac{u}{c^2} Y & (\gamma-1) \frac{v}{c^2} Y & -\frac{\gamma-1}{c^2} Y & 1 + q \frac{\gamma-1}{c^2} Y \\ \frac{\gamma-1}{4} \frac{u^2+v^2}{c^2} - \frac{1}{2} \frac{v}{c} & -\frac{\gamma-1}{2} \frac{u}{c^2} & -\frac{\gamma-1}{2} \frac{v}{c^2} + \frac{1}{2c} & \frac{\gamma-1}{2c^2} & -q \frac{\gamma-1}{2c^2} \\ \frac{\gamma-1}{4} \frac{u^2+v^2}{c^2} + \frac{1}{2} \frac{v}{c} & -\frac{\gamma-1}{2} \frac{u}{c^2} & -\frac{\gamma-1}{2} \frac{v}{c^2} - \frac{1}{2c} & \frac{\gamma-1}{2c^2} & -q \frac{\gamma-1}{2c^2} \end{pmatrix},$$

$$\tilde{R}_B = \tilde{L}_B^{-1} = \begin{pmatrix} 1 & 0 & 0 & 1 & 1 \\ u & 1 & 0 & u & u \\ v & 0 & 0 & v+c & v-c \\ \frac{1}{2}(u^2+v^2) & u & q & H+vc & H-vc \\ 0 & 0 & 1 & Y & Y \end{pmatrix}.$$

It is direct to compute that

$$G^2 := \tilde{L}_A^{-T} \eta_{UU} \tilde{L}_A^{-1} = \tilde{L}_B^{-T} \eta_{UU} \tilde{L}_B^{-1} = \text{diag}(C, \frac{2\gamma}{\rho}, \frac{2\gamma}{\rho}),$$

$$C = \begin{pmatrix} \frac{\gamma}{\gamma-1} \frac{1}{\rho} + 2\frac{Y^2}{\rho} & 0 & -2\frac{Y}{\rho} \\ 0 & \frac{1}{p} & 0 \\ -2\frac{Y}{\rho} & 0 & \frac{2}{\rho} \end{pmatrix}.$$

The 3×3 matrix C can be diagonalized as $C = M \text{diag}(\zeta_1, \zeta_2, \frac{1}{p})M^T$, where $\zeta_1, \zeta_2 = \frac{1}{\rho}(\frac{3\gamma-2}{2\gamma-2} + Y^2) \pm \frac{1}{\rho}\sqrt{(\frac{3\gamma-2}{2\gamma-2} + Y^2)^2 - \frac{2\gamma}{\gamma-1}}$ and M is a unitary matrix given by

$$M = \begin{pmatrix} \frac{\zeta_1 \rho - 2}{\sqrt{(\zeta_1 \rho - 2)^2 + 4Y^2}} & \frac{\zeta_2 \rho - 2}{\sqrt{(\zeta_2 \rho - 2)^2 + 4Y^2}} & 0 \\ 0 & 0 & 1 \\ \frac{2Y}{\sqrt{(\zeta_1 \rho - 2)^2 + 4Y^2}} & \frac{2Y}{\sqrt{(\zeta_2 \rho - 2)^2 + 4Y^2}} & 0 \end{pmatrix}.$$

Then we have

$$C^{-\frac{1}{2}} = M \text{diag}(\frac{1}{\sqrt{\zeta_1}}, \frac{1}{\sqrt{\zeta_2}}, \sqrt{p})M^T := \begin{pmatrix} g_1 & 0 & g_2 \\ 0 & \sqrt{p} & 0 \\ g_2 & 0 & g_3 \end{pmatrix}$$

and

$$R_A = \tilde{R}_A G^{-1} = \begin{pmatrix} g_1 & 0 & g_2 & \sqrt{\frac{\rho}{2\gamma}} & \sqrt{\frac{\rho}{2\gamma}} \\ ug_1 & 0 & ug_2 & (u+c)\sqrt{\frac{\rho}{2\gamma}} & (u-c)\sqrt{\frac{\rho}{2\gamma}} \\ vg_1 & \sqrt{p} & vg_2 & v\sqrt{\frac{\rho}{2\gamma}} & v\sqrt{\frac{\rho}{2\gamma}} \\ \frac{1}{2}(u^2+v^2)g_1+qg_2 & v\sqrt{p} & \frac{1}{2}(u^2+v^2)g_2+qg_3 & (H+uc)\sqrt{\frac{\rho}{2\gamma}} & (H-uc)\sqrt{\frac{\rho}{2\gamma}} \\ g_2 & 0 & g_3 & Y\sqrt{\frac{\rho}{2\gamma}} & Y\sqrt{\frac{\rho}{2\gamma}} \end{pmatrix},$$

$$R_B = \tilde{R}_B G^{-1} = \begin{pmatrix} g_1 & 0 & g_2 & \sqrt{\frac{\rho}{2\gamma}} & \sqrt{\frac{\rho}{2\gamma}} \\ ug_1 & \sqrt{p} & ug_2 & u\sqrt{\frac{\rho}{2\gamma}} & u\sqrt{\frac{\rho}{2\gamma}} \\ vg_1 & 0 & vg_2 & (v+c)\sqrt{\frac{\rho}{2\gamma}} & (v-c)\sqrt{\frac{\rho}{2\gamma}} \\ \frac{1}{2}(u^2+v^2)g_1+qg_2 & u\sqrt{p} & \frac{1}{2}(u^2+v^2)g_2+qg_3 & (H+vc)\sqrt{\frac{\rho}{2\gamma}} & (H-vc)\sqrt{\frac{\rho}{2\gamma}} \\ g_2 & 0 & g_3 & Y\sqrt{\frac{\rho}{2\gamma}} & Y\sqrt{\frac{\rho}{2\gamma}} \end{pmatrix},$$

which satisfy $R_A R_A^T = R_B R_B^T = \eta_{UU}^{-1}$. With R_A and R_B , the dissipation matrices can be computed as for the 1D case (see subsection 3.2).

Having the two-point entropy preserving fluxes and dissipation matrices, we can directly construct high-order entropy preserving/stable schemes in two dimensions. The construction is the same as for the 1D case and we refer to e.g. [35] for the details.

5. NUMERICAL RESULTS

This section is devoted to the validation of our entropy preserving/stable schemes based on both the Tadmor flux and the KEP flux for 1D and 2D reactive Euler equations. For simplicity, we only take $k = 3$ and validate the sixth-order entropy preserving scheme and the fifth-order entropy stable scheme with (fifth-order) WENO reconstruction, which are referred to as EP6 and ES5, respectively. The third-order implicit-explicit Runge-Kutta method in [1] is employed for the time discretization. Four examples are used to demonstrate the designed accuracy of all the schemes as well as the ability of entropy stable schemes for problems with

discontinuities. In all the examples, the parameters of the reactive Euler equations are chosen following [13, 33]:

$$\gamma = 1.2, \quad q = 50, \quad \tilde{T} = 50, \quad \tilde{K} = 2566.4.$$

Except for Example 2, periodic boundary conditions are employed to avoid the effect of boundaries.

Example 1 (1D smooth problem). We first test the accuracy of our schemes through a 1D smooth problem with exact solution

$$(5.1) \quad \rho = 1 + 0.3 \sin(2\pi(x - t)), \quad u = 1, \quad p = 1, \quad Y = 0$$

in the domain $[0, 1]$. We take the mesh size as $\Delta x = 1/20, 1/40, 1/80, 1/160$ and set $\Delta t = \Delta x^2$ and $\Delta t = \Delta x^{5/3}$ for the EP6 and ES5, respectively. The L^1 and L^∞ errors at $t = 0.1$ are listed in Table 1. We observe that for both the Tadmor flux and the KEP flux the designed sixth- and fifth-order convergence is obtained for the EP6 and ES5 scheme, respectively. Additionally, the errors of the two fluxes are very close and have the same values at the first decimal place.

TABLE 1. Error table for 1D smooth problem with exact solution (5.1)

Tadmor flux		EP6			
Δx	L^1 error	order	L^∞ error	order	
1/20	2.7360e-06		9.3507e-06		
1/40	4.8079e-08	5.8305	1.9061e-07	5.6164	
1/80	7.7813e-10	5.9493	3.1416e-09	5.9230	
1/160	1.2265e-11	5.9874	4.9729e-11	5.9813	
Tadmor flux		ES5			
Δx	L^1 error	order	L^∞ error	order	
1/20	2.0015e-04		4.3710e-04		
1/40	2.5855e-05	2.9525	5.3814e-05	3.0219	
1/80	1.5148e-06	4.0933	3.7037e-06	3.8610	
1/160	1.6687e-08	6.5042	4.7931e-08	6.2719	
KEP flux		EP6			
Δx	L^1 error	order	L^∞ error	order	
1/20	2.7362e-06		9.3508e-06		
1/40	4.8077e-08	5.8306	1.9061e-07	5.6164	
1/80	7.7812e-10	5.9492	3.1416e-09	5.9230	
1/160	1.2266e-11	5.9873	4.9733e-11	5.9811	
KEP flux		EP5			
Δx	L^1 error	order	L^∞ error	order	
1/20	2.0148e-04		4.1394e-04		
1/40	2.5574e-05	2.9778	5.3044e-05	2.9642	
1/80	1.5086e-06	4.0834	3.7063e-06	3.8391	
1/160	1.6687e-08	6.4983	4.7875e-08	6.2746	

Example 2 (1D problem with discontinuities). In this test, we consider the Riemann type initial conditions

$$(5.2) \quad (\rho, u, p, Y) = \begin{cases} (1, 0, 1, 0) & \text{if } x < 0, \\ (0.125, 0, 0.1, 0) & \text{if } x > 0, \end{cases}$$

where the initial data of ρ, u, p are the same as those of Sod's problem for the Euler equations [29]. The computational domain is $[-5, 5]$ and we take the mesh size as $\Delta x = 1/16$. The numerical solutions at $t = 2$ with CFL=0.5 for the ES5 scheme are plotted in Fig. 1. It can be seen that the results of the Tadmor flux and the KEP flux are almost the same and the discontinuities are well captured without oscillations. As expected, the total numerical entropy $\sum_i \hat{\eta}(U_i(t))\Delta x$ decreases with respect to time; see Fig. 2. We also observe from Fig. 1 that the reactant mass fraction Y oscillates slightly and becomes negative around the contact discontinuity. The magnitude of the oscillation is reduced under a smaller mesh size $\Delta x = 1/160$ in our numerical experiments. These indicate that the present schemes do not guarantee the positivity of Y . Enforcing both the positivity of solution and the ES property will be our next target.

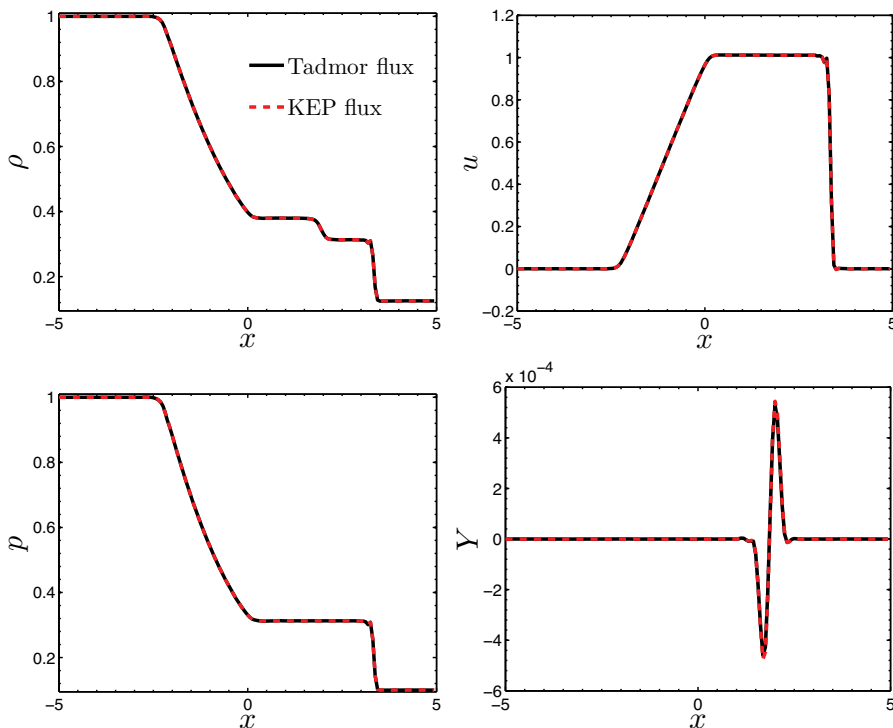


FIGURE 1. Example 2: Computational results at $t = 2$ with $\Delta x = 1/16$

Example 3 (2D smooth problem). In the following, we validate our schemes for 2D problems. As for the 1D case, we first test the accuracy with the exact solution

$$(5.3) \quad \rho = 1 + 0.3 \sin(2\pi(x + y - t)), \quad u = 1, \quad v = 0, \quad p = 1, \quad Y = 0$$

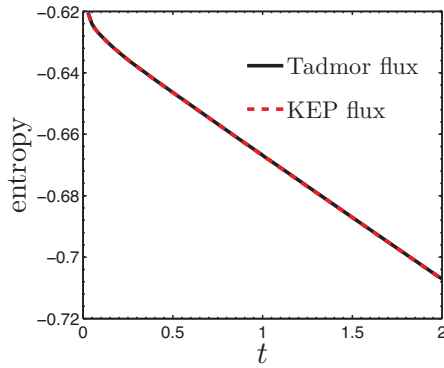


FIGURE 2. Example 2: Evolution of the total numerical entropy

in a square domain $[0, 1] \times [0, 1]$. The mesh sizes are $\Delta x = 1/20, 1/40, 1/80, 1/160$ and the time steps are $\Delta t = \Delta x^2, \Delta x^{5/3}$ for the EP6 and ES5, respectively. Table 2 lists the errors at $t = 0.01$, from which designed convergence orders can be observed for both the Tadmor flux and the KEP flux. Similar to the 1D case, the errors of the two fluxes are also very close. These demonstrate the accuracy of our schemes for 2D problems.

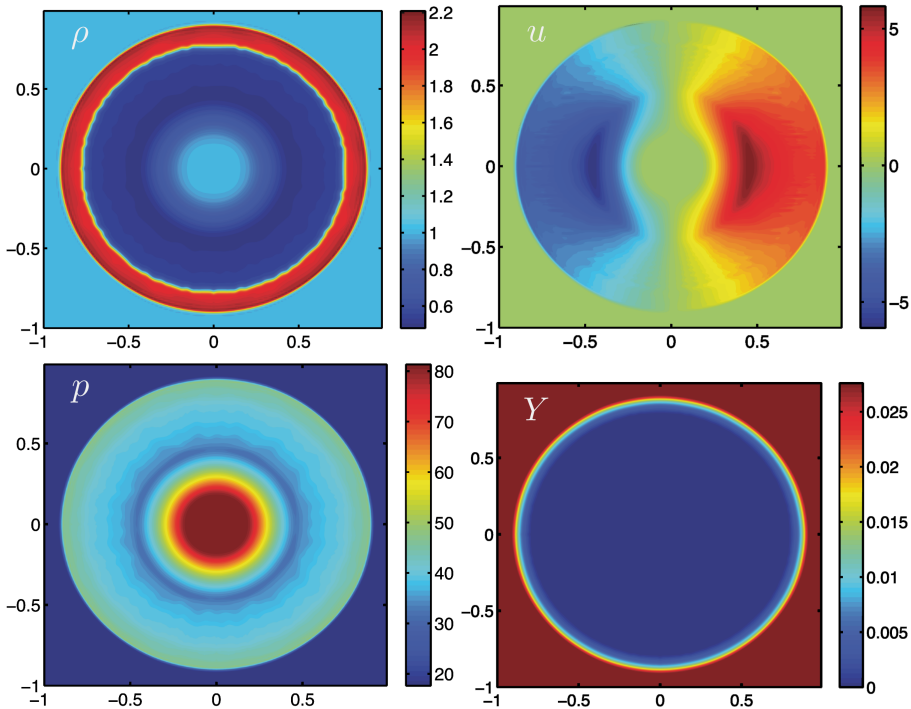
FIGURE 3. Example 4: Contours of different variables at $t = 0.04$

TABLE 2. Error table for 2D smooth problem with exact solution (5.3)

Tadmor flux		EP6		
Δx	L^1 error	order	L^∞ error	order
1/20	2.7913e-07		1.0150e-06	
1/40	4.8688e-09	5.8412	1.9297e-08	5.7170
1/80	7.7978e-11	5.9643	3.1515e-10	5.9361
1/160	1.2275e-12	5.9893	4.9808e-12	5.9835
Tadmor flux		EP5		
Δx	L^1 error	order	L^∞ error	order
1/20	8.4400e-05		2.5753e-04	
1/40	9.2748e-06	3.1858	3.8804e-05	2.7305
1/80	4.1865e-07	4.4695	2.1626e-06	4.1654
1/160	8.9274e-09	5.5514	4.4572e-08	5.6005
KEP flux		EP6		
Δx	L^1 error	order	L^∞ error	order
1/20	2.7914e-07		1.0150e-06	
1/40	4.8686e-09	5.8414	1.9296e-08	5.7170
1/80	7.7978e-11	5.9643	3.1515e-10	5.9361
1/160	1.2275e-12	5.9892	4.9812e-12	5.9834
KEP flux		EP5		
Δx	L^1 error	order	L^∞ error	order
1/20	8.5440e-05		3.3197e-04	
1/40	8.8719e-06	3.2676	3.0030e-05	3.4666
1/80	4.2291e-07	4.3908	2.2207e-06	3.7573
1/160	8.8464e-09	5.5791	4.6625e-08	5.5737

Example 4 (2D problem with discontinuities). In this example, we test our schemes for a 2D problem containing discontinuities. The computational domain is $[-1, 1] \times [-1, 1]$ and the initial data is given by

$$(5.4) \quad (\rho, u, v, p, Y) = \begin{cases} (1, 0, 0, 80, 0.2), & x^2 + y^2 \leq 0.36, \\ (1, 0, 0, 10, 0.8), & \text{otherwise,} \end{cases}$$

which is taken from [39]. In the computation we employ the ES5 scheme with a mesh size $\Delta x = 1/100$ and $CFL = 0.2$. Again, the results of the Tadmor flux and the KEP flux are very similar. The contour plots of ρ, u, p, Y at $t = 0.04$ obtained with the Tadmor flux are given in Fig. 3 and the solutions along the horizontal line $y = 0$ are plotted in Fig. 4. We see that the von Neumann spike is clearly resolved. Additionally, as shown in Fig. 5 the total numerical entropy $\sum_{i,j} \hat{\eta}(U_{i,j}(t))\Delta x$ decreases with respect to time, supporting that our schemes are entropy stable.

6. CONCLUSIONS AND REMARKS

In this paper, we present entropy analysis and high-order ES finite difference schemes for the reactive Euler equations in both one- and two-dimensions on a Cartesian mesh. First, we show that the thermodynamic entropy is no longer strictly convex for the reactive Euler equations. To address this issue, we propose

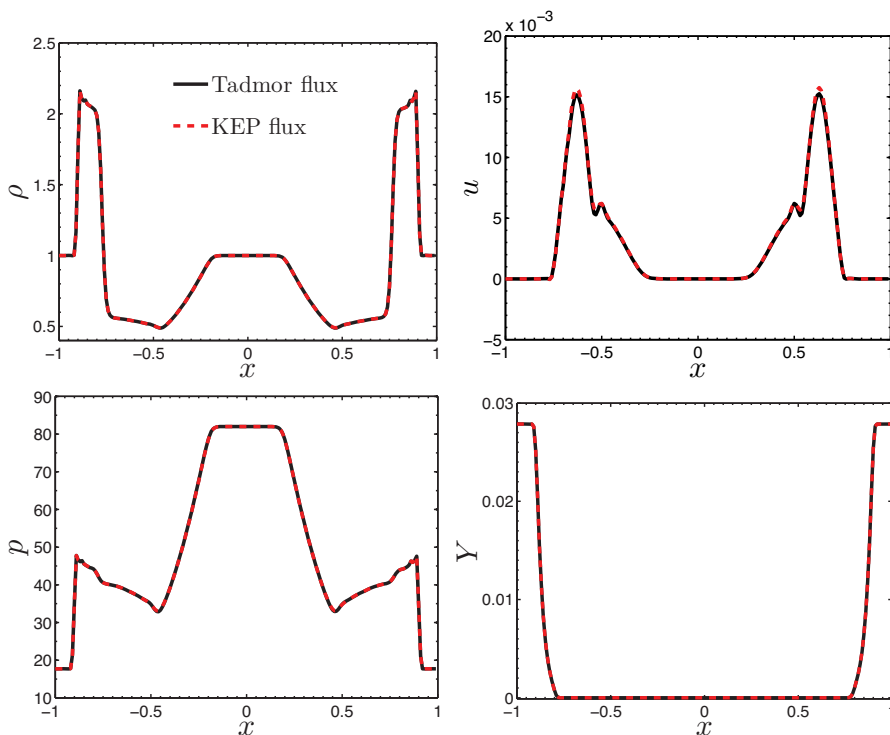


FIGURE 4. Example 4: Solutions along the horizontal line $y = 0$

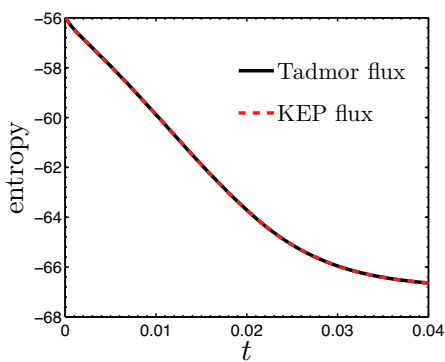


FIGURE 5. Example 4: Evolution of the total numerical entropy

a strictly convex entropy function by adding an extra term to the thermodynamic entropy. As a result, a new entropy-entropy flux pair is obtained. Thanks to the strict convexity of the proposed entropy, the Roe-type dissipation operator in terms of the entropy variables can be formulated [28]. Note that such dissipation operators are not available based on the thermodynamic entropy, as it is not strictly convex.

Furthermore, we construct two sets of second-order EP fluxes by extending those in [5, 28] for the Euler equations within the framework of [31]. In particular, the

EP fluxes extended from [5] are also KEP. With the EP fluxes and the Roe-type dissipation operators, high-order EP/EC fluxes are derived following [17, 25], where the sign-preserving ENO [16] and WENO [3] reconstructions are employed for the high-order dissipation operators. Numerical experiments in 1D and 2D validate the designed accuracy and good performance for smooth and discontinuous problems. The entropy decrease of ES schemes is verified as well.

We would like to point out that for the reactive Euler equations as hyperbolic balance laws, the strict convexity of entropy function is crucial for the global existence of solution [36]. The present strictly convex entropy may be helpful for the theoretical analysis of the reactive Euler equations. On the other hand, we observe that the proposed schemes do not guarantee the positivity of the reactant mass fraction. This may be overcome with the positivity limiters in [37, 38]. These will be the topic of our work in the future.

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