1. Write a function m-file **myrk.m** along the lines of the m-file **myeuler.m** which I have posted. It should implement the classical fourth order Runge-Kutta method with y and f vectors. Try your code with various step sizes on the example

$$y'' + y' - 6y = 20e^t$$
, $y(0) = 0$, $y'(0) = 1$, $0 \le t \le 2$

whose exact solution is $y(t) = -5e^t + .8e^{-3t} + 4.2e^{2t}$.

2. We again consider the nonlinear two-point boundary value problem

$$y'' = e^y - 1, \quad y(0) = 0, \quad y(1) = 3$$

We are going to find the missing initial value y'(0) by using the *shooting method*. We denote the solution of

$$y'' = e^y - 1, \quad y(0) = 0, \quad y'(0) = s$$

by y(t; s). The problem is to find s so that y(1; s) = 3. For each value of s, we can use **ode45** to find y(1, s). We then use **fzero** to find the root of G(s) = y(1; s) - 3 = 0. (You should compare your answer with the answer to Assignment#5, problem 8.) Once you have found y'(0), use **ode45** to plot the solution.

- 3. Ex. 7.4 p.35 Numerical Computing with MATLAB.
- 4. Ex. 7.12 p.38 Numerical Computing with MATLAB.
- 5. Ex. 7.14 p.39 Numerical Computing with MATLAB.